Errata on "Strengthened Circle and Popov Criteria for the Stability Analysis of Feedback Systems With ReLU Neural Networks"

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IN THE above article [1], the following corrections should be noted. The publisher regrets the errors.

In (22), an extraneous character was included. The correct formula is presented here.

$$\dot{V}_c(x) \leq 2x'\mathbf{P}\dot{x} + 2\Phi(y)'\mathbf{V}[y - \Phi(y)] + 2\Phi(y)'\mathbf{Q}_{11}\Phi(y) \tag{22}$$

Just below (39), a halmos was incorrectly included at the end of Corollary 1.

Reference [18] included typographical errors and a broken link. The correct reference is as follows:

[18] E. D. Anderson and K. D. Anderson, "The MOSEK interior point optimizer for linear programming: An implementation of the homogeneous algorithm," in *High Performance Optimization*, vol. 33, H. Frenk, K. Roos, T. Terlaky, and S. Zhang, Eds. Boston, MA, USA: Springer, 2000, pp. 197–232, doi: 10.1007/978-1-4757-3216-0_8.

REFERENCE

[1] C. R. Richardson, M. C. Turner, and S. R. Gunn, "Strengthened circle and Popov criteria for the stability analysis of feedback systems with ReLU neural networks," *IEEE Control Syst. Lett.*, vol. 7, pp. 2635–2640, 2023, doi: 10.1109/LCSYS.2023.3287494.

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