

5GinFIRE: An End-to-End Open5G Vertical Network Function Ecosystem

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Abstract

Advanced communication networks, such as 5G and beyond, will be a complex ecosystem made of multiple physically interconnected elements, implying that the upcoming network will have to address capabilities such as flexibility, programmability and extensibility. This article, describes an Open and Extensible 5G Network Function Virtualisation (NFV) based Reference ecosystem of experimental facilities, named *5GinFIRE*, that integrates existing facilities with new vertical-specific ones but also lays down the foundations for instantiation fully softwarised architectures of vertical industries and experimenting with them. Additionally, we present 5GinFIRE as the forerunner experimental playground, together with three uses cases, wherein new components, architecture designs and APIs may be tried and proposed before they are ported to more industrially mainstream 5G networks that are expected to emerge in large scale.

Keywords: Network Function Virtualization, 5G, Experimentation Platform, Network

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1. Introduction

Key industrial sectors, such as manufacturing, automotive, energy, entertainment industry to name a few, are rapidly being transformed by digital and communication technologies leading to the fourth industrial revolution. New ones are in the making, i.e., smart cities, which inspire a new breed of applications and services. The salient characteristic of these verticals is that they do not operate and evolve in a silo mode anymore, relying on closed and proprietary technological environments, but they are becoming open ecosystem built on top of shared physical infrastructures, (re)using the same open source components and APIs and sharing resources utilizing virtualization. This context presents a number of multi-facet challenges (such as interoperability, inter-connectivity, federation, resource sharing, slicing, resource scheduling, operations) of unprecedented magnitude and complexity and it calls for the appropriate identification, introduction, integration and efficient operation of a series of common architectural elements and infrastructure assets that should be combined together with the vertical-specific components. It also calls for an environment engineered in such way that is capable of co-hosting different verticals while addressing competing requirements of applications and services deployed and run in the context of the various verticals. In this direction, this article presents 5GinFIRE ecosystem which is motivated by the previous described context and two interlinked questions.

1. How such a holistic and unified environment should look like?
2. How can 5GinFIRE host and integrate verticals and concurrently deal with reconciling their competing and opposing requirements?

Addressing these key questions, 5GinFIRE main technical objective is to deploy and to operate an open, and extensible 5G NFV-based reference ecosystem² of experimental facilities that not only instantiates facilities with new vertical-specific ones

²5GinFIRE Portal: <https://5ginfire.eu/>

but also lays down the foundations for instantiating fully softwarised architectures of vertical industries and experimenting with them. The instantiation of the 5GinFIRE ecosystem is as generic as possible in order to host any kind of verticals.

In order to guarantee architectural and technological convergence the 5GinFIRE environment has been built in alignment with on-going standardization (i.e. European Telecommunications Standards Institute (ETSI) NFV) and open sources (i.e. OPEN MANO) activities, also targeted by other closely related programme activities such as 5G-PPP³. In particular, 5GinFIRE ecosystem serves as the forerunner experimental playground wherein new components, architecture designs and APIs may be tried and proposed before they are ported to more industrially mainstream 5G networks that are expected to emerge in large scale. So far as we know, 5GinFIRE is the first platform that strongly and uniquely places key standardization activities in the core of its concept. Contributing and enhancing the standardization activities in 5G NFV and offering a unique standardized way of setting up and running experiment for advanced network communities across 5GinFIRE facilities.

In the next section, the state-of-the-art of 5G technologies and platforms are briefly reviewed, following by the 5GinFIRE ecosystem description such as: target areas, 5GinFIRE architecture and overall methodology, blueprint uses cases and final remarks.

2. Related Work

The digital transformation of network infrastructure through NFV and software defined networking (SDN) promises to play a key role with the respect to the commercialization of 5G and the digitalization of vertical markets. There are several major architectural issues facing 5G networks, which can only be overcome leveraging NFV and SDN.

The basic idea behind NFV and SDN is to decouple software from hardware enabling flexibility, programmability and extensibility of the network. With NFV, service

³<https://5g-ppp.eu/>

providers can deploy various Network Functions (NFs), such as firewall or encryption, on virtual machines (VMs). Whenever a customer requests a new NF, service providers
55 are able to spin up a VM for that function automatically. Leveraging this technology, network administrators do not need to invest in high-priced, proprietary hardware to set up a service chain of network-connected devices. And unlike proprietary hardware, these NFs can be installed almost instantaneously.

Many standardization efforts are currently on-going, the most prominent being the
60 European Telecommunications Standards Institute (ETSI)⁴ NFV. This standardization activity follows a dual approach, which benefits on the one hand from top-down design documents and requirements and on the other hand Proof-of-Concept (PoC) demonstrators and prototypes that showcase the aspects under standardization as well as the feasibility of the approach. PoCs usually team together vendors with complementary
65 expertise (i.e. a network vendor and a software house specializing in virtualization or cloud technologies). However, the PoCs are meant for illustrative purpose only, and are typically implemented in a closed environment, which is vendor-specific. This does not allow PoCs to be comparable and they become one-of-a-kind showcase, as opposed to a foundation for further development. With the introduction of components developed
70 in the context of vertical industries, the PoC approach is not sufficient anymore and it needs to be expanded to account for more complex vertical-specific service architecture that must coexist and share the underlying infrastructure substrate and resources therein. This is also stressed in the 5G-PPP white paper [5] and the 5 layered integrated 5G architecture for mobile broadband and vertical services. 5GinFIRE offers
75 an open environment for verticals by establishing an industry-led and industry-focused distributed and multi-domain NFV infrastructure fabric. An environment implemented following the standardized NFV ETSI reference architecture based on Open APIs and Open Source services, which complements the planned activities in ETSI and 5G-PPP for vertical services development and demonstration. In addition, it provides a forerun-
80 ner experimental platform for FIRE + engagement in ETSI standardization, 5G-PPP, and future market transfer.

⁴<http://www.etsi.org/>

Previous network and Future Internet Research & Experimentation (FIRE)⁵ projects have created a lot of know-how in Europe and deployed novel software and hardware facilities, but have had limited adoption by industry leaders, let alone the creation of
85 a single source of innovation in the European SDN and NFV environments. Further, FIRE projects by and large have been distant to standardization activities, let alone used for demonstrating new possibilities with emerging standards. Instead, we have seen several open source projects emerging from large corporations that bypass FIRE facilities.

90 Although NFV is meant to lower the entry barriers to smaller players, practically, the current PoC effort is dominated by large players with limited to almost no Small and Medium-sized Enterprise (SME) involvement. The situation is further aggravated when dealing with innovation targeting specific verticals as the experimentation environment is highly isolated from each other as well as specialized, while offering a few and fixed
95 services for experimentation. Exploiting the potential of softwarization of almost every aspect of functionality, network or application specific, we can foster SME innovation on top of 5GinFIRE ecosystem for experimentation and rapid prototyping in the area of network service virtualization for verticals and application thereof.

Currently NFV vendors or/and users independently implement numerous NFV plat-
100 forms and solutions. This results in the dilution of efforts and fragmentation of technologies to be produced leading to divergence and gaps impacting interoperability, and, ultimately, the openness of platforms. To this end, 5GinFIRE acts as the playground for technology convergence enabling more permanent collaboration link with initiatives such as ETSI, OPENFV⁶, FIRE, 5G-PPP and FIWARE.

105 The 5G Telefonica Open innovation Laboratory (5TONIC) [2] is used by 5GinFIRE platform to offer access to specific-purpose hardware, to assist in experiments, trials and demonstrations with 5G network technologies, as well as to commodity hardware which allows a cost-effective approach to configure different network topologies of variable size and capacity.

⁵<https://www.ict-fire.eu/projects/>

⁶<https://www.docker.com/>

110 FIWARE⁷ platform provides a rather simple powerful set of APIs that ease the development of smart applications in multiple vertical sectors. The specification of these APIs are public and royalty-free. However, FIWARE is far from an open NFV-based reference platform. FIWARE focuses primarily on providing high level APIs targeting at specific applications through a concept called domain specific enablers.

115 A number of projects (SEMAFOUR [10], NOVI [7], 4WARD [1], SAIL [9], T-NOVA [12], UNIFY MCN [13], ALIEN [3]) fall within scope of SDN and NFV. Although they address specific aspects of the 5GinFIRE architecture framework they are rather predecessors of 5G-PPP projects or they had a specific focus. Under any circumstances, these and the 5G-PPP projects may use the 5GinFIRE experimentation
120 environment as a template that can host their outcomes. This will promote reusability of project results facilitated by FIRE solution.

[18] provides a brief overview of NFV, explains its requirements and architectural framework, presents several use cases (i.e. virtualisation of mobile core network, home network), and discusses the challenges (i.e. network performance of VNF, VNF place-
125 ment and migration, VNF outsourcing) and future directions. The authors pointed out that it is envisioned that NFV, along with cloud computing and SDN, will become a critical enabling technology to radically revolutionize the way network operators architect and monetize their infrastructure. 5GinFIRE follows this vision.

The Fraunhofer FOKUS OpenSDNCore [14] is a platform similar to 5GinFIRE
130 that acts as an end-to-end middleware between:

- A distributed heterogeneous infrastructure including dedicated components (e.g. radio), heterogeneous data centers (compute storage) and inter-connecting networks (fronthaul, backhaul, third party backbone, etc.)
- Generic network functions implemented in software and running in virtual machines: Virtualised IMS, EPC, radio and SGi components, home and enterprise
135 networks, Application Servers, etc.

OpenSDNCore is a practical implementation of the future network evolution paradigms,

⁷<https://www.fiware.org/>

realizing Network Functions Virtualisation (NFV) and Software Defined Network (SDN) concepts matching with the 5GinFIRE principles. It also is based on ETSI NFV MANO
140 aligned Orchestrator integrated with OpenStack enabling the dynamic deployment and run-time management of virtual network functions.

In [19] is presented an architecture of an SDN/NFV network and cloud computing platform for end-to-end 5G services. This platform integrates ADRENALINE, GEDOMIS and EXTREME testbeds, three complementary testbeds developed by CTTC,
145 spanning from terminals to radio access network, aggregation/core networks and cloud. 5GinFIRE is also based on multi-domain orchestration offering dynamic and flexible end-to-end connectivity and virtual network provisioning services across multi-domain and multi-technology networks.

The trend for 5G future networks is clearly dominated by softwarization at all levels, starting from Software Defined Radio (SDR) including Dynamic Spectrum Sharing (DSS), SDN, NFV up to a software defined holistic environment for technical and business innovation integrating networking, computing and storage resources into one programmable and unified infrastructure. 5GinFIRE has similarities and is aligned with SOFTFIRE [11] and ORCA [8] projects regarding to the trends for 5G experimentation. SofFIRE looks for bringing NFV and SDN capabilities in order to create
155 a reliable, secure, interoperable and programmable experimental network infrastructure. Such environments are used to assess the maturity and industrial viability of these technologies by evaluating system properties in terms of efficiency, functional responsiveness (expressed in terms of measurable Key Performance Indicators (KPIs)) and the ability to create new applications on the platform. ORCA [8] is an end-to-end network experimentation that focus on open and modular software and hardware architectures available that smartly use novel versatile radio technology, more-specifically real-time SDR platforms meeting the requirements in terms of runtime latencies, throughput, and fast reconfiguration and reprogramming. In order to meet at the same time diverging
160 Quality of Service (QoS) requirements over wireless networks, control mechanisms are introduced by ORCA platform that allows the configuration and deployment of optimized radio slices that can be mapped to virtual network slices configured by SDN, as such realizing a joint SDR-SDN paradigm. On the other hand, 5GinFIRE introduces

business innovation over such transforming communication technologies leading to solution for verticals that are rapidly forming open ecosystems built on top of open common infrastructures and resources. This requires a high degree of technological convergence among vertical industries empowering them with enhanced technical capacity to trigger the development of new, innovative products, applications and services. In order to guarantee architectural and technological convergence the experimentation environment must be in alignment with on-going standardization and open source activities inherently forming a forerunner experimental playground for emerging "mainstream" 5G networks which are defined through 5GinFIRE's goal.

3. 5GinFIRE Architecture

5GinFIRE ecosystem uniquely offers virtualized elements for building complex constellations of virtual functions, all running on a mix of real and virtual network or computing elements. However the biggest challenge in realizing such an open network substrate is "interoperability" which needs to be explicitly addressed at the architecture specification phases.

Interoperability, in terms of orchestration, deployment and Virtual Functions operations, can be achieved through standards specifications, which are necessary to be complemented with actual implementations (PoCs) in the form of open operational reference platforms that validate the standards and act as a showcase or experimentation environment for applications and services for feedback generation.

ETSI's NFV reference architecture and PoCs [17] are an initial attempt to address the issues above while Open NFV open source project (OPNFV) will provide reference software implementations of architectural components of the former. 5GinFIRE overall concept is based on ETSI's NFV reference architecture but in the same time it semantically enriches and extends it in many ways to account for vertical specific requirements and functionalities. As an example, resource scheduling, experimentation planning, experiment operations, VNF versioning, VNF/NSD validation are aspects that are not addressed by the ETSI NFV architecture. It also bridges the gap between verticals operation and execution of experiments since by following standard-

ized deployment mechanisms the same experimentation VNFs can be re-deployed in an operational environment as is. As a result, Figure 1 shows the 5GinFIRE reference model architecture which is composed of four building blocks. These blocks supports the life-cycles of verticals (deployment, instantiation, execution, control and release).

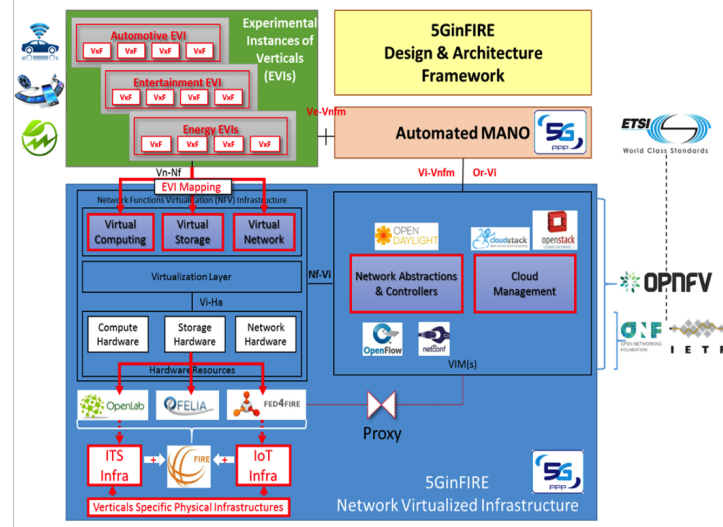


Figure 1: 5GinFIRE reference architecture.

1. **Experimental Instances of Verticals (EVIs):** these EVIs include a composition of several virtual functions (network or vertical) spanning all layers from application and services to networking. We refer to these virtual functions as $VxFs$ without distinguishing between network-centric functions and vertical-centric functions.
2. **5GinFIRE Network Virtualized Infrastructure (5GNVI):** 5GNVI is comprised of facilities that offer raw resources, namely, computational, network and storage which are shared among several $VxFs$. These resources are offered as virtual/physical resources by the underlying hardware through a virtualization layer that extends itself across a combination of mainstream physical infrastructures such as Cloud Computing and vertical specific ones e.g. Intelligent Transportation Systems (ITS) including the vehicles themselves that host Mobile Edge Computing functionality. Management of the operations of the infrastruc-

215 tures and of the corresponding resources is carried out through the Virtualised
Infrastructure Managers (VIMs) while control. As 5GNVI may span across sev-
eral locations, i.e. places operated by different testbed providers, multiple VIMs
may exist, one per testbed site. Although the scope of VIMs is local they are
accessible through well- established APIs and their implementation relies on
220 open source which facilitate their integration and intercommunication for any
distributed EVI functionality.

3. **Automated Management and Orchestration (auto-MANO):** auto-MANO build-
ing block focuses on the orchestration and life-cycle management of the 5GNVI
in a global manner.
- 225 4. **5GinFIRE Design and Architecture Framework:** includes the APIs for creat-
ing and experimenting on new services and applications facilitating the integra-
tion with the industrially led standardization and open source activities.

5GinFIRE architecture is composed of the core network and heterogeneous NFVIs,
also called facilities, that spread over different locations. Both constitute the overall
230 5GinFIRE ecosystem that can be integrated with existing testbeds such as FIRE facili-
ties.

Provisioning and running of network services and applications in FIRE in the form
of experiments are important operations offered by various FIRE facilities, past and
present. This gives rise to an overlapping area with industrially led initiatives such as
235 OPENFV and 5G- PPP that needs to be addressed properly in order to bring mutual
benefits. As the need for creating, experimenting on new services and applications
is ever increasing and is expected to further intensify with the addition for vertical
support, it calls for a radically different underlying physical network infrastructure
that extend horizontally like in the case of 5G. Such requirement is hindered by the
240 availability of specialized hardware and/or proprietary network software which raises
serious open API accessibility and configuration issues in hard-to-find testbed infras-
tructures. Although, federation approaches, as in Fed4FIRE, in particular, in accessing
and using FIRE facilities, may mitigate the problem, they are far from solving it as
they confine themselves to managing stove- piped experimental facilities. 5GinFIRE

245 is aware of this issue and dedicates special attention on how existing FIRE know-how and facilities could be seamlessly integrated with the industrially led standardization and open source activities. This is the purpose of the architecture component, called Proxy (see Figure [?]), which aims at facilitating technological convergence of FIRE with future 5G operational platforms.

250 3.1. Core architectural components

5GinFIRE offered services and tools target to accommodate the following envisaged user roles. All users are assumed to be of an Authenticated role:

- Experimenter: This role represents the user that will utilize 5GinFIRE services and tools to deploy an experiment.
- 255 • VxF Developer: This role is responsible to upload VNF and NSD Descriptors in the 5GinFIRE services.
- Testbed Provider: This role represents users that are responsible for testbed administration, configuration, integration, adaptation, support, etc.
- Experiment Mentor: responsible for monitoring the progress of an experiment, resource usage and allowing or not the deployment of an experiment.
- 260 • Services administrator: This role represents the user that are responsible for maintenance of the 5GinFIRE services.

Figure 2 shows the core architectural components and their interfaces for experimentation in 5GinFIRE platform.

- 265 • **Portal:** 5GinFIRE portal is a web application where end-users (Experimenters, VxF Developers) can subscribe, manage experiments, browse repository, monitor experiment results, etc. In addition, it allows admins to manage the 5GinFIRE platform and the VNF/NSD repositories. In particular, the 5GinFIRE portal provides access to the 5GinFIRE repositories of VxFs metadata and descriptors (e.g. Unifier Gateway VNFs), categorized in EVIs (e.g. Networking, Automotive, Media) through well specified APIs. Three interfaces exist in the portal:
- 270

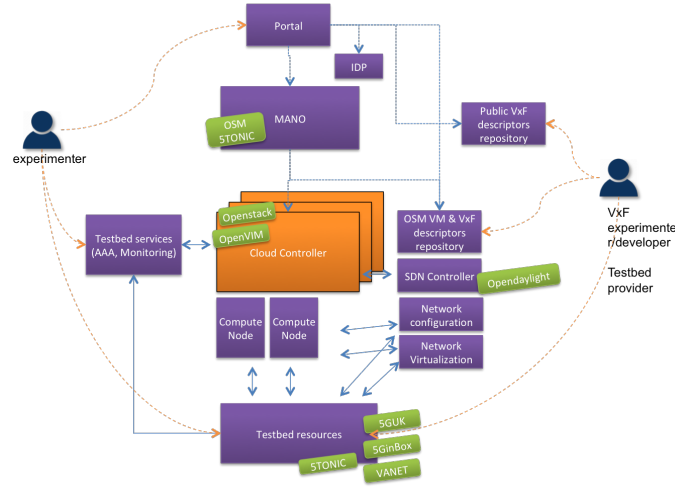


Figure 2: 5GinFIRE high level experimental architecture.

1. **OSM:** this interface allows to communicate with OSM MANO in order to push experiment description and *VxV* descriptors.
2. **IDP:** is an identity provider mechanism for authenticating 5GinFIRE users. IDP has two interfaces: 1) Portal for authenticating portal users and; 2) Support tools for ticketing system authentication.
3. **Public *VxV* descriptor repository:** contains all *VxVs* registered by 5GinFIRE users. It has one interface with the portal that will accept request of managing *VxV* descriptors and their archives.
4. **OSM VIM & *VxV* descriptor repository:** is the OSM repository where *VxV* that will be instantiated need to be committed.

- **5GinFIRE MANO platform:** MANO platform, which is based on OSM as section B describes, receives orchestration actions from 5GinFIRE Portal (i.e. to create/delete a VNFD in/from the OSM catalog, to create/delete an NSD in/from the OSM catalog, to instantiate a NS, etc). The 5GinFIRE MANO platform has interfaces to the portal and towards the VIM endpoints, to request the allocation and release of computing, storage and network resources at the partners' NFV Infrastructure.

- **VIMs (Cloud Controllers):** each partner providing an experimental infrastruc-

290 ture to 5GinFIRE is in charge of the deployment and maintenance of a VIM
supported by the 5GinFIRE MANO platform. Each VIM deployed at a partner
infrastructure domain must provide a compliant northbound API to 5GinFIRE
MANO platform. This component contains two interfaces:

- 295 1. **5GinFIRE MANO:** enables the interactions with 5GinFIRE MANO plat-
form.
2. **Testbed resources:** enables to control and manage the computing, storage
and network resources of a NFVI.

- **Testbed services:** testbed specific services that can be handover to the exper-
imenter in order to facilitate the operations during the experimentation.
- 300 • **Testbed resources:** the available resources for experimentation located in each
target testbed. For instance:

- 5GUK Test Network [4] is a multi-site solution connected through a city-
wide single mode fibre ring with several active switching nodes. The core
network is located at the High-Performance Network (HPN) research group
laboratory at the University of Bristol with access technologies located in
305 Millennium Square for outdoor coverage and We The Curious science mu-
seum for indoor coverage.
- 5TONIC includes a solid baseline of facilities and infrastructure that sup-
ports advanced experimentation in the area of 5G network technologies. It
310 offers a data center with multiple communication racks, a VPN access ser-
vice and high-speed network connectivity with external networks. Through
RedIRIS [15] and GÉANT [6] Communication racks are allocated to in-
dividual 5TONIC members, and may be flexibly interconnected according
to any experimentation requirements. Additionally, 5TONIC provides its
315 members with access to a common infrastructure with specific-purpose
hardware, to assist in experiments, trials and demonstrations with 5G prod-
ucts and services.

- 5GinBox: 5G-In-a-Box, also called Unifier Gateway is a set of VNFs providing various radio access technologies and core network features by embedding Evolved Packet Core (EPC) with Mobility Management Entity (MME), Home Subscriber Server (HSS), Serving/Packet Data Network Gateway (S/P GW) functions (virtualized: vEPC and "SDNized": S/P GW-C and S/PGW-U) as well as Authentication, Authorization, and Accounting (AAA), Dynamic Host Configuration Protocol (DHCP) and Network Address Translation (NAT). These VNFs have the ability to handle standalone private Long Term Evolution (LTE) and Wi-Fi networks but, within the scope of 5GinFIRE, the target is to insert it in a more global framework.

3.2. Multi-testbed Orchestrator

The geographically distributed ecosystem is a significant feature of 5GinFIRE for design and deployment of experiments. Thereby, challenges such as resources placement considering each EVI specific requirements on raw resources placement can be addressed. 5GinFIRE focuses its resource pooling mechanism through core entities running as middleware. Open Source Management and orchestration (OSM), deployed at 5TONIC, fills this gap with two interfaces, one for users to describe and manage their experiments, another to internally provide mechanisms for deploying and delivering of the requested service.

OSM manages the resources to deploy run-time services on raw resources and it enables testbed service model. Also, it exchanges information among VIMs and SDN controllers located at the edge infrastructure. Once the service graph is defined, where vertices are $VxFs$ and edges are interconnection, it is necessary to materialize the connectivity between them in service chain format. To this end, datacenters should have a channel for the data plane; this relationship configures inter-site data-plane communications. Both are built on overlay network given the flexibility and autonomy required by the sites.

The network overlay approach provides inter-site connectivity and it uses Virtual Private Networks (VPN) for security and interoperability goals, further is a suitable mechanism to enable new sites (a.k.a. testbed providers) interconnections to the 5Gin-

FIRE ecosystem. OSM is responsible to deploy the *VxFs* accordingly defined to each experiment. This approach allows for the evolution of the ecosystem to support the
350 addition of new verticals.

Figure 2 details connectivity between 5GinFIRE testbed providers and the inter-site data exchange between these facilities. The network addressing plan is based on pre-defined separated subnets within the same broadcast domain. Each site has a L3 entity that provides an overlay network connection to the VPN server. The yellow line
355 is an enabling channel to exchange control information among OSM, SDN and remote VIMs. The exchanged messages in this channel allow deploy of the required *VxFs*. Additionally, the green line enables OSM to communicate directly with the deployed *VxF* to execute the necessary settings. Also, the purple line is the channel of the data plane, to allow communication between *VxFs*. Note that the data plane distribution
360 model is hub-and-spoke, star topology centered on the 5TONIC. It is possible for sites to establish bilateral data plane connectivity, without fundamentally being centralized, this autonomy supports specific requirements of 5G verticals.

To validate the connectivity, a set of functional tests are pre-defined to integrate a new testbed provider in the 5GinFIRE ecosystem. These functional and experimental
365 tests are done in threefold stages: i) validate the capacity of the overlay network, ii) ability to launch VNFs on remote site and iii) testing the NS deployment.

4. 5GinFIRE Methodology

The reference architecture presented in the previous section supports the methodology that guides the experimentation on top of the 5GinFIRE platform.

370 Figure 3 displays an overview of the experimentation workflow process. There are three main horizontal lines: the experimenter, the 5GinFIRE operations and the 5GinFIRE testbed providers that interact during an experimentation life-cycle. In order to instantiate experimentation scenarios end-users/experimenters must use 5GinFIRE Portal, thus users sign-up to the platform via the portal. The experimenter needs to
375 compose the experimentation description through an ETSI compliant Network Ser-

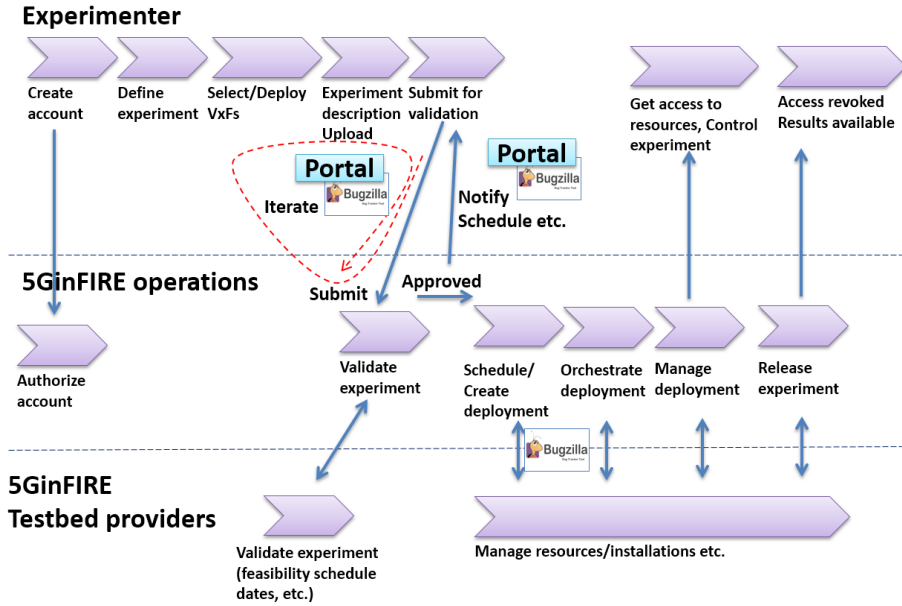


Figure 3: 5GinFIRE experimentation workflow overview

vice Descriptor (NSD) composed of VNF Descriptors (VNFD) based on YAML⁸ that the OSM will accept in order to instantiate the experimentation scenario and submit it to the portal. Then NSD is validated for archive compliance and deploy-ability and then is on-boarded to OSM. As soon as everything is in place and valid for an experiment deployment, the experimenter selects the testbed facility (or facilities for inter-connectivity experiments), places the VNFs to target facilities, defines experiment metadata, scheduling, purpose and submits it for approval.

5GinFIRE operations team has a process for approving an experiment in terms of various rules such as schedule, resource availability, etc. The approval process is closely performed together with the target testbed providers. To properly handle the process the 5GinFIRE operations assigns a so called Experiment Mentor that will approve and monitor the experiment. The Mentor drives discussions between experimenters and VIM owners and also verifies that the requested experiment is deployable. This implies, at least: checking that all the components are onboarded; and checking

⁸<http://yaml.org/>

that the VNFs can be executed in the involved testbeds (e.g., a VNF for an EPC should be executed in a testbed with radio equipment). 5GinFIRE has already setup an automated validation process via Continuous Integration techniques but there are cases that the request is not feasible (e.g. placement on Edge/Gateway devices). The Experiment Mentor also coordinates and provides a specific time slot for the execution of the experiment. This time slot may be different from the time slot requested by the experimenter depending on resources availability. All stages are traced from our ticketing system based on Bugzilla, which informs the operations team and all relevant stakeholders (experimenter, testbed providers, etc). As soon as an experiment is approved by the Experiment Mentor, the 5GinFIRE operations create a deployment request, onboards the NSD to OSM and OSM will orchestrate it. In all stages there is a close collaboration during the management of the orchestration/deployment with the testbed providers. After NSD instantiation the resources are available and accessible to the experimenter. In the end of the experiment schedule, the resources of the experiment are released and access is revoked. Any available results of the experiment might be available to the experimenter (e.g. infrastructure monitoring) when necessary.

5. Experimentation Enablement

In order to make sure that all the necessary functionality and corresponding facilities have been properly developed, integrated and operating and they support verticals experimentation, some internal pilot uses cases have been designed and implemented to validate the 5GinFIRE ecosystem. The outcomes of this internal uses cases have produced some templates and *VxFs* for verticals that provide the basis for future experiments. The next sections briefly describe each one of these uses cases.

5.1. Car Overtaking

This section describes the car overtaking use case that is part of the automotive EVI. The use case's objective is to gather real-time information to assist the driver in critical situations, e.g. car overtaking scenarios with reduced road visibility. To help the read driver in these situations a live stream from the front vehicle is transmitted to the rear

vehicle. However, to cope with the possibility of the targeting vehicle not behind able
 420 to support the original video format, a video transcoding operation must occurs. Thus,
 a video transcoder VxF was developed and deployed at the edge via 5GinFIRE portal.

The architecture of the automotive car overtaking use case is illustrated in Figure 4.
 Each vehicle contains a video camera on its front side and an On-Board Unit (OBU) ca-
 425 pable of providing two different communication technologies: IEEE 802.11p, enabling
 the communication between vehicles (V2V), and between vehicles and the infrastruc-
 ture (V2I), and 4G/5G cellular as a complement technology to be used in the absence of
 IEEE 802.11p communication links. The OBU is connected with an In-Car Node Pro-
 cessor that will be used to process and provide visual information to the driver. On the
 infrastructure side, each Road Side Unit (RSU) is connected to the automotive testbed
 430 datacenter, located in Aveiro, Portugal, where the VNFs are located. The 4G/5G cel-
 lular network is operating under the concept of Cloud-RAN (C-RAN), and supported
 by a VNF cellular unified gateway also deployed at the automotive testbed datacenter.
 However, for the results here presented only IEEE 802.11p communication links were
 used.

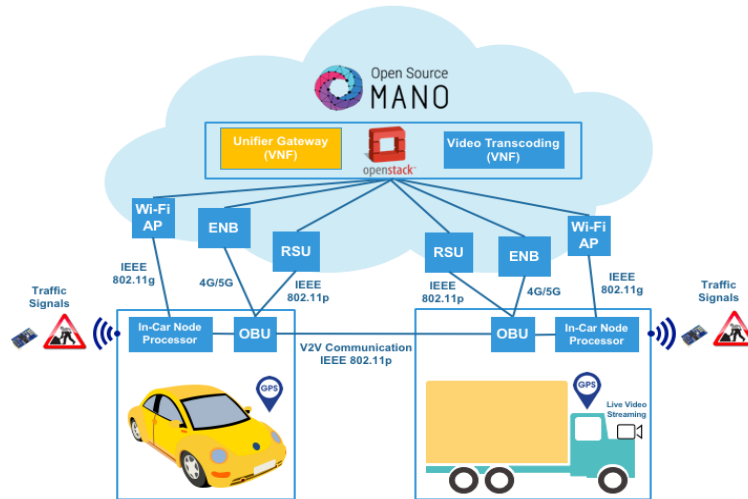


Figure 4: Car overtaking experimentation architecture.

To assess the functionality and performance of the video transcoding VxF, two distinct scenarios were explored. However, in both scenarios the connectivity map is the same consisting of two RSUs and two OBUs: the rear OBU is connected to a rear RSU and the front OBU is connected to a front RSU, *i.e.* no direct connectivity exists
440 between both OBUs. For experimentation purposes, RSUs are connected through Ethernet cable. In the first scenario it is assumed that no video transcoding is required and once the video feed reaches the front RSU it is streamed directly to the rear RSU, and then to the rear vehicle. Once the rear OBU receives the video stream it sends the video to the visual screen in the car, giving the driver the possibility to have real-
445 time access to visual information. In a second scenario the functionalities of the video VxF transcoder are explored. For that, once the video stream reaches the front RSU it goes to the video VxF transcoding located at IT-Aveiro's datacenter. From there, the transcoded live feed is sent to the rear RSU and then to the rear vehicle, using IEEE 802.11p.

450 Table 1 presents the average latency and Received Signal Strength Indicator (RSSI) observed during the experiments. The latency was measured between OBUs while RSSI values were measured on each IEEE 802.11p link, *i.e.* between the front OBU and the first RSU, and between the rear OBU and the second RSU. As expected, the results show that the lowest latency is observed in the shortest communication path.
455 In fact, with the introduction of the VxF video transcoding, performed in the cloud, the latency increased 50 times due to the time needed to perform this operation (the average transcoding delay was 980 ms). As for the RSSI, the results are very similar on each experiment. The RSSI between the rear vehicle and its RSU is higher than the RSSI between the front vehicle and its RSU mainly due to the distances observed
460 during the experiments.

The results presented in Table 1 were obtained in an urban scenario where the average velocity is considerably smaller when compared to a highway scenario. In order to understand the impact of vehicle's speed on the link quality, Figure 5 presents the latency observed between each 802.11p communication, *i.e.* between rear OBU and its
465 RSU, and between front OBU and its RSU. As expected, higher speeds induce higher delays in the communication, but similar results are observed for when the transmitter

Table 1: Average latency and RSSI observed during the car overtaking experiment.

| | Latency end-to-end | RSSI | |
|----------------------------------|-----------------------|---------------------------|-------------------------|
| | | front OBU to front RSU | rear OBU to rear RSU |
| Without VxF Video Transcoding | 19 ms | 38 | 80 |
| With VxF Video Transcoding | 1022 ms | 39 | 79 |

is the OBU and the receiver is the RSU (front OBU front RSU path) and when the transmitter is the RSU and the receiver is the OBU (rear RSU rear OBU path).

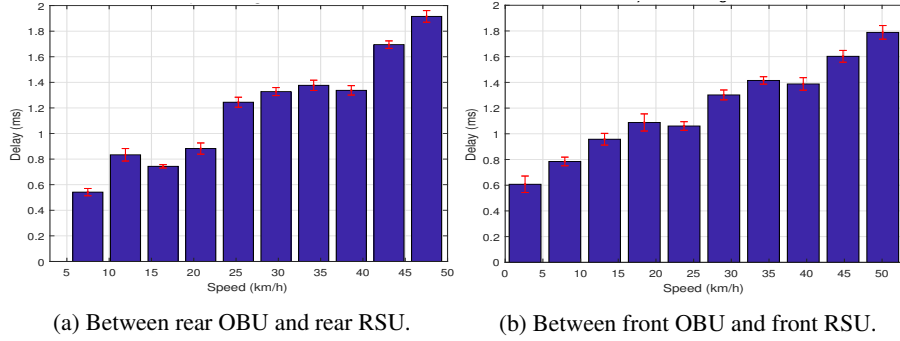


Figure 5: The impact of the vehicle's speed in the latency of an IEEE 802.11p transmission link.

5.2. Smart City Safety

This section describes the smart city EVI where a blueprint smart city use case named *Smart City Safety* has been demonstrated on top of the 5GinFIRE ecosystem. This use case help to identify criminals around the city by capturing 360° live stream video and providing face detection and recognition. To this end a VNF video transcoder (based on OpenCV including face detection and recognition program) has been deployed at the datacenter located in Bristol via 5GinFIRE portal. The NSD and VNFD were uploaded in 5GinFIRE Portal that communicates with OSM MANO to deploy the network service at University of Bristol (UNIVBRIS) NFVI. The VNF video transcoder is responsible for processing the live stream video from the spherical to a rectangular format to enable face detection/recognition.

480 The VNF video transcoder includes three phases:

1. video trasconder: where the 360° live stream video is converted to a rectangular format.
2. face detection: it has the objective of finding the faces in an video frame and extract them to be used by the face recognition algorithm. Haar feature-based cascade classifiers is used as an effective object detection method proposed by [23].
- 485 3. face recognition: with the facial images already extracted, the face recognition algorithm is responsible for finding characteristics which best describe the image. Local Binary Patterns Histograms (LBPH) [16] is used for face recognition. We used a dataset of faces populated with a set of faces from people of Smart Internet Lab ⁹ following data protection and private security for UK.

Figure 6 shows the smart city safety experimentation architecture at UNIVBRIS NFVI. The main building block of this experimentation is composed of a 360° camera connected via WiFi 2.4Ghz to a Raspberry PI (Raspi) Model B and both are connected to a 28000mA battery and attached to a Bike Helmet. The Raspi is connected to the

495 Cloud via WiFi 5GHz. Basically the 360° camera captures the live stream video and sends to the Raspi that sends it to the datacenter to be processed. The processing takes place through the VNF video transcoder and the face detection and recognition programs. As a result, the processed live stream video is sent to a screen where faces of people are recognized.

500 The use case was deployed indoor (in the Smart Internet Lab) and outdoor (Millennium Square in Bristol City Center) ¹⁰.

We perform extensive evaluations of the smart city safety use case running on top of 5GinFIRE ecosystem. The evaluation focuses on testing the 5GinFIRE functionalities and capabilities and, at the same time, the application performance regarding to real

505 time requirements. As an example of our evaluation, Figure 7 shows the Total Response

⁹<http://www.bristol.ac.uk/engineering/research/smart/>

¹⁰Smart City Safety Demo: <https://www.bristol.ac.uk/engineering/research/smart/5g-demonstrations/smart-city-safety/>

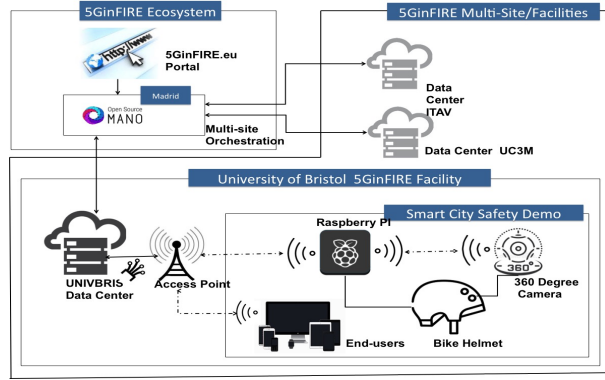


Figure 6: Smart City Safety experimentation architecture.

Time (TRT) for one of the cameras (the results are similar for the other cameras). TRT is the time since the frame is sent from the camera to the datacenter plus the VNF processing time and the time for the video being received at UE. From the real time application point of view, having a small TRT is the main goal. We can observe that the average TRT is $\mu = 0.551 \text{ seconds}$ with $\sigma = \pm 0.132$. The TRT values per frame are slightly similar without being affected for high outliers. Resulting in a good QoE.

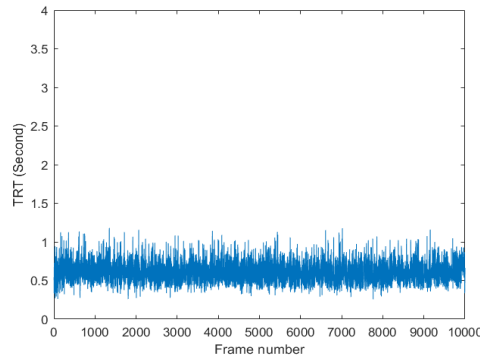


Figure 7: Total response time per video frame.

5.3. Drones

Other example of use case developed from the aforementioned platform is an application of the NFV technology to enable the flexible deployments of *Unmanned Aircraft Systems* (UAS), capable of adapting to different missions in the civil scope. Highlight

that UAS are composed by a set of *Unmanned Aerial Vehicles* (UAVs), which are more commonly known as drones. Accordingly, this use case aims at providing the underlying substrate to execute properly networks functions, as well as transport and application functions through virtualization technologies where the computational resources are provided by the UAVs composing the UAS.

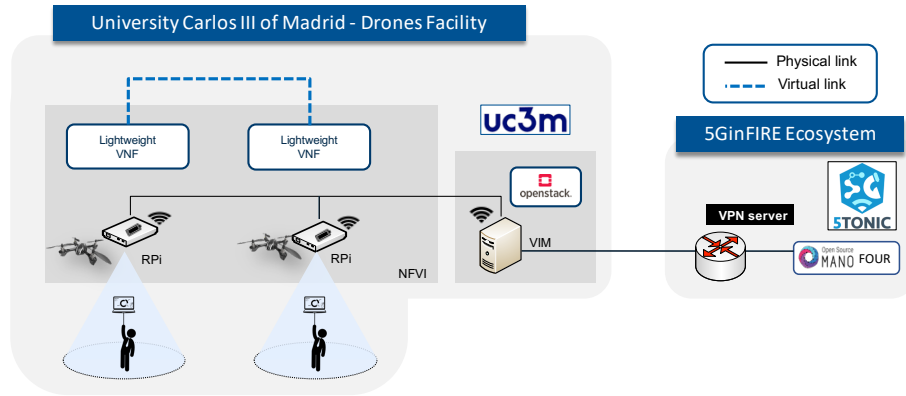


Figure 8: Drones use case architecture

Figure 8 shows the system design employed in this use case, which is mainly composed by three entities; (1) the OSM system, located at 5TONIC and within 5GinFIRE ecosystem, and responsible for orchestrating the deployment of different lightweight VNFs (the term lightweight VNF is referred to those VNFs with low computational cost, capable of being executed in a limited capacity infrastructure as the one offered by an UAV) in the drones facility, as well as the interconnection and configuration of those lightweight VNFs; (2) the hardware and software infrastructure carried out by the UAVs composing the NFVI, which is capable of supporting the execution of the lightweight VNFs; and (3) the VIM in charge of the management of the physical and software resources made available by the NFVI.

This design is provided with a WiFi interface in each UAV, enabling the data exchange with the rest of UAVs that are located within its coverage radio. Additionally, some UAVs can act as access points, offering a common technology to allow the access of users to the services provided by the UAS. Thus, the system design supports

the execution of lightweight VNFs along with the wireless communications among themselves. In this context, different experiments have been carried out to evaluate the network performance offered in the communications between two lightweight VNFs that are hosted by two different UAVs. The first experiment estimates the end-to-end delay between both lightweight VNFs based on the round-trip time (RTT) measurements collected using the *Ping* tool. Figure 9.a makes use of the Cumulative Distribution Function (CDF) of the RTT measured and illustrates that the the 90% of the RTT samples are lower than 11 ms. In a second experiment, the evaluation is focused in the estimation of the bandwidth provided. For this purpose, the throughput is calculated using the *Iperf* tool and with the CDF of the samples, Figure 9.b shows that the 80% of the measurements are above 10 Mbps and also that the maximum value is 12.5 Mbps. Comparing the obtained results with [22], where the authors perform an extensive analysis IN the wireless communications of the UAV devices, it can be concluded that the network performance in terms of end-to-end delay and through is not significant affected by the provision of network functionalities through the use lightweight VNFs.

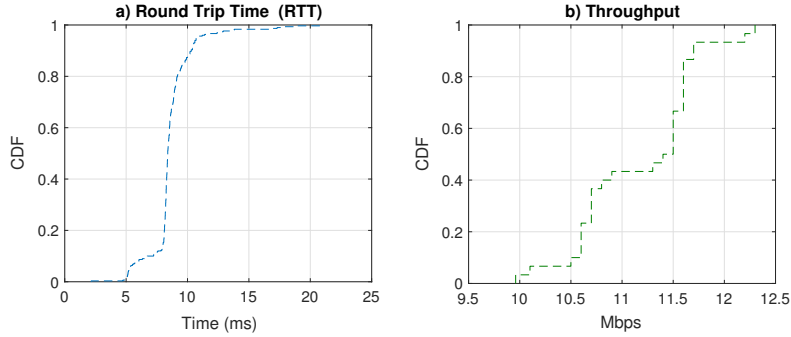


Figure 9: Network performance analysis in the Drones use case

Finally, the implementation of this system design is based on existing open source technologies. Regarding to MANO system, the orchestration solution selected is the one provided by OSM. On the other hand, the cloud computing platform provided by

555 OpenStack handles the management of VIM. For the NFVI composed by the UAV,
Single Board Computers offered by the Raspi provide the sufficient compute capacity
to the UAVs to enable the execution of lightweight VNFs. The lightweights VNFs are
implemented using the containers as virtualization technology. This solution offers a
more elastic way for implementing function virtualization in the UAS context, since the
560 hardware and software resources provided by the UAVs is limited. The work in [21]
and [20] present more in detail the use of UAVs in an NFV environment along with
different experiments to validate the feasibility of a system like the already presented
throughout this section.

6. Remarks and Conclusion

565 5GinFIRE has established the first 5G NFV-enabled experimental testbed capable
of instantiating and supporting vertical industries based on industry-leading and open
source technologies. In particular, it creates an open environment for verticals by es-
tablishing an industry-led and industry-focused common environment which comple-
ments the planned activities in ETSI and 5G-PPP for vertical services development and
570 demonstration and at that same time provides the forerunner experimental platform for
FIRE+ engagement in ETSI standardization, 5G-PPP, and future marker transfer.

As we are in the dawn of softwarisation of whole vertical service architectures
which are then deployed across NFV-enabled infrastructures, it is important to explic-
itly deal with specific verticals in order to understand the dynamics behind the life-
575 cycle process of deploying and operating them. It is also equally important to establish
best practices of how a vertical service that is usually hosted in closed environments, it
should break down into, or composed of components that are distinct and can be com-
bined on demand. 5GinFIRE has specified, implemented and deployed automotive
and smart city vertical which can be instantiated on top of the common experimental
580 facilities and customized for targeted experimentation.

The specification of experiments or, equivalently, of the service architecture of
verticals followed by the deployment, instantiation, and operation across 5G NFV-
enabled infrastructure substrate and vertical-specific physical facilities require the effi-

cient coordination and interoperation of a multitude of functional components known
585 as MANO functionality. MANO covers the orchestration and life-cycle management of
experiments, which coincide with the life-cycle management of VNFs from the NFV
perspective due to the fact that 5GinFIRE shares the same requirements and archi-
tecture framework as ETSI NFV. In this case, 5GinFIRE has integrated MANO open
source components and has increased the level of automation in instantiating any vir-
590 tual function component for experimentation, not just VNFs, including *VxFs*. This has
a great impact on innovation as it gives rise to a modular and pluggable system wherein
more sophisticated functionality pertaining to MANO architectural components or ser-
vice verticals can be tested.

In the spectrum from idea to application, 5GinFIRE is a strong contender for the
595 swift development of marketable products, and yet, with a significant degree of innova-
tion stemming from recent research in the field of FIRE technologies and experimen-
tation tools and facilities. We believe that 5GinFIRE is in a advantageous positioning
for the development of innovative end-to-end 5G experimentation products, Vertical
deployments and integrations that take into account various factors such as practical
600 feasibility, sustainability and market growth.

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