# Statistics Complements to

# Modern Applied Statistics with S-Plus

# Second edition

by

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These complements have been produced to supplement the second edition of MASS. They will be updated from time to time. The definitive source is <a href="http://www.stats.ox.ac.uk/pub/MASS2/">http://www.stats.ox.ac.uk/pub/MASS2/</a>.

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Selectable links are in this colour. Selectable URLs are in this colour.

# Introduction

These complements are made available on-line to supplement the book making use of extensions to S-PLUS in user-contributed library sections.

The general convention is that material here should be thought of as following the material in the chapter in the book, so that new sections are numbered following the last section of the chapter, and figures and equations here are numbered following on from those in the book.

All the libraries mentioned are available for Unix and for Windows. Compiled versions for Windows (for both S-PLUS 3.x and 4.x) are available from either of the URLs

```
http://www.stats.ox.ac.uk/pub/SWin/http://lib.stat.cmu.edu/DOS/S/SWin/
```

Most of the Unix sources are available at

```
http://lib.stat.cmu.edu/S/
```

and more specific information is given for the exceptions where these are introduced.

There are separate Complements documents for programming and for S-PLUS 4.x available from http://www.stats.ox.ac.uk/pub/MASS2/.

# Contents

Introduction				
5	Dist	ributions and Data Summaries	1	
	5.5	Density estimation	1	
	5.6	Bootstrap and permutation methods	8	
7	Gene	eralized Linear Models	12	
	7.1	Functions for generalized linear modelling	12	
	7.3	Poisson models	12	
	7.5	Gamma models	18	
9	Non-	-linear Models	22	
	9.4	Confidence intervals for parameters	22	
10	Random and Mixed Effects			
	10.3	Linear mixed effects models	24	
	10.4	Non-linear mixed effects models	30	
	10.5	Using 1me with autocorrelated data	35	
11	Mod	lern Regression	<b>37</b>	
	11.1	Additive models and scatterplot smoothers	37	
	11.2	Projection-pursuit regression	44	
	11.4	Neural networks	49	
12	Survival Analysis			
	12.1	Estimators of survival curves	55	
	12.6	Non-parametric models with covariates	57	
13	Mult	tivariate Analysis	62	
	13.3	Discriminant analysis	62	
	13.5	Factor analysis	65	

Co.	ontents	iii
14	Tree-based Methods	<b>67</b>
	14.4 Library RPart	67
	14.5 Tree-structured survival analysis	79
15	Time Series	86
	15.1 Second-order summaries	86
16	Spatial Statistics	89
	16.3 Module S+SPATIALSTATS	89
17	Classification	93
	17.3 Forensic glass	93
	17.4 Cross-validation	101
References		
Index		

# Chapter 5

# Distributions and Data Summaries

## 5.5 Density estimation

Simonoff (1996) provides an excellent overview of methods for both smoothing and density estimation. Bowman & Azzalini (1997) concentrate on providing an introduction to kernel-based methods, with an easy-to-use S-PLUS library sm<sup>1</sup> This has the unusual ability to compute and plot kernel density estimates of three-dimensional and spherical data.

Kernel density estimation is a rather simple and usual rapid procedure (although bandwidth selection need not be). More recently there have been a number of alternative approaches which use very much greater amounts of computation.

#### Spline fitting to log-densities

There are several closely-related proposals<sup>2</sup> to use a univariate density estimator of the form

$$f(y) = \exp q(y; \theta) \tag{5.7}$$

for a parametric family  $g(\cdot;\theta)$  of smooth functions, most often splines. The fit criterion is maximum likelihood, possibly with a smoothness penalty. The advantages of (5.7) is that it automatically provides a non-negative density estimate, and that it may be more natural to consider 'smoothness' on a relative rather than absolute scale. It is necessary to ensure that the estimated density has unit mass, and this is most conveniently done by taking

$$f(y) = \exp g(y; \theta) / \int \exp g(y; \theta) \, dy \tag{5.8}$$

The library logspline  $^3$  by Charles Kooperberg implements one variant on this theme by Kooperberg & Stone (1992), although a later version described in Stone *et al.* (1997) is promised to replace it. This uses a cubic spline for g in (5.8), with smoothness controlled not by a penalty (as in smoothing splines) but

 $<sup>^1</sup>$  available from http://www.stats.gla.ac.uk/~adrian/sm and http://www.stat.unipd.it/dip/homes/azzalini/SW/Splus/sm.

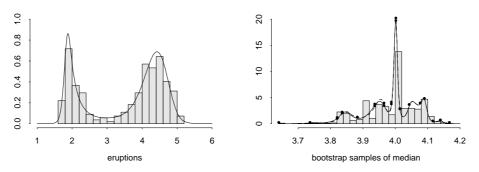
<sup>&</sup>lt;sup>2</sup> see Simonoff (1996, pp. 67–70, 90–92) for others.

 $<sup>^{3}</sup>$  logsplin on Windows.

by the number of knots selected. There is an AIC-like penalty; the number of the knots is chosen to maximize

$$\sum_{i=1}^{n} g(y_i; \widehat{\theta}) - n \log \int \exp g(y; \widehat{\theta}) \, dy - a \times \text{number of parameters}$$
 (5.9)

The default value of a is  $\log n$  (sometimes known as BIC) but this can be set as an argument of logspline.fit. A Newton method is used to maximize the log-likelihood given the knot positions. The initial knots are selected at quantiles of the data and then deleted one at a time using the Wald criterion for significance. Finally, (5.9) is used to choose one of the knot sequences considered.

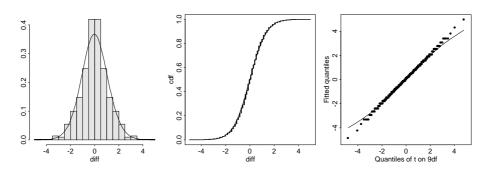


**Figure 5.12**: Histograms and logspline density plots of (left) the Old Faithful eruptions data and (right) bootstrap samples of the median of that dataset. Compare with Figures 5.8 (on page 182), Figure 9.4 (page 288) and Figure 5.11 (page 188).

We first try out our two running examples:

```
library(logspline) # logsplin on Windows
attach(faithful)
faithful.ls <- logspline.fit(eruptions, lbound=0)</pre>
x \leftarrow seq(1, 6, len=200)
truehist(eruptions, nbins=15, xlim=c(1,6), ymax=1.0)
lines(x, dlogspline(x, faithful.ls))
detach()
truehist(tperm, xlab="diff")
tperm.ls <- logspline.fit(tperm)</pre>
x \leftarrow seq(-5, 5, len=200)
lines(x, dlogspline(x, tperm.ls))
sres <- c(sort(tperm), 5); yres <- (0:1024)/1024</pre>
plot(sres, yres, type="S", xlab="diff", ylab="cdf")
lines(x, plogspline(x, tperm.ls))
par(pty="s")
x \leftarrow c(0.0005, seq(0.001, 0.999, 0.001), 0.9995)
plot( qt(x, 9), qlogspline(x, tperm.ls),
      xlab="Quantiles of t on 9 df", ylab="Fitted quantiles",
      type="1", xlim=c(-5, 5), ylim=c(-5, 5))
points( qt(ppoints(tperm), 9), sort(tperm) )
```

The functions dlogspline, plogspline and qlogspline compute the density, CDF and quantiles of the fitted density, so the final plot is a QQ-plot of the data and the fitted density against the  $t_9$  density. The final plot shows that the  $t_9$  density is a better fit in the tails; the logspline density estimate always has exponential tails. (The function logspline.plot will make a simple plot of the density, CDF or hazard estimate.)



**Figure 5.13**: Plots of the logspline density estimate of the permutation dataset tperm. The three panels show the histogram with superimposed density estimate, the empirical and fitted CDFs and QQ-plots of the data and the fitted density against the conventional  $t_9$  distribution.

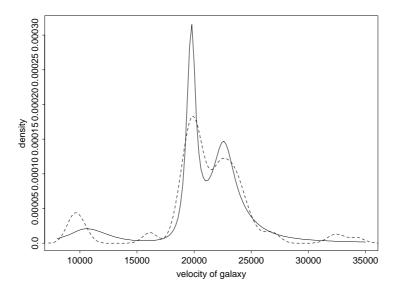
We can also explore density plots of the bootstrapped median values from page 187 (which we recall actually has a discrete distribution).

```
truehist(res, nbins=nclass.FD(res), ymax=20)
x <- seq(3.7, 4.2, len=1000)
res.ls <- logspline.fit(res)
lines(x, dlogspline(x, res.ls))
points(res.ls$knots, dlogspline(res.ls$knots, res.ls))
res.ls <- logspline.fit(res, penalty=2)
lines(x, dlogspline(x, res.ls), lty=3)
points(res.ls$knots, dlogspline(res.ls$knots, res.ls))</pre>
```

Changing the penalty a to the AIC value of 2 has a small effect. The dots show where the knots have been placed. (The function logspline.summary shows details of the selection of the number of knots.)

The results for the galaxies data are also instructive.

Maximum-likelihood methods and hence logspline.fit can easily handle censored data (see page 55).



**Figure 5.14**: Logspline (solid line) and kernel density (dashed) estimates for the galaxies data. The bandwidth of the kernel estimate was chosen by width.SJ.

## Local polynomial density estimation

The local regression approach of loess can be extended to local likelihood estimation and hence used for density estimation. One implementation is the function locpoly in library  $KernSmooth^4$ . This uses a fine grid of bins on the x axis and applies a local polynomial smoother to the counts of the binned data.

Loader (1997) introduces his implementation in the locfit package; the theory for density estimation is in Loader (1996). The default is that  $\log f(y)$  is fitted by a quadratic polynomial: to estimate the density at x we maximize

$$\sum_{i=1}^{n} K\left(\frac{y_i - x}{b}\right) g(y_i; \theta(x)) - n \log \int K\left(\frac{y - x}{b}\right) \exp g(y; \theta(x)) dy$$

that is, (5.9) localized near x, and with a quadratic polynomial model for  $g(y;\theta)$ . The function K is controlled by the argument kern; by default it is the tricubic function used by loess; kern="gauss" gives a Gaussian kernel with bandwidth 2.5 times<sup>5</sup> the standard deviation. The documentation with the package is sparse: the Web site

has the sources and a number of on-line documents from which the details here were gleaned.

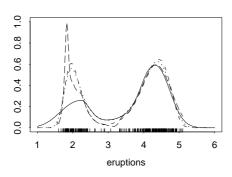
We can use locfit on the eruptions data by

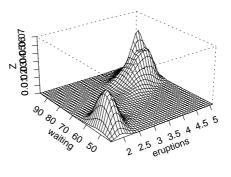
<sup>&</sup>lt;sup>4</sup> ksmooth on Windows. The current Unix sources are at http://www.biostat.harvard.edu/~mwand

<sup>&</sup>lt;sup>5</sup> density and hence our account in Chapter 5 uses  $4\times$ .

```
library(locfit, first=T)
faithful.lf <- locfit(~ eruptions, data=faithful, flim=c(1,6))
plot(faithful.lf, get.data=T, mpv=200, ylim=c(0,1))</pre>
```

where get.data adds the rug and mpv evaluates at 200 points to ensure a smooth curve. (The flim parameter asks for a fit to cover that range of x values.)





**Figure 5.15**: locfit density estimates for the faithful dataset. **Left:** Density of the duration of eruptions. The solid line is the default, the medium dashed line is from **Loader** (1997), the dotted line is a constant bandwidth chosen by AIC, and the long-dashed line (with a sharp peak) is the adaptive bandwidth chosen by a surrogate Poisson model for the binned data. **Right:** Joint density of both variables.

As for loess we have to choose how much to localize, that is to choose the bandwidth h, possibly as a function of x. This is done in locfit by choosing the larger of a nearest-neighbour-based estimate and a fixed bandwidth. On the very similar geyser dataset Loader (1997) suggests

but without explaining where these numbers came from. (The default is c(0.7, 0). The notes on the Web site have c(0.1, 0.8). Clearly this is not an automated choice!) The first number is equivalent to the span parameter of loess; set it to zero to remove the adaptive part of the bandwidth choice. The second number is a fixed bandwidth; there is also a third argument related to the penalty in (5.9) which we discuss below.

locfit can handle censored data, and provide estimates of the density or hazard (see page 55). It can also, in a limited way, handle multidimensional density estimation. For example, we can produce a perspective plot of the joint density of the two variables in the faithful dataset by

Compare this to the perspective plot of Figure 5.9 on page 185 of the book. One restriction is that the same bandwidth is chosen in all variables, so the variables

need to be rescaled<sup>6</sup> to a scale on which such a bandwidth would be acceptable. (Setting scale=0 forces such a scale to be chosen.) The default is to use a spherically symmetric kernel, but kt="prod" chooses a product kernel.

#### Bandwidth selection

Loader advocates a local version of AIC for bandwidth selection. For a constant bandwidth he gives a function akaike. We use this for a gaussian kernel with standard deviation  $h \in (0.1, 0.6)$ , remembering that density has 4 times and locfit 2.5 times the standard error as the 'bandwidth' for a Gaussian kernel.

```
akaike <- function(formula, alpha, pen=2, ...)</pre>
  m <- nrow(alpha); ll <- numeric(m); vr <- numeric(m)</pre>
  for(i in 1:m) {
    fit <- locfit(formula, alpha=alpha[i,], ...)</pre>
    ll[i] <- fit$dp["lk"]; vr[i] <- fit$dp["t0"]</pre>
  cbind(alpha=alpha, LogLik=11, df=vr, AIC=-2*11+pen*vr)
attach(faithful)
akaike( ~ eruptions,
       alpha = cbind(0, 2.5 * seq(0.1, 0.6, by = 0.05)),
       ev = "data", kern = "gauss")
                  LogLik
                                df
                                         AIC
 [1,] 0 0.250 -249.8242 21.410054 542.4684
 [2,] 0 0.375 -255.1024 14.860509 539.9258
 [3,] 0 0.500 -258.1887 11.261502 538.9003
 [4,] 0 0.625 -259.1892 9.056460 536.4914
 [5,] 0 0.750 -258.8195 7.655461 532.9498
 [6,] 0 0.875 -257.7784 6.704812 528.9664
 [7,] 0 1.000 -256.5723 6.015671 525.1760
 [8,] 0 1.125 -255.8101 5.493791 522.6078
 [9,] 0 1.250 -256.2696 5.088088 522.7155
[10,] 0 1.375 -258.7174 4.764574 526.9640
[11,] 0 1.500 -263.6509 4.497959 536.2977
```

The df term is the local version of the number of parameters. This suggests  $h \approx 0.48$ , which we can fit by

The parameter ev controls where the fitted density is evaluated (and interpolation from these points is used for prediction). To find the AIC we evaluate at the data points, whereas for plotting we evaluate at a grid of mg points. The m argument of lines.locfit is equivalent to mpv, controlling the number of points at which the curve is plotted.

<sup>&</sup>lt;sup>6</sup> without this the computational shortcuts used by locfit fail in this example

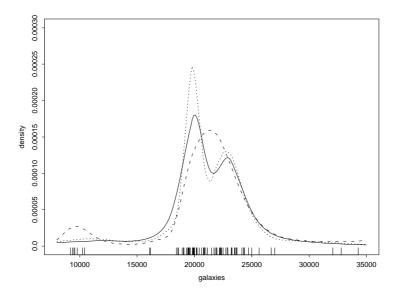
Loader (1995) suggests an alternative approach, which is to bin the data and treat the counts as independent Poisson variates (which they are not, but as for surrogate Poisson GLMs this gives the correct likelihood). We can then use a local log-linear model to smooth the counts, and allow its bandwidth to be chosen locally by minimizing the local AIC.

This seems to be the most successful approach.

We can also consider the galaxies data.

```
plot(locfit(~ galaxies, flim=c(8000, 35000)),
     get.data=T, ylim=c(0, 0.0003), mpv=200)
akaike( ~ galaxies,
       alpha=cbind(seq(0.15, 0.7, 0.05), 0),
       ev="data", kern="gauss")
 [1,] 0.15 0 -763.8799 22.344750 1572.449
 [2,] 0.20 0 -769.8116 17.432047 1574.487
 [3,] 0.25 0 -772.8257 14.899450 1575.450
 [4,] 0.30 0 -773.0860 13.101204 1572.374
 [5,] 0.35 0 -773.8923 11.804248 1571.393
 [6,] 0.40 0 -774.1579 10.487591 1569.291
 [7,] 0.45 0 -774.7961 9.467591 1568.527
 [8,] 0.50 0 -776.1849 8.304028 1568.978
 [9,] 0.55 0 -776.7574 7.741446 1568.998
[10,] 0.60 0 -778.5080 7.316588 1571.649
[11,] 0.65 0 -779.3692 6.922880 1572.584
[12,] 0.70 0 -780.3391 6.610473 1573.899
fit <- locfit(~ galaxies, alpha=0.45, flim=c(8000, 35000),
        kern="gauss", ev="grid", mg=200)
lines(fit, m=200, lty=2)
galaxies.bin <- data.frame(velocity=seq(8000, 35000, 500),</pre>
    count=hist(galaxies, breaks=seq(7750, 35250, 500),
               plot=F)$counts)
fit2 <- locfit(count ~ velocity, data=galaxies.bin,</pre>
               weights=rep(82*500, nrow(galaxies.bin)),
               alpha=c(0, 0, 2), family="poisson")
lines(fit2, m=200, lty=3)
```

Here the choice by local AIC of an adaptive bandwidth fails to work well, and seems very sensitive to the rounding used.



**Figure 5.16**: locfit density estimates for the galaxies dataset. The solid line is the default, the dotted line has a variable bandwidth chosen by AIC, and the dashed line uses a surrogate Poisson model.

## 5.6 Bootstrap and permutation methods

## Using library boot

The main text discusses some of the bootstrap functions introduced in S-PLUS 4.0. In this complement we consider the library boot of Davison & Hinkley (1997). This is included on a diskette with the book in both Unix and Windows versions, and can be downloaded from

```
http://dmawww.epfl.ch/davison.mosaic/BMA/library.html
```

```
> library(boot)
> attach(faithful)
> set.seed(101)
> erupt.boot <- boot(eruptions, function(x,i) median(x[i]),
                     R=1000)
> erupt.boot
ORDINARY NONPARAMETRIC BOOTSTRAP
Bootstrap Statistics:
    original
                bias
                        std. error
t1*
           4 -0.014807
                          0.078703
> boot.ci(erupt.boot, conf=c(0.90, 0.95),
          type=c("norm","basic","perc","bca"))
BOOTSTRAP CONFIDENCE INTERVAL CALCULATIONS
Based on 1000 bootstrap replicates
```

```
Intervals:
Level Normal Basic
90% (3.885, 4.144) (3.908, 4.167)
95% (3.861, 4.169) (3.892, 4.167)

Level Percentile BCa
90% (3.833, 4.092) (3.825, 4.083)
95% (3.833, 4.108) (3.759, 4.083)
Calculations and Intervals on Original Scale
Some BCa intervals may be unstable
```

Note that the results are similar to those using bootstrap, but not identical as the random numbers are used in a different way. In this particular example the BCa confidence intervals are very slow to calculate.

Davison & Hinkley's function boot is much more general than bootstrap in that it allows many other types of bootstrap sampling. What is commonly known as the bootstrap (random sampling with replacement from the original dataset) is the default but boot can also perform a parametric bootstrap (sampling from a fitted distribution specified by argument ran.gen), and stratified, weighted, balanced, antithetic and permutational sampling. Functions censboot and tsboot implement various forms of the bootstrap that have been suggested for right-censored data and time series respectively.

The function boot.ci calculates confidence intervals of one or more of five types, the first-order normal approximation, the percentile bootstrap interval (that found from the percentiles of the bootstrap distribution), the basic bootstrap interval (the percentile interval reflected about the estimate) and the BCa correction to the basic interval. Finally, it can calculate a studentized bootstrap interval (a basic bootstrap interval applied to a studentized statistic), and compute intervals on a transformed scale.

We also consider bootstrapping residuals from a non-linear regression on pp. 281–2. We can repeat that analysis with library boot by a very small change to the function storm.bf. The bootstrapping here took about 90 seconds, the confidence interval calculations about 5 seconds each. (The times for bootstrap under 4.x are very similar.)

```
t1* 28.7156 0.71178
                      0.84350
t2* 2.4799 -0.29007 0.60765
> boot.ci(storm.boot, index=1,
        type=c("norm", "basic", "perc", "bca"))
   . . . .
Intervals:
Level Normal Basic
95% (26.35, 29.66) (26.29, 29.63)
Level Percentile
                           BCa
95% (27.80, 31.14) (27.10, 29.66)
Calculations and Intervals on Original Scale
Warning: BCa Intervals used Extreme Quantiles
Some BCa intervals may be unstable
> boot.ci(storm.boot, index=2,
        type=c("norm", "basic", "perc", "bca"))
   . . . .
Intervals:
Level Normal
                          Basic
95% (1.579, 3.961) (1.632, 4.111)
Level Percentile
                           BCa
95% (0.848, 3.328) (1.588, 3.802)
Calculations and Intervals on Original Scale
Some BCa intervals may be unstable
```

The index parameter selects which of the components of the statistic are of interest. In this example it looks as if the percentile interval has a considerable bias. For reference, BCa intervals from the bootstrap output are given in Section 9.4 of these complements.

#### Using library bootstra

Another, older, set of bootstrap functions written by Rob Tibshirani accompanies Efron & Tibshirani (1993). This is usually installed as library section bootstrap on a Unix machine but as bootstra on a Windows machine<sup>7</sup>. This too has a function bootstrap to perform the bootstrap sampling, and other functions to find bootstrap confidence intervals which similar code to bootstrap internally. This S code is written less efficiently than that in 4.x or boot, and should be used with care to avoid using excessive amounts of memory.

There is little advantage in using this function bootstrap for simple bootstrap sampling, as there are no special tools to analyse its results.

```
> library(bootstra)
> attach(faithful)
> set.seed(101)
> erupt.boot <- bootstrap(eruptions, 1000, median)</pre>
```

<sup>&</sup>lt;sup>7</sup> since S-PLUS 3.x for Windows can only use MSDOS 8+3 filenames.

```
> mean(erupt.boot$thetastar - median(eruptions))
[1] -0.014807
> sqrt(var(erupt.boot$thetastar))
[1] 0.078703
```

However, the function bootstrap also incorporates the 'jackknife after bootstrap' technique.

As this code was already using 25 Mb of memory, this is not practicable advice.

This library has functions beanon and boott to compute BCa and studentized confidence limits, but the first fails on this example.

We can also consider the Stormer viscometer data from Section 9.4. There we bootstrap residuals, so cannot use the jackknife directly and hence beanon (which tries to evaluate the function on vectors of size n-1) fails. We can use boott, but it is slow (15 minutes), especially so as the bootstrapping has to be run separately for each component of the parameter.

```
storm.bf1 <- function(rs) {</pre>
     assign("Tim", fitted(storm.fm) + rs, frame = 1)
     nls(Tim ~ (b * Viscosity)/(Wt - c), stormer,
              start = coef(storm.fm))$parameters[1]
  }
storm.bf2 <- function(rs) {</pre>
     assign("Tim", fitted(storm.fm) + rs, frame = 1)
     nls(Tim ~ (b * Viscosity)/(Wt - c), stormer,
              start = coef(storm.fm))$parameters[2]
  }
set.seed(101)
boott(rs, storm.bf1, perc=c(0.025, 0.05, 0.95, 0.975))
$confpoints:
             0.05 0.95 0.975
      0.025
[1,] 26.434 26.825 29.228 29.336
set.seed(101)
boott(rs, storm.bf2, perc=c(0.025, 0.05, 0.95, 0.975))
$confpoints:
      0.025 0.05 0.95 0.975
[1,] 1.8939 2.0168 3.6694 3.8459
```

# Chapter 7

# Generalized Linear Models

## 7.1 Functions for generalized linear modelling

Estimation of the dispersion parameter  $\varphi$ 

We saw on page 226 that an approximately unbiased estimator of the dispersion parameter  $\varphi$  is

$$\widehat{\varphi} = \frac{D_M}{n - p}$$

This is not, however, the estimator used by summary.glm, which is the sum of squares of the Pearson residuals divided by the residual degrees of freedom. Thus

$$\widetilde{\varphi} = \frac{1}{n-p} \sum_{i} \frac{(y_i - \hat{\mu}_i)^2}{V(\hat{\mu}_i)/A_i}$$
(7.11)

where  $V(\mu)$  is the variance function. (Here p is the number of linearly independent parameters.) Note that  $\widetilde{\varphi} = \widehat{\varphi}$  for the Gaussian family, but in general differs.

The estimate of dispersion is only used to compute the estimated standard errors of the coefficients, and only for the binomial and Poisson families if summary is called with argument dispersion=0. We explore further the estimation of the dispersion parameter for a Gamma family in Section 7.5.

#### 7.3 Poisson models

Log-linear models with formulae and data frames

The standard function loglin fits a log-linear model to frequency data by iterative proportional scaling, which can be more computationally efficient than the surrogate Poisson model approach, particularly for very large frequency arrays. However, it has several limitations.

• It can only handle categorical predictor variables, and the frequencies must be given as a complete multiway frequency table. Missing cells (or structural zeros) *can* be handled. Note that this is not a necessary restriction; the more general algorithm developed in Darroch & Ratcliff (1972) can handle both quantitative and categorical predictors.

- It cannot discover redundancies in the underlying model matrix. Hence if there are missing cells loglin may report an incorrect number of error degrees of freedom. This restriction is difficult to overcome without explicitly constructing the model matrix, something that iterative proportional scaling algorithms are designed to avoid.
- Deviances and fitted values are the main products of the algorithm. If the input frequency array has no missing cells and none with zero fitted values, constrained parameter estimates relative to a complete dummy variable model matrix are available, but their standard errors are not.

Nevertheless it is an important and useful fitting algorithm for very large frequency tables

The algorithm is based on the score equations for Poisson data with the natural log link. That is, the mean vector,  $\mu$ , must have the appropriate multiplicative structure and satisfy

$$X^T y = X^T \mu$$

where X is the model matrix. With purely categorical predictors this implies that the arrays of observed frequencies and of the fitted values have identical *marginal totals*. Hence it is sufficient to specify the margins over which frequency and fitted values must have the same totals. For example, for a three-way frequency table, Fr, the 'no three-factor-interaction' model may be specified by

$$loglin(Fr, list(c(1,2), c(1,3), c(2,3)))$$

where the second argument specifies that all two-way faces must have the same marginal totals. If Fr has a dimnames attribute with *named* components the marginal faces may be specified using these names, so if we set

we could specify the no three-factor-interaction model as

Note that if the c(1,2) -face is specified then all faces marginal to it—the first and second dimensions and the entire array—also have equal frequency and fitted value totals. These redundant faces may also be specified, although this may slow down the algorithm slightly.

The function loglm in the MASS library is designed to make calls to loglin easier by allowing the fixed margins to be specified by an S formula and the frequencies to be specified either as an array or as a vector in, for example, a data frame. In the latter case the frequency array will be constructed before calling

7.3 Poisson models 14

loglin. If the frequencies are specified as an array, the formula has an empty left-hand side and the right-hand side specifies the fixed marginal totals. Thus the previous example could be handled by calling either

```
loglm(~(1 + 2 + 3)^2, Fr)
```

or, if the dimnames are present,

```
loglm(\sim (A + B + C)^2, Fr)
```

Note that the dimensions of the array may always be referred to by *number* using the same convention as loglin, and that any multiplicative-like term connecting the faces, such as 1:2, 1\*2 or even 1/2, simply implies 'the c(1,2) -face'. In constructing the call to loglin, loglm finds and uses only the minimal set of marginal totals which must agree, so it does not matter if (as here) the formula specifies some redundant margins.

Let us consider the detergent brand preference study on page 238–242 of Chapter 7, which is a four-way contingency table. We can fit the final model specified as a GLM on page 240 using the same formula in a call to loglm.

This call to loglm actually constructs the iterative proportional scaling fit via loglin shown as detg.ips on page 241.

For another example, consider the Minnesota school leavers' data of 1938. The frequencies are held in the data frame minn38, but this is easily converted into a complete frequency array.

```
> sapply(minn38, function(x) length(levels(x)))
hs phs fol sex f
3  4  7  2 0
> minn38a <- array(0, c(3,4,7,2), lapply(minn38[, -5], levels))
> minn38a[data.matrix(minn38[, -5])] <- minn38$f
> minn38.fm <- loglm(~ 1 + 2 + 3 + 4, minn38a)
> minn38.fm1 <- update(minn38.fm, ~.^2)
> minn38.fm2 <- update(minn38.fm, ~.^3)</pre>
```

This uses numeric labels for the variables (dimensions) and fits complete 1-, 2- and 3-factor interaction models. Since this way of constructing the array also supplies names for the dimnames attribute, we could have specified the first model as

```
minn38.fm <- loglm(~ hs + phs + fol + sex, minn38a)
```

and subsequent updates would have carried the names forward. The advantage would have that later output will carry the informative names rather than the numeric labels. The object resulting from a call to loglm carries class loglm, for which methods for the generic functions summary, print, anova, coef, deviance, fitted, residuals and update are provided.

The print method displays the object in a succinct way.

The default behaviour for the summary method is to give almost the same output, but with the argument fitted=T this will also give tables of observed and expected frequencies. For example

```
> summary(minn38.fm2, fitted=T)
Re-fitting to find fitted values
Formula:
 \sim 1 + 2 + 3 + 4 + 1:2 + 1:3 + 1:4 + 2:3 + 2:4 + 3:4 +
        1:2:3 + 1:2:4 + 1:3:4 + 2:3:4
Statistics:
                   X^2 df P(> X^2)
Likelihood Ratio 47.745 36 0.091137
        Pearson 47.184 36 0.100486
Observed (Expected):
, , F1, F
           C
                       Ε
                                   N
L 53 (49.5) 13 (16.6)
                          7 ( 7.6) 76 ( 75.4)
M 163 (163.6) 28 ( 25.8) 30 ( 29.1) 118 (120.5)
U 309 (311.9) 38 (36.6) 17 (17.3) 89 (87.2)
, , F2, F
           C
                       Ε
                                   N
                                              0
L 36 (31.5) 11 (13.9) 16 (13.2) 111 (115.4)
M 116 (112.8) 53 (47.8) 41 (42.6) 214 (220.8)
U 225 (232.7) 68 (70.3) 49 (50.2) 210 (198.8)
```

The model will be re-fitted unless fit=T was specified on the original call to loglm.

We can compare the models by likelihood-ratio tests using

```
> anova(minn38.fm, minn38.fm1, minn38.fm2)
LR tests for hierarchical log-linear models
```

7.3 Poisson models 16

```
Model 1:
 ~ 1 + 2 + 3 + 4
Model 2:
 \sim 1 + 2 + 3 + 4 + 1:2 + 1:3 + 1:4 + 2:3 + 2:4 + 3:4
Model 3:
  \sim 1 + 2 + 3 + 4 + 1:2 + 1:3 + 1:4 + 2:3 + 2:4 + 3:4
       + 1:2:3 + 1:2:4 + 1:3:4 + 2:3:4
         Deviance df Delta(Dev) Delta(df) P(> Delta(Dev))
  Model 1 3711.915 155
  Model 2 220.043 108 3491.873
                                       47
                                                 0.00000
  Model 3 47.745 36 172.298
                                       72
                                                  0.00000
Saturated 0.000 0
                         47.745
                                       36
                                                  0.09114
```

The tail areas refer to the approximate chi-squared distribution under the null hypothesis. In this instance only the final model appears near reasonable as a description of the data.

The function loglm is generic with method dispatch based on the second argument (data) rather than the first. It has a method for objects of class crosstabs which is the natural way of tabulating frequencies, particularly for factors held in data frames. For example the Cars93 data frame has information on 93 models of car released in the USA in 1993. Two factors are Type and Origin.

```
> attach(Cars93)
> levels(Type)
[1] "Compact" "Large" "Midsize" "Small" "Sporty" "Van"
> levels(Origin)
[1] "Import" "Local"
> detach()
```

We could check the (unlikely) hypothesis that the proportions of each type of vehicle are the same for imported and locally manufactured cars using

The Minnesota school leavers' example could be handled without explicitly constructing the array of frequencies by the call

```
minn38.fm \leftarrow loglm(f \sim ., minn38, fit = T)
```

Note that arguments to loglin may be specified on the call to loglm. The extra argument, fit=T, is not needed here but if supplied will cause the fitted values (and by default the frequencies as well) to be saved *as an array* in the fitted model object. Note that the customary abbreviation, '.', may be used to specify 'all

7.3 Poisson models 17

other factors in the data frame joined by +'. (This is not possible if the data are given as an array of frequencies.)

The Quine absenteeism data is an example of a four-way classification with unequal numbers of observations in each cell including some completely empty. The maximum number of observations in any one cell is 11. In cases like this the frequencies will be held as a five-way array with the last dimension, conventionally labelled .Within., playing no part in the fitted models. Empty cells in the five-way array are handled as structural zeros. The result will be a fitted log-linear model with correct deviance, but with residual degrees of freedom is sometimes incorrect.

```
> quine.loglm <- loglm(Days ~ .^3, quine)
> quine.glm <- glm(Days ~ .^3, poisson, quine)
> c(loglm = deviance(quine.loglm), glm = deviance(quine.glm))
loglm glm
    1181    1181
> c(loglm = quine.loglm$df, glm = quine.glm$df)
loglm glm
    117    120
```

Notice that (unlike loglin) loglm does subtract one degree of freedom for structural zeros, but is unable to detect the extra three degrees of freedom that result from redundancies in the model matrix.

#### How loglm works

The function loglm must be able to convert numeric labels in formulae to a form in which they can be parsed correctly. This operation is done by a recursive function called denumerate which converts a numeric label 2, say, to the identifier .v2.

```
> denumerate
function(object) UseMethod("denumerate")
> denumerate.formula
function(x)
  if(length(x) == 1) {
    if(mode(x) == "numeric" || (mode(x) == "name" &&
      any(substring(x, 1, 1) == as.character(1:9))))
      x <- as.name(paste(".v", x, sep = ""))</pre>
  }
  else {
    x[[2]] \leftarrow Recall(x[[2]])
    if(length(x) == 3 \&\& x[[1]] != as.name("^"))
      x[[3]] \leftarrow Recall(x[[3]])
  }
  X
}
```

It is not intended to be called directly by the user, but if it is, unless the object given to it is a formula it will issue a (somewhat cryptic) error message. This is one intended side-effect of making the function generic. The function renumerate is similar and converts the encoded identifiers to numeric labels. These functions provide examples of how operations on the language itself are possible and not particularly difficult.

#### 7.5 Gamma models

The role of dispersion parameter  $\varphi$  in the theory and practice of GLMs is often confusing (and not just in notation as pointed out on page 226). For a Gaussian family with identity link the moment estimator used for  $\varphi$  is the usually unbiased modification of the maximum likelihood estimator (see equations (7.6) and (7.7)). For binomial and Poisson families we usually take  $\varphi=1$ , and when we allow  $\varphi$  to vary it is almost always as an *ad hoc* adjustment for over-dispersion which does not correspond precisely to any family of error distributions. (Of course, for the Poisson family the negative binomial family introduced in Section 7.4 provides a parametric alternative way of modelling over-dispersion.)

The situation for the Gamma family is rather different. This is a parametric family which can be fitted by maximum likelihood, including its shape parameter  $\alpha$ . Elsewhere we have taken its density as

$$\log f(y) = \alpha \log \lambda + (\alpha - 1) \log y - \lambda y - \log \Gamma(\alpha)$$

so the mean is  $\mu = \alpha/\lambda$ . If we re-parametrize by  $(\mu, \alpha)$  we obtain

$$\log f(y) = \alpha(-y/\mu - \log \mu) + \alpha \log y + \alpha \log \alpha - \log y - \log \Gamma(\alpha)$$

Comparing this with the general form in equation (7.1) (on page 223) we see that the canonical link is  $\theta=1/\mu$  and  $\varphi=1/\alpha$  is the dispersion parameter. For fixed  $\varphi$ , fitting by glm gives the maximum likelihood estimates of the parameters in the linear predictor, but  $\varphi$  is estimated from the sum of squares of the deviance residuals, which need not be similar to the maximum likelihood estimator. Note that  $\widehat{\varphi}$  is used to estimate the standard errors for the parameters in the linear predictor, so appreciable differences in the estimate can have practical significance.

Some authors (notably McCullagh & Nelder (1989, pp. 295–6)) have argued against the maximum likelihood estimator of  $\varphi$ . The MLE is the solution to

$$2n \left[\log \alpha - \psi(\alpha)\right] = D$$

where  $\psi = \Gamma'/\Gamma$  is the digamma function and D is the residual deviance. Then the customary estimator of  $\varphi = 1/\alpha$  is D/(n-p) and the MLE is approximately  $1/\alpha$ 

 $<sup>^{1}</sup>$  for large  $\widehat{\alpha}$ 

 $\bar{D}(6+\bar{D})/(6+2\bar{D})$  where  $\bar{D}=D/n$ . Both the customary estimator (7.7) and the MLE are based on the residual deviance

$$D = -2\sum_{i} [\log(y_{i}/\hat{\mu}_{i}) - (y_{i} - \hat{\mu}_{i})/\hat{\mu}_{i}]$$

and this is very sensitive to small values of  $y_i$ . Another argument is that if the gamma GLM is being used as a model for distributions with a constant coefficient of variation, the MLE is inconsistent for the true coefficient of variation except at the gamma family. These arguments are equally compelling for the customary estimate; McCullagh & Nelder prefer the moment estimator

$$\hat{\sigma}^2 = \frac{1}{n-p} \sum_{i} [(y_i - \hat{\mu}_i)/\hat{\mu}_i]^2$$
 (7.12)

for the coefficient of variation  $\sigma^2$  which equals  $\varphi$  under the gamma model. This coincides with  $\widetilde{\varphi}$  as quoted by summary.glm (see (7.11) on page 12).

The functions glm.shape and glm.dispersion in library MASS compute the MLEs of  $\alpha$  and  $\varphi$  respectively from a fitted Gamma glm object. We illustrate these with an example on clotting times of blood taken from McCullagh & Nelder (1989, pp. 300–2).

```
> clotting <- data.frame(</pre>
    u = c(5,10,15,20,30,40,60,80,100),
    lot1 = c(118,58,42,35,27,25,21,19,18),
    lot2 = c(69,35,26,21,18,16,13,12,12)
> clot1 <- glm(lot1 ~ log(u), data=clotting, family=Gamma)
> summary(clot1, cor=F)
Coefficients:
                Value Std. Error t value
(Intercept) -0.016554 0.00092754 -17.848
     log(u) 0.015343 0.00041496 36.975
(Dispersion Parameter for Gamma family taken to be 0.00245)
> clot1$deviance/clot1$df.residual
[1] 0.00239
> gamma.dispersion(clot1)
[1] 0.0018583
> clot2 <- glm(lot2 ~ log(u), data=clotting, family=Gamma)
> summary(clot2, cor=F)
Coefficients:
                Value Std. Error t value
(Intercept) -0.023908 0.00132645 -18.024
     log(u) 0.023599 0.00057678 40.915
(Dispersion Parameter for Gamma family taken to be 0.00181)
> clot2$deviance/clot2$df.residual
```

```
[1] 0.0018103
> gamma.dispersion(clot2)
[1] 0.0014076
```

The differences here are enough to affect the standard errors, but the shape parameter of the gamma distribution is so large that we have effectively a normal distribution with constant coefficient of variation.

These functions may also be used for a quasi family with variance proportional to mean squared. We illustrate this on the quine dataset.

```
> gm <- glm(Days + 0.1 ~ Age*Eth*Sex*Lrn,
           quasi(link=log, variance=mu^2), data=quine)
> summary(gm, cor=F)
Coefficients: (4 not defined because of singularities)
                  Value Std. Error t value
                 Value Std. Error t value
   (Intercept) 3.06105 0.39152 7.818410
        AgeF1 -0.61870 0.52528 -1.177863
        AgeF2 -2.31911 0.87546 -2.649018
        AgeF3 -0.37623 0.47055 -0.799564
   . . . .
(Dispersion Parameter for Quasi-likelihood family taken
                                       to be 0.61315)
    Null Deviance: 190.4 on 145 degrees of freedom
Residual Deviance: 128.36 on 118 degrees of freedom
> gamma.shape(gm, verbose=T)
Initial estimate: 1.0603
Iter. 1 Alpha: 1.23840774338543
Iter. 2 Alpha: 1.27699745778205
Iter. 3 Alpha: 1.27834332265501
Iter. 4 Alpha: 1.27834485787226
Alpha: 1.27834
  SE: 0.13452
> summary(gm, dispersion = gamma.dispersion(gm), cor=F)
Coefficients: (4 not defined because of singularities)
                 Value Std. Error t value
   (Intercept) 3.06105 0.44223 6.921890
        AgeF1 -0.61870 0.59331 -1.042800
        AgeF2 -2.31911 0.98885 -2.345261
        AgeF3 -0.37623 0.53149 -0.707880
    . . . .
```

In this example the McCullagh–Nelder preferred estimate is given by

```
> sum((residuals(gm, type="resp")/fitted(gm))^2/gm$df.residual)
[1] 0.61347
```

7.5 Gamma models 21

which is the same as the estimate returned by summary.glm, whereas (7.7) gives

```
> gm$deviance/gm$df.residual
[1] 1.0878
> gamma.dispersion(gm)
[1] 0.78226
```

There will also be differences between deviance tests and the AIC used by step.glm and likelihood-ratio tests and the exact AIC. Making the necessary modifications is left as an exercise for the reader.

# Chapter 9

# Non-linear Models

## 9.4 Confidence intervals for parameters

## Bootstrapping

In this example the empirical percentile intervals appear biased, especially that for c. Running a different simulation gives

```
> storm.boot <- bootstrap(rs, storm.bf, seed=101, B=1000)
> summary(storm.boot)
   . . . .
Summary Statistics:
 Observed Bias Mean SE
  28.72 0.6821 29.398 0.8304
    2.48 -0.2506 2.229 0.6090
Empirical Percentiles:
    2.5% 5% 95% 97.5%
b 27.6406 27.989 30.734 30.91
c 0.9906 1.238 3.224 3.43
BCa Percentiles:
   2.5% 5% 95% 97.5%
b 26.616 26.661 29.433 29.681
c 1.532 1.724 3.618 3.958
Correlation of Replicates:
      b c
b 1.0000 -0.9193
c -0.9193 1.0000
```

Note that there will be warnings that indicate that the use of jackknifing in this problem is unreliable, so the BCa intervals are not to be trusted.

A 'jackknife after bootstrap' analysis confirms that the bootstrap estimates of the bias in the least-squares estimates is indicative but not statistically significant.

An alternative approach using the library boot of Davison & Hinkley (1997) is given in Section 5.6 of these Complements.

# Chapter 10

## Random and Mixed Effects

The account in the text used version 2.1 of the nlme software contained in S-PLUS 3.4, 4.0, 4.5 and 5.0. A near-final release of version 3.0 (written by Pinheiro and Bates) is now available from

```
http://nlme.stat.wisc.edu
```

for both Unix and Windows versions of S-PLUS 3.x and 4.x, and it is planned that this will be incorporated into forthcoming releases of S-PLUS. In this chapter we discuss the changes need to make our examples work with version 3.0, and also explore some analyses which were not straightforward in earlier versions.

The main innovation in nlme version 3.0 is support of multilevel random effects; however much of the system has been rewritten and the user interface re-designed. The new system needs to override the old one, so use

```
library(nlme3, first=T) # or whatever name is used locally
```

if the library has been downloaded and added.

## 10.3 Linear mixed effects models

The main change is how the 'clusters' are specified, which now has to allow multilevel random effects and is usually done by conditioning the formula in the random argument in a very similar way to Trellis formulae.

The method of estimation (REML or maximum likelihood) is specified by the argument method rather than est.method.

Making these changes to the gasoline data petrol example gives

. . . .

Note a change in value of BIC (which is no longer qualified as 'restricted') and the changes in the printed output for the fixed effects.

```
> pet3.lme <- update(pet3.lme, method = "ML")</pre>
> summary(pet3.lme)
Linear mixed-effects model fit by maximum likelihood
 Data: Petrol
    AIC
           BIC logLik
  149.38 159.64 -67.692
Random effects:
 Formula: ~ 1 | No
       (Intercept) Residual
StdDev:
           0.92889 1.8273
Fixed effects: Y \sim SG + VP + V10 + EP
            Value Std. Error DF t-value p-value
(Intercept) 19.694 0.47815 21 41.188 <.0001
        SG 0.221 0.12282 6 1.802 0.1216
        VP 0.549 0.44076 6 1.246 0.2590
       V10 -0.153 0.03417 6 -4.469 0.0042
        EP 0.156 0.00587 21 26.620 <.0001
> pet4.lme <- update(pet3.lme, fixed = Y \sim V10 + EP)
> anova(pet4.lme, pet3.lme)
        Model df AIC BIC logLik
                                        Test Lik.Ratio
         1 5 149.61 156.94 -69.806
pet4.lme
pet3.lme
            2 7 149.38 159.64 -67.692 1 vs. 2 4.2285
        p-value
pet4.lme
pet3.lme 0.1207
> coef(pet4.lme)
  (Intercept)
                V10
                          EΡ
    21.054 -0.21081 0.15759
```

It is possible to handle the oats example as in the text, but this is most naturally handled by making use of multilevel random effects.

```
> options(contrasts = c("contr.treatment", "contr.poly"))
> oats.lme <- lme(Y \sim N + V, random = \sim1 | B/V, data=oats)
> summary(oats.lme)
Data: oats
    AIC
          BIC logLik
  586.07 605.78 -284.03
Random effects:
Formula: ~ 1 | B
      (Intercept)
StdDev:
           14.645
Formula: ~ 1 | V %in% B
      (Intercept) Residual
         10.473 12.75
StdDev:
Fixed effects: Y \sim N + V
            Value Std.Error DF t-value p-value
(Intercept) 79.917 8.2203 51 9.722 <.0001
   NO.2cwt 19.500 4.2500 51 4.588 <.0001
   NO.4cwt 34.833 4.2500 51 8.196 <.0001
   NO.6cwt 44.000 4.2500 51 10.353 <.0001
VMarvellous 5.292 7.0789 10 0.748 0.4720
  VVictory -6.875 7.0789 10 -0.971 0.3544
Number of Observations: 72
Number of Groups:
B V %in% B
 6
        18
```

Notice that we specify multilevel random effects as a nested model in exactly the same way as a Error term in a aov model.

The approach *via* specifying a covariance structure still works: two equivalent specifications are given by

```
oatssp \leftarrow model.matrix(\sim V - 1, oats)
oats1.lme \leftarrow lme(Y \sim N + V, oats,
```

It should be clear that these are less than obvious, and we are grateful to Dr Pinheiro for elucidating the precise forms needed.

The multilevel approach allows us to handle easily the cooperative trial by

```
lme(Conc ~ 1, random = ~1 | Lab/Bat, data = coop,
    subset = Spc=="S1")
Linear mixed-effects model fit by REML
  Data: coop
  Subset: Spc == "S1"
  Log-restricted-likelihood: 21.022
  Fixed: Conc ~ 1
 (Intercept)
     0.50806
Random effects:
 Formula: ~ 1 | Lab
      (Intercept)
StdDev:
           0.24529
Formula: ~ 1 | Bat %in% Lab
       (Intercept) Residual
         0.073267 0.079355
StdDev:
Number of Observations: 36
Number of Groups:
Lab Bat %in% Lab
```

which agrees with the raov analysis.

#### Sitka spruce example

There is a problem with the analysis of this example in the text: we misunderstood the meaning of the correlation model fitted which was in fact in units of the meaurement number, not days. We first consider an analysis without serial correlation.

79.901 127.34 -27.95 Random effects: Formula: ~ 1 | tree (Intercept) Residual StdDev: 0.61011 0.16105 Fixed effects: size ~ treat \* ordered(Time) Value Std.Error DF t-value p-value (Intercept) 4.9851 0.12287 308 40.572 <.0001 treat -0.2112 0.14861 77 -1.421 0.1594 ordered(Time).L 1.1971 0.03221 308 37.166 <.0001 ordered(Time).Q -0.1341 0.03221 308 -4.162 <.0001 ordered(Time).C -0.0409 0.03221 308 -1.268 0.2056 treatordered(Time).Q -0.0264 0.03896 308 -0.679 0.4977 treatordered(Time) ^ 4 0.0124 0.03896 308 0.318 0.7504 > attach(Sitka) > Sitka\$treatslope <- Time \* (treat=="ozone")</pre> > detach() > sitka.lme2 <- update(sitka.lme, fixed = size ~ ordered(Time) + treat + treatslope) > summary(sitka.lme2) Linear mixed-effects model fit by REML Data: Sitka AIC BIC logLik 69.269 104.92 -25.635 Random effects: Formula: ~ 1 | tree (Intercept) Residual StdDev: 0.61015 0.1604 Fixed effects: size ~ ordered(Time) + treat + treatslope Value Std.Error DF t-value p-value (Intercept) 4.9851 0.12287 311 40.572 <.0001 ordered(Time).L 1.1976 0.03204 311 37.372 <.0001 ordered(Time).C -0.0506 0.01805 311 -2.804 0.0054 ordered(Time) ^ 4 -0.0167 0.01805 311 -0.926 0.3549 treat 0.2217 0.17561 77 1.262 0.2107 

Note that although the model is different, the conclusions are very similar.

Predictions and fitted values are specified somewhat differently in the later version of lme. The random effects are now specified by level, with the 'popula-

tion' values at level 0 and the BLUPs used up to the level specified (which defaults to the innermost level). Thus we can examine the fitted mean values by

The names tell us that these correspond to trees 1 and 61, but at level 0 are the same for all the trees in a treatment group.

We can specify a correlation structure by

```
lme(size ~ treat*ordered(Time), random = ~1 | tree,
   data = Sitka, corr = corCAR1(, ~Time | tree))
```

but this will not converge properly (the reported correlation coefficient is 0.2, the default starting value). If we give it a better initial value it does converge:

```
> sitka.lme <-
  lme(size ~ treat*ordered(Time), random = ~1 | tree,
      data = Sitka, corr = corCAR1(0.9, ~Time | tree))
> summary(sitka.lme)
Correlation Structure: Continuous AR(1)
Parameter estimate(s):
   Phi
0.9989
Fixed effects: size ~ treat * ordered(Time)
                      Value Std. Error DF t-value p-value
          (Intercept) 4.9851 0.12636 308 39.452 <.0001
               treat -0.2112   0.15284   77   -1.382   0.1711
      ordered(Time).L 1.1971 0.04907 308 24.396 <.0001
      ordered(Time).Q -0.1341  0.02642 308 -5.073 <.0001
      ordered(Time).C -0.0409 0.01979 308 -2.065 0.0398
    ordered(Time) ^ 4 -0.0273  0.01673 308 -1.632  0.1037
 treatordered(Time).Q -0.0264 0.03196 308 -0.827 0.4086
 treatordered(Time).C -0.0142  0.02394  308  -0.595  0.5521
treatordered(Time) ^ 4 0.0124 0.02023 308 0.613 0.5403
```

Note that the specification of the correlation structures has altered: see the help on corClasses for the current form.

The specification of a systematic component to the variances<sup>1</sup> has also altered, now using the weights argument; see the help on varClasses.

<sup>&</sup>lt;sup>1</sup> mentioned on pages 310 and 312 but not used in our examples

## 10.4 Non-linear mixed effects models

The changes needed to use nlme are similar to those for lme: specify the 'clusters' by conditioning the random effects formulae, use 1 rather than . is the formulae, and the method is specified by method, still defaulting to maximum likelihood.

For the sitka data we first fit without a correlation structure.

```
> options(contrasts = c("contr.treatment", "contr.poly"))
> sitka.nlme <- nlme(size \sim A + B * (1 - exp(-(Time-100)/C)),
    fixed = list(A ~ treat, B ~ treat, C ~ 1),
    random = A + B ~ 1 | tree, data = Sitka,
    start = list(fixed = c(2, 0, 4, 0, 100)),
    method = "ML", verbose = T)
> summary(sitka.nlme)
 Nonlinear mixed-effects model fit by maximum likelihood
  Model: size \sim A + B * (1 - exp( - (Time - 100)/C))
 Data: Sitka
      AIC BIC logLik
  -96.275 -60.465 57.138
Random effects:
 Formula: list(A ~ 1, B ~ 1)
 Level: tree
 Structure: General positive-definite
              StdDev Corr
A. (Intercept) 0.83561 A. (Int
B.(Intercept) 0.81954 -0.69
     Residual 0.10297
Fixed effects: list(A ~ treat, B ~ treat, C ~ 1)
              Value Std.Error DF t-value p-value
A.(Intercept) 2.304 0.1995 312 11.547 <.0001
      A.treat 0.175 0.2117 312 0.826 0.4096
B.(Intercept) 3.921 0.1808 312 21.687 <.0001
      B.treat -0.564 0.2156 312 -2.618 0.0093
           C 81.769 4.7270 312 17.299 <.0001
> sitka.nlme2 <- update(sitka.nlme,
     fixed = list(A \sim 1, B \sim 1, C \sim 1),
     start = list(fixed=c(2.3, 3.9, 79)))
> summary(sitka.nlme2)
 Nonlinear mixed-effects model fit by maximum likelihood
  Model: size \sim A + B * (1 - exp( - (Time - 100)/C))
 Data: Sitka
      AIC
             BIC logLik
  -91.588 -63.736 52.794
    . . . .
```

```
Fixed effects: list(A \sim 1, B \sim 1, C \sim 1)
    Value Std.Error DF t-value p-value
 A 2.421 0.1312 314 18.462 <.0001
 B 3.536 0.1079 314 32.775 <.0001
 C 81.658 4.6906 314 17.409 <.0001
 > anova(sitka.nlme2, sitka.nlme)
            Model df AIC BIC logLik Test Lik.Ratio
 sitka.nlme 2 9 -96.275 -60.465 57.138 1 vs. 2 8.6869
           p-value
 sitka.nlme2
  sitka.nlme 0.013
We can now allow a correlation, and do get sensible results:
 > sitka.nlme3 <- update(sitka.nlme,
                       corr = corCAR1(0.9, ~Time | tree))
 > summary(sitka.nlme3)
  Nonlinear mixed-effects model fit by maximum likelihood
   Model: size \sim A + B * (1 - exp( - (Time - 100)/C))
  Data: Sitka
     AIC BIC logLik
   -104.5 -64.715 62.252
 Random effects:
  Formula: list(A ~ 1, B ~ 1)
```

```
Level: tree
Structure: General positive-definite
               StdDev Corr
A.(Intercept) 0.81602 A.(Int
B.(Intercept) 0.76069 -0.674
     Residual 0.13068
Correlation Structure: Continuous AR(1)
Parameter estimate(s):
    Phi
 0.96751
Fixed effects: list(A ~ treat, B ~ treat, C ~ 1)
              Value Std.Error DF t-value p-value
A.(Intercept) 2.313 0.2052 312 11.271 <.0001
      A.treat 0.171 0.2144 312 0.796 0.4267
B.(Intercept) 3.892 0.1813 312 21.466 <.0001
      B.treat -0.564 0.2162 312 -2.607 0.0096
C 80.901 5.2920 312 15.288 <.0001
```

This does correspond to a correlation of  $0.96751^{26.5} \approx 0.4$  at the average spacing between observations.

## Blood pressure in rabbits

There have been considerable changes in self-starting nls models which are also incorporated in the nlme library. We make use of the supplied self-starting model SSfpl.

```
> R.nlsList <- nlsList(
    BPchange ~ SSfpl(log(Dose), A, B, ld50, scal) | Run,
    data = Rabbit)
> M1 <- coef(R.nlsList)
> M1
                  ld50
        Α
              В
                          scal
C1 1.8095 34.787 3.5610 0.30918
C2 1.4840 29.683 4.0382 0.27792
C3 1.5994 23.759 3.8581 0.26935
C4 1.4077 34.198 3.8426 0.30502
C5 1.4146 19.023 3.5374 0.22890
M1 1.1295 41.817 4.4688 0.41052
M2 1.3676 28.612 4.6049 0.18381
      NA
             NA
                    NA
M4 1.9063 24.148 4.7032 0.26616
            NA
M5
      NΑ
                  NΑ
> fixed.effects(R.nlsList)
        B 1d50 scal
 1.5148 29.504 4.0768 0.28136
```

This is essentially as before, but the roles of A and B are reversed. The rest of the preliminary analysis is unchanged.

```
> R.nls <- nls(BPchange ~ A[Run] + (B - A[Run])/
     (1 + exp((log(Dose) - ld50[Run])/scal)), data = Rabbit,
     start = list(A=rep(29.5, 10), B=1.5, ld50=rep(4.1, 10),
                  scal=0.28))
> b <- as.vector(coef(R.nls))</pre>
> M2 <- cbind(b[1:10], b[11], b[12:21], b[22])
> dimnames(M2) <- dimnames(M1)</pre>
> M2
               В
                   1d50
        Α
                            scal
C1 34.351 1.6515 3.5481 0.27383
C2 29.646 1.6515 4.0417 0.27383
C3 23.804 1.6515 3.8613 0.27383
C4 33.876 1.6515 3.8468 0.27383
C5 19.335 1.6515 3.5630 0.27383
M1 37.592 1.6515 4.3883 0.27383
M2 30.682 1.6515 4.6632 0.27383
M3 27.672 1.6515 4.2249 0.27383
M4 24.276 1.6515 4.6994 0.27383
M5 21.402 1.6515 4.7547 0.27383
```

Using this as an initial object for nlme fails, as the fitting process fails.

We can fit nlme models to the separate treatment groups by

```
Fpl \leftarrow deriv(\sim A + (B-A)/(1 + exp((log(d) - ld50)/th)),
    c("A", "B", "ld50", "th"), function(d, A, B, ld50, th) {})
c1 <- fixed.effects(R.nlsList); c1[2:1] <- c1[1:2]</pre>
Rc.nlme <- nlme(BPchange ~ Fpl(Dose, A, B, 1d50, th),
     fixed = list(A \sim 1, B \sim 1, ld50 \sim 1, th \sim 1),
     random = A + 1d50 ~ 1 | Animal, data = Rabbit,
     subset = Treatment=="Control".
     start = list(fixed=c1))
Rm.nlme <- update(Rc.nlme, subset = Treatment=="MDL")</pre>
Nonlinear mixed-effects model fit by maximum likelihood
  Model: BPchange ~ Fpl(Dose, A, B, 1d50, th)
  Data: Rabbit
  Subset: Treatment == "Control"
 Log-likelihood: -66.502
 Fixed: list(A \sim 1, B \sim 1, ld50 \sim 1, th \sim 1)
             B 1d50
                           th
 28.332 1.5134 3.7744 0.28957
Random effects:
Formula: list(A ~ 1, ld50 ~ 1)
Level: Animal
 Structure: General positive-definite
          StdDev Corr
       A 5.76889 A
    ld50 0.17953 0.112
Residual 1.36735
> Rm.nlme
Nonlinear mixed-effects model fit by maximum likelihood
  Model: BPchange ~ Fpl(Dose, A, B, 1d50, th)
  Data: Rabbit
  Subset: Treatment == "MDL"
 Log-likelihood: -65.422
 Fixed: list(A \sim 1, B \sim 1, ld50 \sim 1, th \sim 1)
      A B 1d50
 27.521 1.7839 4.5257 0.24236
Random effects:
Formula: list(A \sim 1, ld50 \sim 1)
Level: Animal
Structure: General positive-definite
          StdDev Corr
       A 5.36549 A
    ld50 0.18999 -0.594
Residual 1.44172
```

We can now combine the groups. As we have a means to handle multilevel random effects, we will make use of them.

```
> options(contrasts=c("contr.treatment", "contr.poly"))
> c1 <- c(28, 1.6, 4.1, 0.27, 0)
> R.nlme1 <- nlme(BPchange ~ Fpl(Dose, A, B, ld50, th),
      fixed = list(A ~ Treatment, B ~ Treatment,
                 ld50 ~ Treatment, th ~ Treatment),
    random = A + 1d50 ~ 1 | Animal/Run, data = Rabbit,
     start = list(fixed=c1[c(1,5,2,5,3,5,4,5)]))
> summary(R.nlme1)
Nonlinear mixed-effects model fit by maximum likelihood
 Model: BPchange ~ Fpl(Dose, A, B, 1d50, th)
 Data: Rabbit
    AIC
           BIC logLik
 292.63 324.04 -131.31
Random effects:
Formula: list(A \sim 1, ld50 \sim 1)
Level: Animal
Structure: General positive-definite
                StdDev
                         Corr
   A.(Intercept) 4.6063 A.(Int
ld50.(Intercept) 0.0626 -0.166
Formula: list(A \sim 1, ld50 \sim 1)
Level: Run %in% Animal
Structure: General positive-definite
                StdDev Corr
   A.(Intercept) 3.2489 A.(Int
ld50.(Intercept) 0.1707 -0.348
       Residual 1.4113
Fixed effects: list(A ~ Treatment, B ~ Treatment,
                   ld50 ~ Treatment, th ~ Treatment)
                  Value Std. Error DF t-value p-value
   A.(Intercept) 28.326 2.7802 43 10.188 <.0001
    A.Treatment -0.727 2.5184 43 -0.288 0.7744
   B.(Intercept) 1.525 0.5155 43 2.958 0.0050
     B.Treatment 0.261 0.6460 43
                                     0.405 0.6877
ld50.(Intercept) 3.778 0.0955 43 39.579 <.0001
  ld50.Treatment 0.747 0.1286 43 5.809 <.0001
  th.(Intercept) 0.290 0.0323 43
                                     8.957 <.0001
   th.Treatment -0.047 0.0459 43 -1.020 0.3135
> R.nlme2 <- update(R.nlme1,
      fixed = list(A \sim 1, B \sim 1, ld50 \sim Treatment, th \sim 1),
      start = list(fixed=c1[c(1:3,5,4)]))
> anova(R.nlme2, R.nlme1)
        Model df
                  AIC
                           BIC logLik
                                          Test Lik.Ratio
R.nlme2
          1 12 287.29 312.43 -131.65
           2 15 292.63 324.04 -131.31 1 vs. 2 0.66905
R.nlme1
> summary(R.nlme2)
```

```
Random effects:
Formula: list(A \sim 1, ld50 \sim 1)
Level: Animal
 Structure: General positive-definite
                   StdDev
                           Corr
               A 4.668022 A
ld50.(Intercept) 0.072652 -0.116
Formula: list(A \sim 1, ld50 \sim 1)
Level: Run %in% Animal
 Structure: General positive-definite
                 StdDev
                          Corr
               A 3.15072 A
ld50.(Intercept) 0.17128 -0.376
       Residual 1.42791
Fixed effects: list(A \sim 1, B \sim 1, ld50 \sim Treatment, th \sim 1)
                 Value Std. Error DF t-value p-value
               A 28.170 2.4909 46 11.309 <.0001
               B 1.667 0.3069 46 5.433 <.0001
ld50.(Intercept) 3.779 0.0921 46 41.036 <.0001
 ld50.Treatment 0.759 0.1217 46 6.233 <.0001
             th 0.271 0.0226 46 11.964 <.0001
```

The results differ in detail, but the conclusions are the same. Finally, we can plot by

### 10.5 Using 1me with autocorrelated data

We also used lme in Section 15.6 to fit regressions with autocorrelated data. This is most easily done by the new function gls in the nlme library.

Here REML is the default method, as for lme.

### Chapter 11

## Modern Regression

### 11.1 Additive models and scatterplot smoothers

### Scatterplot smoothing

Simonoff (1996) provides an excellent overview of methods for smoothing whereas Bowman & Azzalini (1997) concentrate on providing an introduction to the kernel approach, with an easy-to-use S-PLUS library sm<sup>1</sup>. They concentrate on using a local linear smoother implemented in their function sm.regression, which can produce smooth functions of one or two covariates.

The methods expounded by Wand & Jones (1995) are implemented in Wand's library KernSmooth<sup>2</sup>. We can apply their local polynomial smoother to the simulated motorcycle example by

This applies first a local linear and then a local quadratic fit. The bandwidth is chosen by the method of Ruppert *et al.* (1995).

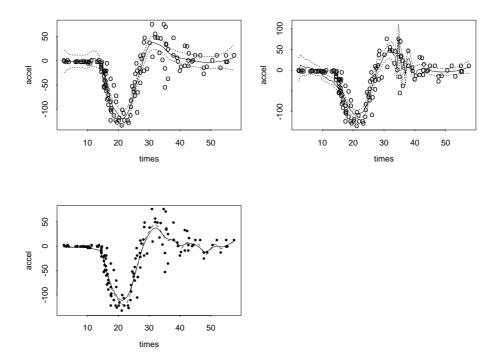
The package locfit (Loader, 1997) also uses local polynomial fitting, of one or more covariates. The documentation with the package is sparse: the Web site <a href="http://cm.bell-labs.com/stat/project/locfit">http://cm.bell-labs.com/stat/project/locfit</a> has the sources<sup>3</sup> and a number of on-line documents, including some analyses of the mcycle dataset. A simple analysis is

```
library(locfit, first=T)
fit <- locfit(accel ~ times, alpha = 0.3, data=mcycle)
plot(fit, se.fit=T, get.data=T)</pre>
```

<sup>&</sup>lt;sup>1</sup> available from http://www.stats.gla.ac.uk/~adrian/sm and http://www.stat.unipd.it/dip/homes/azzalini/SW/Splus/sm.

<sup>2</sup> ksmooth on Windows. The current Unix sources are at http://www.biostat.harvard.edu/~mwand

<sup>&</sup>lt;sup>3</sup> for Unix; our port to Windows is later and more complete than that there.



**Figure 11.11**: Smooths by local polynomial fits of the mcycle data. The bottom is by locpoly, with a local linear (solid line) and local quadratic (dashed line) model. The top row are by locfit with an assumed constant variance (left) and estimated variance (right). The dashed lines are  $\pm$  a standard error.

where the value of  $\alpha$  was chosen by trial-and-error. We could use local AIC to set the bandwidth, but as Figure 11.1 or 11.11 show, an assumption of constant noise variance is not tenable. So we need a smooth estimate of the noise variance. A simple idea is to under-smooth slightly, fit a smooth curve to the squared residuals and use this for a variance estimate. However, this proves to be far too low at the beginning, so we increase it somewhat to avoid choosing the bandwidth to fit the first few observations.

The degree of smoothness chosen is rather sensitive to the precise variance estimate used.

### Fitting additive models

Other ways to fit additive models in S-PLUS are available from the contributions of users. These are generally more ambitious than gam and step.gam in their

choice of terms and the degree of smoothness of each term, and by relying heavily on compiled code can be very substantially faster. All of these methods can fit to multiple responses (by using the total sum of squares as the fit criterion).

Library mda of Hastie and Tibshirani provides functions bruto and mars. The method BRUTO is described in Hastie & Tibshirani (1990); it fits additive models with smooth functions selected by smoothing splines and will choose between a smooth function, a linear term or omitting the variable altogether. The function mars implements the MARS method of Friedman (1991) briefly mentioned on page 341 of the book. By default this is an additive method, fitting splines of order 1 (piecewise linear functions) to each variable; again the number of pieces is selected by the program so that variables can be entered linearly, non-linearly or not at all.

The library polymars of Kooperberg and O'Connor implements a restricted form of MARS (for example, allowing only pairwise interactions) suggested by Kooperberg *et al.* (1997).

### An example: the cpus data

As a running example for various types of non-linear regression we consider the data frame cpus (Ein-Dor & Feldmesser, 1987) which contains computer performance data on mainframe cpus described on page 419 of the book. We randomly select 100 examples for fitting the models and test the performance on the remaining 109 examples. (This is related to but not identical to the experiments in Ripley, 1994a.) We use a linear model as a benchmark.

```
set.seed(123)
cpus0 <- cpus[, 2:8] # excludes names, authors' predictions</pre>
for(i in 1:3) cpus0[,i] <- log10(cpus0[,i])</pre>
samp <- sample(1:209, 100)</pre>
cpus.lm <- lm(log10(perf) ~ ., data=cpus0[samp,])</pre>
test <- function(fit)</pre>
  sqrt(sum((log10(cpus0[-samp, "perf"]) -
            predict(fit, cpus0[-samp,]))^2)/109)
test(cpus.lm)
[1] 0.21295
cpus.lm2 <- step(cpus.lm, trace=F)</pre>
cpus.lm2$anova
Initial Model:
log10(perf) ~ syct + mmin + mmax + cach + chmin + chmax
Final Model:
log10(perf) ~ mmin + mmax + cach + chmin + chmax
    Step Df Deviance Resid. Df Resid. Dev AIC
                            93 3.2108 3.6942
2 - syct 1 0.013177 94
                                  3.2240 3.6383
```

```
test(cpus.lm2)
[1] 0.21271
```

Now we consider BRUTO and MARS models. These need matrices (rather than formulae and data frames) as inputs.

```
Xin <- as.matrix(cpus0[samp,1:6])</pre>
library(mda)
test2 <- function(fit) {</pre>
  Xp <- as.matrix(cpus0[-samp,1:6])</pre>
  sqrt(sum((log10(cpus0[-samp, "perf"]) -
            predict(fit, Xp))^2)/109)
cpus.bruto <- bruto(Xin, log10(cpus0[samp,7]))</pre>
test2(cpus.bruto)
[1] 0.21336
cpus.bruto$type
[1] excluded smooth linear smooth
                                           smooth
                                                   linear
cpus.bruto$df
 syct
        mmin mmax cach chmin chmax
    0 1.5191 1 1.0578 1.1698
# examine the fitted functions
par(mfrow=c(3,2))
Xp <- matrix(sapply(cpus0[samp, 1:6], mean), 100, 6, byrow=T)</pre>
for(i in 1:6) {
  xr <- sapply(cpus0, range)</pre>
  Xp1 \leftarrow Xp; Xp1[,i] \leftarrow seq(xr[1,i], xr[2,i], len=100)
  Xf <- predict(cpus.bruto, Xp1)</pre>
  plot(Xp1[ ,i], Xf, xlab=names(cpus0)[i], ylab="", type="l")
```

The result (not shown) indicates that the non-linear terms have a very slight curvature, as might be expected from the equivalent degrees of freedom that are reported.

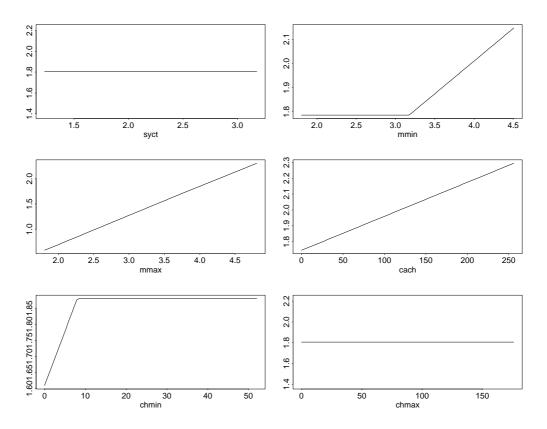
We can use mars to fit a piecewise linear model with additive terms.

```
[3,]
       0 0.0000 3.6021
                                     0
[4,]
       0 3.1761 0.0000
                          0
                               0
                                     0
[5,]
       0 0.0000 0.0000
                         0
                               8
                                     0
                                     0
[6,]
       0 0.0000 0.0000
                          0
> test2(cpus.mars)
[1] 0.21366
# examine the fitted functions
Xp <- matrix(sapply(cpus0[samp, 1:6], mean), 100, 6, byrow=T)</pre>
for(i in 1:6) {
 xr <- sapply(cpus0, range)</pre>
 Xp1 \leftarrow Xp; Xp1[,i] \leftarrow seq(xr[1,i], xr[2,i], len=100)
 Xf <- predict(cpus.mars, Xp1)</pre>
 plot(Xp1[ ,i], Xf, xlab=names(cpus0)[i], ylab="", type="l")
> cpus.mars2 <- mars(Xin, log10(cpus0[samp,7]), degree=2)</pre>
> showcuts(cpus.mars2)
    syct mmin mmax cach chmin chmax
[1,] 0 0.0000 0.0000 0
                               Ω
                                     Λ
       0 0.0000 3.6021 0
                               0
                                     0
[2,]
[3,] 0 1.9823 3.6021 0
                               0
                                     0
[4,] 0 0.0000 0.0000 16
                               8
                                     0
     0 0.0000 0.0000 0
                               0
                                     0
[5.]
> test2(cpus.mars2)
[1] 0.21495
> cpus.mars6 <- mars(Xin, log10(cpus0[samp,7]), degree=6)</pre>
> showcuts(cpus.mars6)
                    mmax cach chmin chmax
      syct mmin
[1,] 0.0000 0.0000 0.0000 0 0
[2,] 0.0000 1.9823 3.6021
                                 0
                                       0
                          0
                                8
[3,] 0.0000 0.0000 0.0000 16
                                       0
[4,] 0.0000 0.0000 0.0000 16
                                8
[5,] 0.0000 0.0000 3.6990 0
                                8
                                       0
                                 8
[6,] 2.3979 0.0000 0.0000 16
                                       0
[7,] 2.3979 0.0000 3.6990 16
                                8
                           0
[8,] 0.0000 0.0000 0.0000
                                 0
                                       0
> test2(cpus.mars6)
[1] 0.20604
```

Allowing pairwise interaction terms (by degree=2) or allowing arbitrary interactions make little difference to the effectiveness of the predictions.

We can use these results to indicate a possible scope for step.gam. This was not covered in the main text, as we have found it to be too slow for routine use. It fits a series of gam models, at each stage selecting one term from a list. Here we allow each variable to be dropped, entered linearly or taken as a smooth term with 2 or 4 (equivalent) degrees of freedom.

```
cpus.gam <- gam(log10(perf) ~ ., data=cpus0[samp, ])
cpus.gam2 <- step.gam(cpus.gam, scope=list(
   "syct" = ~ 1 + syct + s(syct, 2) + s(syct),
   "mmin" = ~ 1 + mmin + s(mmin, 2) + s(mmin),</pre>
```



**Figure 11.12**: Plots of the additive functions used by cpus.mars.

```
"mmax" = \sim 1 + mmax + s(mmax, 2) + s(mmax),
  "cach" = \sim 1 + cach + s(cach, 2) + s(cach),
  "chmin" = \sim 1 + chmin + s(chmin, 2) + s(chmin),
  "chmax" = \sim 1 + \text{chmax} + \text{s(chmax, 2)} + \text{s(chmax)}
> print(cpus.gam2$anova, digits=3)
Initial Model:
log10(perf) ~ syct + mmin + mmax + cach + chmin + chmax
Final Model:
log10(perf) \sim s(mmin, 2) + mmax + s(cach, 2) + s(chmax, 2)
Scale: 0.034525
                  To Df Deviance Resid. Df Resid. Dev AIC
   From
1
                                         93
                                                   3.21 3.69
2 mmin s(mmin, 2) -1
                          -0.160
                                         92
                                                   3.05 3.60
3 syct
                           0.019
                                         93
                                                   3.07 3.55
                      1
   cach s(cach, 2) -1
                          -0.115
                                         92
                                                   2.95 3.51
5 chmax s(chmax, 2) -1
                          -0.095
                                                   2.86 3.48
                                         91
6 chmin
                      1
                           0.055
                                         92
                                                   2.91 3.47
> test(cpus.gam2)
[1] 0.20377
```

This gives a result similar to that of BRUTO. We could include pairwise interaction terms using 10, but this will not allow any extrapolation and so prediction of our test set will fail.

For comparison, the regression tree procedure of Chapter 14 will give

```
cpus.ltr <- tree(log10(perf) ~ ., data=cpus0[samp,])
plot(cv.tree(cpus.ltr,, prune.tree))
cpus.ltr1 <- prune.tree(cpus.ltr, best=10)
test(cpus.ltr1)
[1] 0.24126</pre>
```

Other methods are considered later in this chapter.

#### Local likelihood models

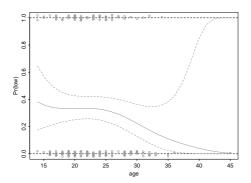
Local likelihood provides a different way to extend models such as GLMs to use smooth functions of the covariates. In the local likelihood approach the prediction at x is made by fitting a fully parametric model to the observations in a neighbourhood of x. More formally, a weighted likelihood is used, where the weight for observation i is a decreasing function of the 'distance' of  $x_i$  from x. (We have already seen this approach for density estimation.) Note that in this approach we are compelled to have predictions which are a smooth function of all the covariates jointly and so it is only suitable for a small number of covariates, usually not more than two. In principle the computational load will be daunting, but this is reduced (as in loess) by evaluating the prediction at a judiciously chosen set of points and interpolating.

The library sm of Bowman & Azzalini (1997) implements this approach for a single covariate in functions sm.logit (a Binomial log-linear model) and sm.poisson (a Poisson log-linear model). For example, we can consider the effect of the mother's age on the probability of a low birthweight in the dataset birthwt by

```
library(sm)
attach(birthwt)
sm.logit(age, low, h=5, display="se")
detach()
```

Here the bandwidth h is the standard deviation of the Gaussian kernel used.

Library locfit provides a function locfit with much greater flexibility. It can fit Gaussian, binomial, Poisson, gamma and negative binomial GLMs with identity, log, logit, inverse and square root links and one or more (in practice, two or three) covariates, and choose the bandwidth based on the  $k=\alpha n$  nearest neighbours or fixed or chosen by a local AIC criterion (as we saw for a Poisson model on page 7). We can try this for the joint response to age and lwt in birthwt.



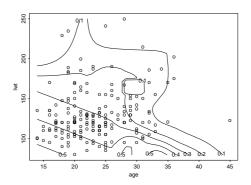


Figure 11.13: Probability of low birthweight in dataset birthwt. Left: Against mother's age, by sm.logit, with pointwise confidence intervals shown by dashed lines. Right: Against mother's age and last weight, by locfit.

Note that the use of scale=0 is essential as in density estimation. We chose a local linear fit as the data are few and quadratic fitting (the default) has little theoretical advantage over linear fitting.

As a second example, consider the dataset Pima.tr of diabetes on 200 Pima Indians. Previous studies (Wahba *et al.*, 1995; Ripley, 1996) have suggested that the two continuous variables glu (plasma glucose level) and bmi (body mass index) have the most discriminatory effect. We consider a local logistic regression on these two variables

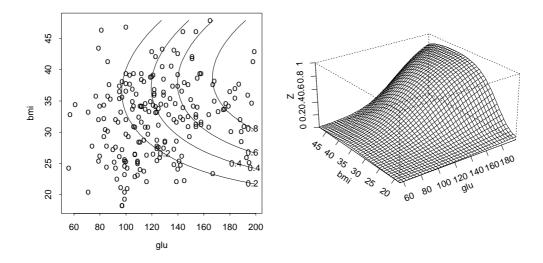
shown in Figure 11.14.

### 11.2 Projection-pursuit regression

An alternative way to fit projection pursuit regression models is to use BDR's library ppr <sup>4</sup> which is (like ppreg) based on the SMART program described in Friedman (1984). This provides a formula-based interface and the ability to use smoothing splines (based on the code for smooth.spline) for the smoothing of the ridge functions.

We can demonstrate this on the rock example.

 $<sup>^4</sup>$  Available from www.stats.ox.ac.uk in directory /pub/S (Unix) and /pub/SWin (Windows).



**Figure 11.14**: Plots of the probability surface fitted to the Pima.tr dataset by locfit using a local logistic regression.

This essentially reproduces the fit on page 332 of the book (on a different OS; both ppreg and ppr are very sensitive to the order and precision of calculations). The summary method gives a little more information.

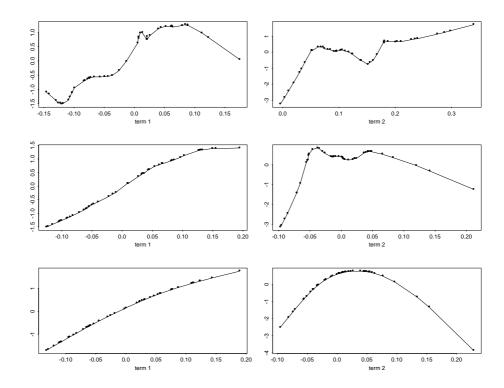


Figure 11.15: Plots of the ridge functions for three 2-term projection pursuit regressions fitted to the rock dataset. The top two fits used supsmu, whereas the bottom fit used smoothing splines.

```
peri -0.945544 -0.866757
shape 0.062226 0.242839

Coefficients of ridge terms:
   term 1 term 2
1.00638 0.72915
```

The added information is the direction vectors  $\alpha_k$  and the coefficients  $\beta_{ij}$  in

$$Y_i = \alpha_{i0} + \sum_{j=1}^{M} \beta_{ij} f_j(\boldsymbol{\alpha}_j^T \boldsymbol{X}) + \epsilon$$
 (11.10)

Note that this is the extension of (11.5) to multiple responses, and so we separate the scalings from the smooth functions  $f_j$  (which are scaled to have zero mean and unit variance over the projections of the dataset).

We can examine the fitted functions  $f_j$  by

```
par(mfrow=c(3,2))
plot(rock.ppr)
plot(update(rock.ppr, bass=5))
plot(update(rock.ppr, sm.method="gcv", gcvpen=2))
```

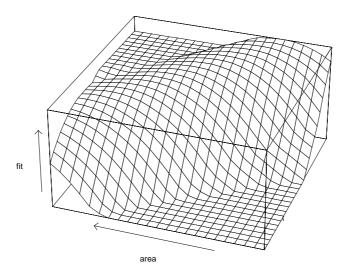
We first increase the amount of smoothing in the 'super smoother' supsmu to fit a smoother function, and then change to using a smoothing spline with smoothness chosen by GCV (generalized cross-validation) with an increased complexity penalty. We can then examine the details of this fit by

```
rock.ppr2 <- update(rock.ppr, sm.method="gcv", gcvpen=2)</pre>
summary(rock.ppr2)
Goodness of fit:
 2 terms 3 terms 4 terms 5 terms
21.335 21.669 21.615 0.000
Projection direction vectors:
       term 1 term 2
area 0.31407 0.42179
peri -0.94203 -0.86766
shape 0.11803 -0.26317
Coefficients of ridge terms:
 term 1 term 2
0.87673 0.21402
Equivalent df for ridge terms:
term 1 term 2
     2 3.06
```

This fit is substantially slower since the effort put into choosing the amount of smoothing is much greater. Note that here only two effective terms could be found, and that area and peri dominate. We can arrange to view the surface for a typical value of shape.

#### An example: the cpus data

We can also consider the cpus test problem. Our experience suggests that smoothing the terms rather more that the default for supsmu is a good idea.



**Figure 11.16**: A two-dimensional fitted section of a projection pursuit regression surface fitted to the rock data. Compare this with Figure 11.5. Note that the prediction extends the ridge functions as constant beyond the fitted functions, hence the planar regions shown. For display on paper we set drape=F.

```
Goodness of fit:
 2 terms 3 terms 4 terms 5 terms 6 terms 7 terms 8 terms
2.70334 2.37041 1.96751 1.56136 1.45629 1.06552 0.87165
9 terms 10 terms
0.81152 0.73181
cpus.ppr <- ppr(log10(perf) ~ ., data=cpus0[samp,],</pre>
                nterms=7, max.terms=10, bass=5)
test(cpus.ppr)
[1] 0.18809
> ppr(log10(perf) ~ ., data=cpus0[samp,],
      nterms=2, max.terms=10, sm.method="spline")
Goodness of fit:
 2 terms 3 terms 4 terms 5 terms 6 terms 7 terms 8 terms
2.6218 2.2941 2.2842 1.8223 1.7465 1.4952 1.3857
9 terms 10 terms
1.3276 1.2924
> cpus.ppr2 <- ppr(log10(perf) ~ ., data=cpus0[samp,],</pre>
    nterms=5, max.terms=10, sm.method="spline")
> test(cpus.ppr2)
[1] 0.19201
> cpus.ppr3 <- ppr(log10(perf) ~ ., data=cpus0[samp,],</pre>
    nterms=3, max.terms=10, sm.method="spline")
> test(cpus.ppr3)
[1] 0.20901
```

In these experiments projection pursuit regression outperformed all the additive models, but not by much. A different S-PLUS platform gave similar results but a different ranking of the smoothing methods.

Are these results actually better than those for the linear model? We can test whether the prediction errors are smaller on the test set by a paired statistical test: as it is moot whether to use the absolute error or squared error, and neither is close to normally distributed, we use a rank test.

Remember there is a selection effect here: we have tested one of the best fits we found. Much larger reductions in the prediction variance are needed for statistical (or practical) significance.

#### 11.4 Neural networks

In this complement we provide more details of the functions in the current version of library nnet. This has both enhanced functionality and improvements in the output.

### Using formulae with nnet

Since the book was written we have made nnet into a generic function, with a default method nnet.default that reproduces the previous behaviour. There is a new logical argument Hess that adds a call to nnet.Hess from within the call to nnet, with the Hessian contained in the Hessian component of the returned object.

The method nnet.formula provides an additional way to specify the network that may combine more easily with other model-based procedures. The interface is similar to that of the multinom function (which fits multiple logistic regressions via a call to nnet.default), but has less specialized print and summary methods. The formula should be of the form

```
type ~ var1 + var2 + ...
```

where interactions are allowed on the right-hand side but will not normally be useful. The response variable is normally a factor, but it could also be a vector or matrix. (Vector and matrices are passed unchanged to nnet.default.) Response factors are treated in one of two ways, after having any unused levels removed. If the reduced factor has just two levels, nnet.default is called with y as the

indicator function of the second level, and with entropy=T. If there are more than two levels, y is set to the indicator matrix of the factor (in which each row is zero except in the column for the level which occurred) and softmax is used. These are sensible defaults when (as is usual) the neural network is being used a non-linear logistic discriminant.

We can use a formula to simplify slightly the specification of the example on page 340 of the book.

Neural nets specified by a formula will most often be used for prediction. If the response is a factor, the default return value from predict.nnet is the predicted probabilities for each class (or of one of the classes if there are only two). However, the option type="class" returns the class with the highest predicted probability.

This form makes it easier to view the fitted surface for the rock dataset. We can use essentially the same code as we used for the fits by ppr.

### Multiple logistic regression and discrimination

The function multinom is a wrapper function that uses nnet.default to fit a multiple logistic regression. There was once a separate library multinom, but this has been merged with library nnet in the libraries for the second edition.

There are close similarities between nnet.formula and multinom, but multinom adds the class multinom to the object it returns and has specialized methods for the generic functions print, summary, predict, coef, vcov, add1, drop1 and extractAIC<sup>5</sup>.

The model is specified by a formula. The response can be either a matrix giving the number of occurrences of each class at that particular x value, or (more commonly) a factor giving the observed class. The right-hand side specifies the design matrix in the usual way. If the response Y is a factor with just two levels, the model fitted is

$$\operatorname{logit} p(Y = 1 \mid X = \boldsymbol{x}) = \boldsymbol{\beta}^T \boldsymbol{x}$$

 $<sup>^{5}</sup>$  the method-dependent part of stepAIC.

This is a logistic regression, and is fitted as a neural network with skip-layer connections and no units in the hidden layer. There is a potential problem in that both the bias unit and an intercept in x may provide an intercept term: this is avoided by constraining the bias coefficient to be zero. The entropy measure of fit is used; this is equivalent to maximizing the likelihood.

For a factor response with more that two levels or a matrix response the model fitted is

$$\log \frac{p(Y = c \mid X = \boldsymbol{x})}{p(Y = 1 \mid X = \boldsymbol{x})} = \boldsymbol{\beta}_c^T \boldsymbol{x}$$

where  $\beta_1 \equiv 0$ . Once again the parameters are chosen by maximum likelihood. (This is achieved by using the softmax option of nnet.default.)

Approximate standard errors of the coefficients are found for vcov.multinom and summary.multinom by inverting the Hessian of the (negative) log-likelihood at the maximum likelihood estimator.

It is possible to add weight decay by setting a non-zero value for decay on the call to multinom. Beware that because the coefficients for class one are constrained to be zero, this has a rather asymmetric effect (unlike nnet.formula) and that the quoted standard errors are no longer appropriate. Using weight decay has an effect closely analogous to ridge regression, and will often produce better predictions than using stepwise selection of the variables.

In all these problems the measure of fit is convex, so there is a unique global minimum. This is attained at a single point unless there is collinearity in the explanatory variables or the minimum occurs at infinity (which can occur if the classes are partially or completely linearly separable).

#### Internal details of nnet.default

The C code on which nnet.default is based is quite general and can in fact be used for networks with an arbitrary pattern of feed-forward connections. Internally the nodes are numbered so that all connections are from lower to higher numbers; the bias unit has number 0, the inputs numbers 1 to m, say, and the output units are the highest-numbered units. The code in summary.nnet shows how to 'unpack' the connections. These are stored in vectors, so the weights are stored in a single vector. The connections are sorted by their *destination* so that all connections to unit i precede those to unit i+1. The vector conn gives the source unit, and nconn is an index vector for the first connection to that destination. An example will make this clearer:

```
> rock.nn$nconn
[1] 0 0 0 0 0 4 8 12 19
> rock.nn$conn
[1] 0 1 2 3 0 1 2 3 0 1 2 3 0 4 5 6 1 2 3
> summary(rock.nn)
a 3-3-1 network with 19 weights
options were - skip-layer connections linear output units
decay=0.001
```

```
b->h1 i1->h1 i2->h1 i3->h1
4.47 -11.16 15.31 -8.78
b->h2 i1->h2 i2->h2 i3->h2
9.15 -14.68 18.45 -22.93
b->h3 i1->h3 i2->h3 i3->h3
1.22 -9.80 7.10 -3.77
b->o h1->o h2->o h3->o i1->o i2->o i3->o
8.78 -16.06 8.63 9.66 -1.99 -4.15 1.65
```

Unit 0 is the bias ("b"), units 1 to 3 are the inputs, 4 to 6 the hidden units and 7 the output. The vectors conn and nconn follow the C indexing convention, starting with zero. Thus unit h1 (4) has connections from units 0, 1, 2 and 3. The vector nconn has a final element giving the total number of connections.

These connection vectors are normally constructed by the function add.net; this automatically adds a connection to a bias unit whenever a unit gets its first incoming connection.

### An example: the cpus data

To use the nnet software effectively it is essential to scale the problem. A preliminary run with a linear model demonstrates that we get essentially the same results as the conventional approach to linear models.

We now consider adding non-linear terms to the model.

```
final value 2.339850
test(cpus.nn4)
[1] 0.23
```

This demonstrates that the degree of fit is almost completely controlled by the amount of weight decay rather than the number of hidden units (provided there are sufficient). We have to be able to choose the amount of weight decay *without* looking at the test set. To do so we borrow the ideas of Chapter 17, by using cross-validation and by averaging across multiple fits.

```
CVnn.cpus <- function(formula, data=cpus1[samp, ],
     size = c(0, 4, 4, 10, 10),
     lambda = c(0, rep(c(0.003, 0.01), 2)),
     nreps = 5, nifold = 10, ...)
  CVnn1 <- function(formula, data, nreps=1, ri, ...)
    truth <- log10(data$perf)</pre>
    res <- numeric(length(truth))</pre>
    cat(" fold")
    for (i in sort(unique(ri))) {
      cat(" ", i, sep="")
      for(rep in 1:nreps) {
        learn <- nnet(formula, data[ri !=i,], trace=F, ...)</pre>
        res[ri == i] <- res[ri == i] +
                        predict(learn, data[ri == i,])
      }
    }
    cat("\n")
    sum((truth - res/nreps)^2)
  }
  choice <- numeric(length(lambda))</pre>
  ri <- sample(nifold, nrow(data), replace=T)</pre>
  for(j in seq(along=lambda)) {
    cat(" size =", size[j], "decay =", lambda[j], "\n")
    choice[j] <- CVnn1(formula, data, nreps=nreps, ri=ri,</pre>
                        size=size[j], decay=lambda[j], ...)
  cbind(size=size, decay=lambda, fit=sqrt(choice/100))
CVnn.cpus(log10(perf) ~ ., data=cpus1[samp,],
          linout=T, skip=T, maxit=1000)
    size decay
                    fit
[1,] 0 0.000 0.19746
[2,] 4 0.003 0.23297
[3,] 4 0.010 0.20404
[4,] 10 0.003 0.22803
[5,] 10 0.010 0.20130
```

54

This took around 6 Mb and 15 minutes on the PC. The cross-validated results seem rather insensitive to the choice of model. We show how to use one of the non-linear models, even though non-linearity does not seem justified.

## Chapter 12

# Survival Analysis

#### 12.1 Estimators of survival curves

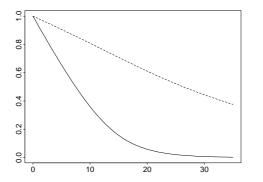
In the text we concentrated on wholly non-parametric estimators of the survivor function S and cumulative hazard H; the resulting estimators were not smooth, indeed discontinuous. There are analogues of density estimation for survival data in which we seek smooth estimates of the survival function S, the density f or (especially) the hazard function h. There seem no current S-PLUS implementations of the kernel-based approaches (Wand & Jones, 1995, §6.2.3, 6.3).

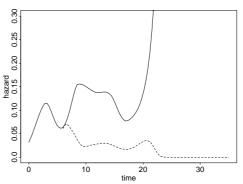
### Likelihood-based approaches

Censoring is easy to incorporate in maximum-likelihood estimation; the likelihood is given by (12.1) on page 344. One approach to using a smooth estimator is to fit a very flexible parametric family and show the density/hazard/survivor function evaluated at the maximum likelihood estimate. This is the approach of the logspline library that we considered in Chapter 5 of these complements. Consider the gehan dataset.

As there is no function for plotting lines, we have to add the second group by hand. Small changes allow us to plot the density or hazard function.

Once again there is a local likelihood approach (see, for example Hjort, 1997) to hazard estimation, in which the terms are weighted by their proximity to t.





**Figure 12.1**: Smooth survival (left, by logspline.fit) and hazard (right, by locfit) fits to the gehan dataset. The solid line indicates the control group, the dashed line that receiving 6-MP.

The full log-likelihood is

$$\sum_{t : \delta : -1} \log h(t_i) - \sum_{i} \int_{0}^{t_i} h(u) \, \mathrm{d}u$$

and we insert weighting terms as before. This is implemented in Loader's library locfit: using a locally polynomial (by default quadratic) hazard.

The xlim=c(0, 1e10) argument sets a lower bound (only) on the support of the density.

Both there approaches can have difficulties in the right tail of the distribution, where uncensored observations may be rare. The right tail of a distribution fitted by logspline.fit necessarily is exponential beyond the last observation. In HEFT (Hazard Estimation with Flexible Tails; Kooperberg *et al.*, 1995a). a cubic spline model is used for the log hazard, but with two additional terms  $\theta_1 \log t/(t+c)$  and  $\theta_2 \log(t+c)$  where c is the upper quartile for the uncensored data. Then the space of fitted hazards includes the functions

$$h(t) = e^{\theta_0} t^{\theta_1} (t+c)^{\theta_2 - \theta_1}$$

which includes the Weibull family and the Pareto density

$$f(t) = \frac{bc^b}{(t+c)^{b+1}}$$

for given c. Thus there is some hope that the tail behaviour can be captured within this parametric family. This is implemented in function heft.fit in library heft. To illustrate this, let us consider the whole of the Australian AIDS dataset Aids.

1500

2000

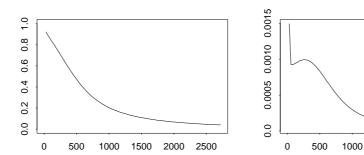


Figure 12.2: Survivor curve and hazard fitted to Aids by heft.fit.

```
library(heft)
attach(Aids2)
aids.heft <- heft.fit(death-diag+0.9, status=="D")
heft.summary(aids.heft)
par(mfrow=c(2,2))
heft.plot(aids.heft, what="s", ylim=c(0,1))
heft.plot(aids.heft)</pre>
```

This is rather slow (20 seconds). The sharp rise at 0 of the hazard reflects the small number of patients diagnosed at death. Note that this is the *marginal* hazard and its shape need not be at all similar to the hazard fitted in a (parametric or Cox) proportional hazards model.

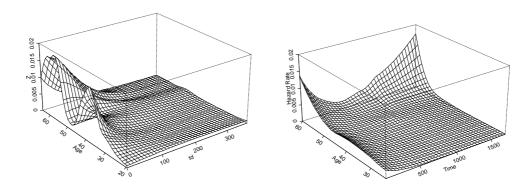
### 12.6 Non-parametric models with covariates

There have been a number of approaches to model the effect of covariates on survival without a parametric model. Perhaps the simplest is a localized version of the Kaplan-Meier estimator

$$\hat{S}(t \mid x) = \prod_{t_i \le t, \delta_i = 1} \left[ 1 - \frac{w(x_i - x)}{\sum_{j \in R(t_i)} w(x_j - x)} \right]$$

which includes observations with weights depending on the proximity of their covariates to x. This does not smooth the survivor function, but the function  ${\tt sm.survival}$  in library  ${\tt sm}$  (Bowman & Azzalini, 1997) plots quantiles as a function of x by smoothing the inverse of the survival curve and computing quartiles of the smoothed fit. Following them, we can plot the median survival time after transplantation in the Stanford heart transplant data heart by

```
library(sm)
attach(heart[heart$transplant==1,])
sm.survival(age+48, log10(stop - start), event, h=5, p=0.50)
detach()
```



**Figure 12.3**: Smooth hazard functions (in days) as a function of age post-transplantation in the Stanford heart-transplant study. **Left:** by locfit and **right:** by hazcov using local scoring.

This shows some evidence of a decline with age, which can also be seen in the Cox analysis.

The local likelhood approach easily generalizes to localizing in covariate space too: in locfit this is requested by adding covariate terms to the right-hand-side of the formula.

Gray (1996, 1994) takes a similar but less formal approach, using loess to smooth a discretized version of the problem. This is implemented in his function hazcov in library hazcov. First the data are grouped on the covariate values, using quantiles of the marginal distributions or factor levels. Then time is divided into intervals and the number of events and total follow-up time computed for each interval for each covariate combination. In the default method described in the 1996 paper, the numbers of events and the follow-up totals are separately smoothed using loess function, and the hazard estimate formed by taking ratios. We can try this by

```
library(hazcov)
heart.hc <- hazcov(Surv(td, event) ~ Age, span=0.5)
plot(heart.hc)
persp.hazcov(Hazard.Rate ~ Time*Age, heart.hc)</pre>
```

The loess span was chosen by guesswork. Gray describes an approximate version of  $C_p$  to help select the span which we can use by

This indicates a minimum at  $\alpha = 0.2$ , but very little difference over the range [0.2, 0.5].

The alternative method (Gray, 1994: 'local scoring' invoked by ls=T), the counts are viewed a independent Poisson variates with mean total follow-up times hazard, and a local log-linear Poisson GLM is fitted by IWLS, using loess to smooth the log-hazard estimates.

```
heart.hc <- hazcov(Surv(td, event) ~ Age, span=0.5, ls=T)
plot(heart.hc)
persp.hazcov(Hazard.Rate ~ Time*Age, heart.hc)</pre>
```

### Spline approaches

HARE (HAzard Rate Estimation; Kooperberg *et al.*, 1995a) fits a linear tensor-spline model for the log hazard function conditional on covariates, that is  $\log h(t \mid x) = \eta(t, x; \theta)$  is a MARS-like function of (t, x) jointly. The fitting procedure is similar to that for logspline and lspec: an initial set of knots is chosen, the log-likelihood is maximized given the knots by a Newton algorithm, and knots and terms are added and deleted in a stepwise fashion. Finally, the model returned is that amongst those considered that maximizes a penalized likelihood (by default with penalty  $\log n$  times the number of parameters).

It remains to describe just what structures are allowed for  $\eta(t,x)$ . This is a linear combination of linear spline basis functions and their pairwise products, that is a linear combination of terms like  $c,t,(t-c)_+,x_j,(x_j-c)_+,tx_j,(tx_j-c)_+,x_jx_k,(x_jx_k-c)_+$  where the c are generic constants. The product terms are restricted to products of simple terms already in the model, and wherever a non-linear term occurs, that term also occurs with the non-linear term replaced by a linear term in the same variable. Thus this is just a MARS model in the p+1 variables restricted to pairwise interactions.

The model for the hazard function will be a proportional hazards model if (and only if) there are no products between t and covariate terms. In any case it has a rather restricted ability to model non-constant hazard functions, and it is recommended to transform time to make the marginal distribution close to exponential (with constant hazard) before applying HARE.

HARE is implemented in library hare by function hare.fit. The paper contains an analysis of the dataset cancer.vet which we can reproduce by

```
# VA is constructed on page 363
> attach(VA)
> library(HARE)
> options(contrasts=c("contr.treatment", "contr.poly"))
```

```
> VAx <- model.matrix( ~ treat+age+Karn+cell+prior, VA)[,-1]
> VA.hare <- hare.fit(stime, status, VAx)
> hare.summary(VA.hare)
the present optimal number of dimensions is 9.
penalty(AIC) was the default: BIC=log(samplesize): log(137)=4.92
  dim1
                 dim2
                                beta
                                           SE
                                                     Wald
Constant
                                                    -4.35
                              -9.83e+00 2.26e+00
Co-3 linear
                               2.50e-01 1.08e-01
                                                     2.31
Co-5 linear
                               2.43e+00 4.72e-01
                                                     5.15
Co-4 linear
                              -1.39e+00 6.35e-01
                                                    -2.20
Time 1.56e+02 Co-5 linear
                              -1.25e-02 4.50e-03
                                                    -2.77
Time
     1.56e+02
                               2.45e-02 5.84e-03
                                                     4.20
Co-3 2.00e+01
                              -2.60e-01 1.08e-01
                                                    -2.41
Co-3 linear
                               3.87e-02 1.12e-02
                                                     3.46
               Co-4 linear
Time 1.56e+02 Co-3 linear
                              -4.33e-04 9.58e-05
                                                    -4.52
     0.008
     90000
     0.004
```

**Figure 12.4**: The marginal distribution of lifetime in the cancer.vet dataset. **Left:** Hazard as fitted by heft.fit. **Right:** Time as transformed by the distribution fitted by heft.fit and by a fitted Weibull distribution.

We found that an exponential model for the residual hazard was adequate, but Kooperberg *et al.* (1995a) explore the marginal distribution by HEFT and conclude that the time-scale could usefully be transformed. They used

```
library(HEFT)
VA.heft <- heft.fit(stime, status, leftlog=0)
heft.plot(VA.heft, what="h")
nstime <- -log(1 - pheft(stime, VA.heft))</pre>
```

In fact the transformation used is close to that from fitting a Weibull distribution

```
survreg(Surv(stime, status) ~ 1, data=VA)
....
Coefficients:
  (Intercept)
    4.793146
```

It does seem undesirable to ignore the highly significant covariate effects in making such a transformation; this is illustrated in this example by the change in the Weibull shape parameter from 1.174 to 0.928 (foot of page 364) on fitting linear terms in the survival regression model.

Having transformed time, we can re-fit the model.

```
> VA.hare2 <- hare.fit(nstime, status, VAx)</pre>
hare.summary(VA.hare2)
the present optimal number of dimensions is 10.
penalty(AIC) was the default: BIC=log(samplesize): log(137)=4.92
               dim2
                                        SE
 dim1
                             beta
                                                 Wald
Constant
                            -7.06e+00 2.60e+00 -2.72
Co-3 linear
                            2.72e-01 1.10e-01
                                                2.47
Co-5 linear
                            5.54e+00 1.15e+00
                                               4.81
Time 2.67e+00
                            2.24e+00 6.22e-01
                                                3.60
Time 2.67e+00 Co-5 linear -2.00e+00 5.40e-01 -3.70
Time 2.67e+00 Co-3 linear -4.21e-02 9.54e-03 -4.42
Co-4 linear
                           -1.16e+00 6.53e-01 -1.77
                          -2.73e-01 1.17e-01 -2.33
Co-3 8.50e+01
Co-3 linear Co-4 linear
                            3.39e-02 1.15e-02
                                                 2.94
Co-3 2.00e+01
                           -2.31e-01 1.08e-01 -2.13
```

Allowing for the time transformation, the fitted model is quite similar. Covariate 3 is the Karnofsky score, and 4 and 5 are the contrasts of cell type adeno and small with squamous. It is not desirable to have a variable selection process that is so dependent on the coding of the factor covariates.

This example was used to illustrate the advantages of HARE/HEFT methodology by their authors, but seems rather to show up its limitations. We have already seen that the *marginal* transformation of time is quite different from that suggested for the *conditional* distribution. In our analysis via Cox proportional hazards models we found support for models with interactions where the main effects are not significant (such models will never be found by a forward selection procedure such as used by HARE) and the suspicion of time-dependence of such interactions (which would need a time cross covariate cross covariate interaction which HARE excludes).

## Chapter 13

## Multivariate Analysis

### 13.3 Discriminant analysis

Correspondence analysis (continued)

There are many ways to look at correspondence analysis and corresponding plots, and as Gower & Hand (1996, p. 183) point out<sup>1</sup>

'It is important that any published graphics make it clear just which of these, or other, representations is being represented.'

We considered correspondence analysis for an  $r \times c$  table  $N = (n_{ij})$  via the singular value decomposition of  $D_r^{-1/2}(N/n)D_c^{-1/2} = U\Lambda V^T$  where n = n...,  $D_r = \sqrt{\operatorname{diag}(n_{i.}/n)}$  and  $D_c = \sqrt{\operatorname{diag}(n_{.j}/n)}$ . We dropped the first component which corresponds to columns of one; we can now eliminate this component by considering  $n_{ij}/n - (n_{i.}/n)(n_{.j}/n)$ ; we then have the singular-value decomposition of

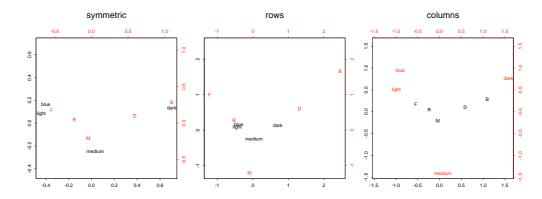
$$X_{ij} = \frac{n_{ij}/n - (n_{i\cdot}/n)(n_{\cdot j}/n)}{\sqrt{(n_{i\cdot}/n)(n_{\cdot j}/n)}} = \frac{n_{ij} - n \, r_i \, c_j}{n\sqrt{r_i \, c_j}}$$

where  $r_i = n_i / n$  and  $c_j = n_{\cdot j} / n$  are the proportions in each row and column. One view is to see  $\sum_s \left| X_{is} - X_{js} \right|^2$  as a squared 'distance' from row i to column j.

In this form the simple correspondence analysis corresponds to selecting the first singular value and left and right singular vectors of  $X_{ij}$  and rescaling by  $D_r^{-1/2}$  and  $D_c^{-1/2}$  respectively<sup>2</sup>. Can we make use of the subsequent singular values? In what Gower & Hand call 'classical CA' we consider  $A = D_r^{-1/2}U\Lambda$  and  $B = D_c^{-1/2}V\Lambda$ . Then the first columns of A and B are what we have termed the row and column scores *scaled by*  $\rho$ , the first canonical correlation. More generally, we can see distances between the rows of A as approximating (in the  $\chi^2$ -distance) the distances between the row profiles (rows rescaled to unit

<sup>&</sup>lt;sup>1</sup> although they neglect to follow their own advice; for example their figures 4.2 and 9.1 have no axes and no indication of what precisely has been plotted.

<sup>&</sup>lt;sup>2</sup> and that is how the code now works.



**Figure 13.15**: Three variants of correspondence analysis plots from Fisher's data on people in Caithness.

sum) of the table  $\,N\,$ , and analogously for the rows of  $\,B\,$  and the column profiles.

Classical CA plots the first two columns of A and B on the same figure. This is a form of a biplot and is obtained with our software by plotting a correspondence analysis object with  $\mathsf{nf} \geqslant 2$  or as the default for the method biplot.correspondence. Note that this is not a standard biplot as the inner products

$$AB^{T} = D_{r}^{-1/2} U \Lambda^{2} V^{T} D_{c}^{-1/2}$$

have no simple interpretation. This is sometimes known as a 'symmetric' plot.

Other authors (for example Greenacre, 1992) advocate 'asymmetric' plots. The asymmetric plot for the rows is a plot of the first two columns of A with the column labels plotted at the first two columns of  $\Gamma = D_c^{-1/2}V$ ; the corresponding plot for the columns has columns plotted at B and row labels at  $\Phi = D_r^{-1/2}U$ . The most direct interpretation for the row plot is that

$$A = D_r^{-1} N \Gamma$$

so A is a plot of the *row profiles* (the rows normalized to sum to one) as convex combinations of the column vertices given by  $\Gamma$ . The asymmetric plots are produced by giving plot or biplot argument type="rows" or type="columns".

By default corresp only retains one-dimensional row and column scores; then plot.corresp plots these scores and indicates the size of the entries in the table by the area of circles. The two-dimensional forms of the plot are shown in Figure 13.15 for Fisher's data on people from Caithness. These were produced by

```
caith <- read.table("Fisher.dat")
dimnames(caith)[[2]] <- c("F", "R", "M", "D", "B")
par(mfcol=c(1,3))
plot(corresp(caith, nf=2)); title("symmetric")
plot(corresp(caith, nf=2), type="rows"); title("rows")
plot(corresp(caith, nf=2), type="col"); title("columns")</pre>
```

Note that the symmetric plot (left) has the row points from the asymmetric row plot (middle) and the column points from the asymmetric column plot (right) superimposed on the same plot (but with different scales).

Multiple correspondence analysis

Multiple correspondence analysis (MCA) is (confusingly!) a method for visualizing the joint properties of  $p \ge 2$  categorical variables that does *not* reduce to correspondence analysis (CA) for p = 2, although the methods are closely related (see, for example, Gower & Hand, 1996, §10.2).

Suppose we have n observations on the p factors with  $\ell$  total levels. Consider G, the  $n \times \ell$  indicator matrix whose rows give the levels of each factor for each observation. Then all the row sums are p. MCA is often (Greenacre, 1992) defined as CA applied to the table G, that is the singular-value decomposition of  $D_r^{-1/2}(G/\sum_{ij}g_{ij})D_c^{-1/2}=U\Lambda V^T$ . Note that  $D_r=pI$  since all the row sums are p, and  $\sum_{ij}g_{ij}=np$ , so this amounts to the SVD of  $p^{-1/2}GD_c^{-1/2}/pn^3$ 

An alternative point of view is that MCA is a principal components analysis of the data matrix  $X=G(pD_c)^{-1/2}$ ; with PCA it is usual to centre the data but it transpires that the largest singular value is one and the corresponding singular vectors account for the means of the variables. Thus a simple plot for MCA is to plot the first two principal components of X. It will not be appropriate to add axes for the columns of X as the possible values are only  $\{0,1\}$ , but it is usual to add the positions of X on each of these axes, and label these by the factor level. (The 'axis' points are plotted at the appropriate row of  $(pD_c)^{-1/2}V$ .) The point plotted for each observation is the vector sum of the 'axis' points for the levels taken of each of the factors. Gower and Hand seem to prefer (e.g. their figure 4.2) to rescale the plotted points by p, so they are plotted at the centroid of their levels. This is exactly the asymmetric row plot of the CA of G, apart from an overall scale factor of  $p\sqrt{n}$ .

We can apply this to the example of Gower & Hand (1996, p. 75) by

```
farms.mca <- mca(farms, abbrev=T) # Use levels as names
plot(farms.mca, cex=rep(0.7,2))</pre>
```

Sometimes it is desired to add rows or factors to an MCA plot. Adding rows is easy: the observations are placed at the centroid of the 'axis' points for levels that are observed. Adding factors (so-called *supplementary variables*) is less obvious. The 'axis' points are plotted at the rows of  $(pD_c)^{-1/2}V$ . Since  $U\Lambda V^T=X=G(pD_c)^{-1/2}$ ,  $V=(pD_c)^{-1/2}G^TU\Lambda^{-1}$  and

$$(pD_c)^{-1/2}V = (pD_c)^{-1}G^TU\Lambda^{-1}$$

This tells us that the 'axis' points can be found by taking the appropriate column of G, scaling to total 1/p and then taking inner products with the second and third columns of  $U\Lambda^{-1}$ . This procedure can be applied to supplementary variables and so provides a way to add them to the plot. The predict method for class "mca" allows rows or supplementary variables to be added to an MCA plot.

 $<sup>^3</sup>$  Gower & Hand (1996) omit the divisor pn.

### 13.5 Factor analysis

### Rotation of principal components

The usual aim of both PCA and factor analysis studies is to find an interpretable smaller set of new variables that explain the original variables. Factor rotation is a very appealing way to achieve interpretability, and it can also be applied in the space of the first m principal components. The S-PLUS function rotate.princomp applies rotation to the output of a princomp analysis. For example, if we varimax rotate the first two principal components of ir.pca (page 383 of the text) we find

Note that only the first two components have been rotated, although all four are displayed.

It is important to consider normalization carefully when applying rotation to a principal component analysis, which is not scale-invariant.

- (a) Using argument cor=T to princomp ensures that the original variables are rescaled to unit variance when the principal components (PCs) are selected.
- (b) The 'loadings' matrix given by princomp is the orthogonal matrix V which transforms the variables X to the principal components Z = XV, so  $X = ZV^T$ . This is not the usual loadings matrix considered for rotation in principal component analysis (Basilevsky, 1994, p. 258), although it is sometimes used (Jolliffe, 1986, §7.4). The loadings of a factor analysis correspond to a set of factors of unit variance; normalizing the principal components to unit variance corresponds to  $X = Z^*A^T$  for  $A = V\Lambda$  and  $Z^* = Z\Lambda^{-1}$ . where (as on page 304)  $\Lambda$  denotes the diagonal matrix of singular values. The matrix A is known as the *correlation loadings*. since  $A_{ij}$  is the correlation between the ith variable and the jth PC (provided the variables were normalized to unit variance). Orthogonal rotations of  $Z^*$  remain uncorrelated and correspond to orthogonal rotations of the correlation loadings.
- (c) The S-PLUS default for rotations such as varimax is to normalize the loadings as at (13.8) so the sum of squares for each row (variable) is one. Thus (standardized) variables which are fitted poorly by the first m PCs are given the same weight as those which are fitted well. This seems undesirable for PCs (Basilevsky, 1994, p. 264), so it seems preferable not to normalize.

Taking these points into account we have

66

which does have a clear interpretation as dividing the variables into two nearly disjoint groups. It does seem that one common use of rotation in both principal component and factor analysis is to cluster the original variables, which can of course also be done by a cluster analysis of  $X^T$ .

## Chapter 14

### Tree-based Methods

### 14.4 Library RPart

The library section rpart by Beth Atkinson and Terry Therneau (Therneau & Atkinson, 1997) provides an alternative to tree for tree-based methods in S-PLUS which is both more and less flexible: the original code is available from statlib. We describe here the version released in March 1998<sup>1</sup>.

The underlying philosophy of rpart (which stands for Recursive Partitioning) is slightly different from that of tree, and is closer to that of Breiman et al. (1984) and the CART program. There is one function, rpart, that both grows and computes where to prune a tree; although there is a function prune.rpart it merely further prunes the tree at points already determined by the call to rpart, which has itself done some pruning. It is also possible to print a pruned tree by giving a pruning parameter to print.rpart. Note that (by default) rpart runs a 10-fold cross-validation akin to cv.tree and the results are stored in the rpart object to allow the user to choose the degree of pruning at a later stage.

The rpart system was designed to be easily extended to new types of responses. At present it has the following types, selected by the argument method.

- "anova" A regression tree, with the impurity criterion the reduction in sum of squares on creating a binary split of the data at that node. The criterion R(T) used for pruning is the mean square error of the predictions of the tree on the current dataset (that is, the residual mean square).
- "class" A classification tree, with a categorical or factor response and default impurity criterion the Gini index (p. 418). The deviance-based approach taken by tree corresponds to the 'entropy' or 'information' index, selected by the argument parms=list(split="information"). The pruning criterion R(T) is the predicted loss, normally the error rate. (Note that the default for prune.tree, deviance-based pruning, is not available.)

"poisson" in which the response is the number of events  $N_i$  in a specified duration  $t_i$  of observation. Deviance-based criteria are used to splitting

<sup>&</sup>lt;sup>1</sup> Available from http://www.stats.ox.ac.uk/pub/S/rpart.sh.gz (Unix) and the usual locations for Windows

and for pruning, assuming a Poisson-distributed number of events with mean  $\lambda_t t_i$  where the rate depends on the node t. The response is specified as either a two-column matrix of  $(N_i, t_i)$  or just a vector of  $N_i$  (in which case the time intervals are taken to be of unit length for all observations).

"exp" A survival tree in which the response must be a survival object, normally generated by Surv. This is a variant of the "poisson" method. Suppose that an exponential distribution was appropriate for the survival times. Then by the duality between views of a Poisson process the observed number of events (0 or 1) in the duration to censoring or death can be taken to be Poisson distributed, and the "poisson" method will give the correct likelihood. In general the exponential distribution is not appropriate, but it can perhaps be made so by non-linearly transforming time by the cumulative hazard function, and this is done estimating the cumulative hazard from the data<sup>2</sup>. This gives a proportional hazards model with the baseline hazard fixed as the estimated marginal hazard.

If the method argument is missing an appropriate type is inferred from the response variable in the formula.

It will be helpful to consider a few examples. First we consider a regression tree for the cpus data, then a classification tree for the iris data. The precise meaning of the argument cp is explained later; it is proportional to  $\alpha$  in the cost-complexity measure.

```
> library(Rpart)
> set.seed(123)
> cpus.rp <- rpart(log10(perf) ~ ., cpus[ ,2:8], cp=1e-3)
> cpus.rp
node), split, n, deviance, yval
      * denotes terminal node
  1) root 209 43.000 1.8
   2) cach<27 143 12.000 1.5
      4) mmax<6100 78 3.900 1.4
        8) mmax<1750 12 0.780 1.1 *
        9) mmax>1750 66 1.900 1.4
         18) mmax<2500 17 0.570 1.3 *
         19) mmax>2500 49 1.100 1.5
           38) chmax<4.5 14 0.350 1.4 *
           39) chmax>4.5 35 0.570 1.5
            78) syct<110 9 0.077 1.4 *
            79) syct>110 26 0.390 1.5 *
      5) mmax>6100 65 4.000 1.7
       10) syct>360 7 0.130 1.3 *
       11) syct<360 58 2.500 1.8
```

<sup>&</sup>lt;sup>2</sup> Note that this transformation is of the *marginal* distribution of survival times, although an exponential distribution would normally be assumed for the distribution conditional on the covariates. This is the same criticism as we saw for the HARE/HEFT methodology. RPart follows LeBlanc & Crowley (1992) in this 'one-step' approach.

```
22) chmin<5.5 46 1.200 1.7
           44) cach<0.5 11 0.200 1.5 *
           45) cach>0.5 35 0.620 1.8
             90) chmin>1.5 15 0.260 1.7 *
             91) chmin<1.5 20 0.260 1.8
              182) mmax<14000 13 0.088 1.8 *
              183) mmax>14000 7 0.110 1.9 *
         23) chmin>5.5 12 0.550 2.0 *
    3) cach>27 66 7.600 2.2
      6) mmax<28000 41 2.300 2.1
       12) cach<96.5 34 1.600 2.0
         24) mmax<11240 14 0.420 1.8 *
         25) mmax>11240 20 0.380 2.1
           50) chmax<14 10 0.078 2.0 *
           51) chmax>14 10 0.120 2.2 *
       13) cach>96.5 7 0.170 2.3 *
      7) mmax>28000 25 1.500 2.6
       14) cach<56 7 0.069 2.3 *
       15) cach>56 18 0.650 2.7 *
> ird <- data.frame(rbind(iris[,,1], iris[,,2],iris[,,3]),</pre>
           Species=c(rep("s",50), rep("c",50), rep("v",50)))
> ir.rp <- rpart(Species ~ ., data=ird, method="class", cp=1e-3)</pre>
> ir.rp
node), split, n, loss, yval, (yprob)
      * denotes terminal node
1) root 150 100 c ( 0.33 0.33 0.33 )
  2) Petal.L.>2.45 100 50 c ( 0.50 0.00 0.50 )
    4) Petal.W.<1.75 54 5 c ( 0.91 0.00 0.092 ) *
    5) Petal.W.>1.75 46  1 v ( 0.02 0.00 0.98 ) *
  3) Petal.L.<2.45 50 0 s ( 0.00 1.00 0.00 ) *
```

The output from the print method is very similar to that from print.tree, although the deviance is omitted for classification trees (only). The tree for the cpus data is larger than that shown in Figure 14.6; the tree for the iris data is one node smaller than that shown in Figure 14.5. (Note that neither rpart tree has yet been pruned to final size.)

We can now consider pruning by using printcp to print out the information stored in the rpart object.

```
> printcp(cpus.rp)
Regression tree:
rpart(formula = log10(perf) ~ ., data = cpus[, 2:8], cp = 0.001)
Variables actually used in tree construction:
[1] cach chmax chmin mmax syct
```

Root node error: 43.1/209 = 0.206

	CP	nsplit	rel	error	xerror	xstd
1	0.54927	0		1.000	1.005	0.0972
2	0.08934	1		0.451	0.480	0.0487
3	0.03282	3		0.274	0.322	0.0322
4	0.02692	4		0.241	0.306	0.0306
5	0.01856	5		0.214	0.278	0.0294
6	0.00946	9		0.147	0.288	0.0323
7	0.00548	10		0.138	0.247	0.0289
8	0.00440	12		0.127	0.245	0.0287
9	0.00229	13		0.123	0.242	0.0284
10	0.00141	15		0.118	0.240	0.0282
11	0.00100	16		0.117	0.238	0.0279

The columns xerror and xstd are random, depending on the random partition used in the cross-validation. We can see the same output graphically (Figure 14.10) by a call to plotcp.

plotcp(cpus.rp)

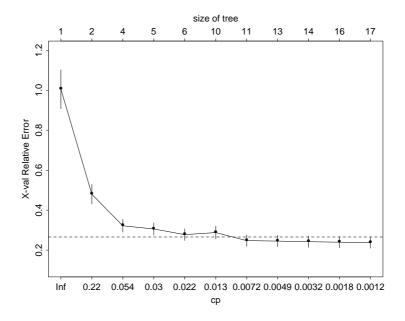


Figure 14.10: Plot by plotcp of the rpart object cpus.rp1.

We first need to explain the *complexity parameter* cp; this is just the cost-complexity parameter  $\alpha$  divided by the number  $R(T_{\emptyset})$  for the root tree<sup>3</sup>. A 10-fold cross-validation has been done within rpart to compute the entries<sup>4</sup> xerror and xstd; the complexity parameter may then be chosen to minimize xerror. An alternative procedure is to use the 1-SE rule, the largest value with xerror within one standard deviation of the minimum. In this case the 1-SE rule

 $<sup>^{3}</sup>$  thus for most measures of fit the complexity parameter lies in  $\left[0,1\right]$  .

 $<sup>^4</sup>$  all the errors are scaled so the root tree has error  $\,R(T_\emptyset)\,$  scaled to one.

gives 0.238 + 0.0279, so we choose line 7, a tree with 10 splits and hence 11 leaves<sup>5</sup>. We can examine this by

```
> print(cpus.rp, cp=0.006, digits=3)
node), split, n, deviance, yval
      * denotes terminal node
 1) root 209 43.1000 1.75
   2) cach<27 143 11.8000 1.52
     4) mmax<6100 78 3.8900 1.37
       8) mmax<1750 12 0.7840 1.09 *
       9) mmax>1750 66 1.9500 1.43 *
     5) mmax>6100 65 4.0500 1.70
      10) syct>360 7 0.1290 1.28 *
      11) syct<360 58 2.5000 1.76
        22) chmin<5.5 46 1.2300 1.70
          44) cach<0.5 11 0.2020 1.53 *
          45) cach>0.5 35 0.6160 1.75 *
        23) chmin>5.5 12 0.5510 1.97 *
   3) cach>27 66 7.6400 2.25
     6) mmax<28000 41 2.3400 2.06
      12) cach<96.5 34 1.5900 2.01
        24) mmax<11240 14 0.4250 1.83 *
        25) mmax>11240 20 0.3830 2.14 *
      13) cach>96.5 7 0.1720 2.32 *
     7) mmax>28000 25 1.5200 2.56
      14) cach<56 7 0.0693 2.27 *
      15) cach>56 18 0.6540 2.67 *
# or
> cpus.rp1 <- prune(cpus.rp, cp=0.006)</pre>
> plot(cpus.rp1, branch=0.4, uniform=T)
> text(cpus.rp1, digits=3)
```

The plot is shown in Figure 14.11.

The function xpred.rpart runs a V-fold cross-validation separately and returns the cross-validation predictions, so can be used to study cross-validation in more detail.

For the iris data we have

```
> printcp(ir.rp)
    ....
Variables actually used in tree construction:
[1] Petal.L. Petal.W.
Root node error: 100/150 = 0.66667
    CP nsplit rel error xerror xstd
```

<sup>&</sup>lt;sup>5</sup> The number of leaves is always one more than the number of splits.

72

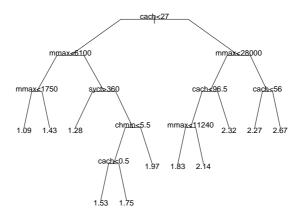


Figure 14.11: Plot of the rpart object cpus.rp1.

1	0.500	0	1.00	1.13	0.0528
2	0.440	1	0.50	0.58	0.0596
3	0.001	2	0.06	0.12	0.0332

which suggests no pruning, but that too small a tree has been grown since xerror has not reached its minimum.

The summary method, summary.rpart, produces much more output that summary.tree:

```
> summary(ir.rp)
Call:
rpart(formula = Species ~ ., data = ird, method = "class",
      cp = 0.001)
     CP nsplit rel error xerror xstd
1 0.500
             0
                   1.00
                         1.13 0.053
2 0.440
                          0.58 0.060
             1
                   0.50
3 0.001
            2
                   0.06
                          0.12 0.033
Node number 1: 150 observations,
                                   complexity param=0.5
 predicted class= c expected loss= 0.67
     class counts: 50 50 50
   probabilities: 0.33 0.33 0.33
 left son=2 (100 obs) right son=3 (50 obs)
 Primary splits:
     Petal.L. < 2.5 to the right, improve=50, (0 missing)
     Petal.W. < 0.8 to the right, improve=50, (0 missing)
      Sepal.L. < 5.4 to the left, improve=34, (0 missing)
     Sepal.W. < 3.3 to the left, improve=19, (0 missing)
 Surrogate splits:
     Petal.W. < 0.8 to the right, agree=1.00, (0 split)
     Sepal.L. < 5.4 to the right, agree=0.92, (0 split)
      Sepal.W. < 3.3 to the left, agree=0.83, (0 split)
Node number 2: 100 observations, complexity param=0.44
```

```
predicted class= c expected loss= 0.5
    class counts: 50 0 50
   probabilities: 0.5 0.0 0.5
 left son=4 (54 obs) right son=5 (46 obs)
 Primary splits:
     Petal.W. < 1.8 to the left, improve=39.0, (0 missing)
     Petal.L. < 4.8 to the left, improve=37.0, (0 missing)
     Sepal.L. < 6.1 to the left, improve=11.0, (0 missing)
     Sepal.W. < 2.5 to the left, improve= 3.6, (0 missing)
 Surrogate splits:
     Petal.L. < 4.8 to the left, agree=0.91, (0 split)
     Sepal.L. < 6.1 to the left, agree=0.73, (0 split)
     Sepal.W. < 3 to the left, agree=0.67, (0 split)
Node number 3: 50 observations
 predicted class= s expected loss= 0
    class counts: 0 50 0
   probabilities: 0 1 0
Node number 4: 54 observations
 predicted class= c expected loss= 0.093
    class counts: 49 0 5
   probabilities: 0.91 0.00 0.09
Node number 5: 46 observations
  predicted class= v expected loss= 0.022
    class counts: 1 0 45
    probabilities: 0.02 0.00 0.98
```

The initial table is that given by printcp. The summary method gives the top few (default up to five) splits and their reduction in impurity, plus up to five surrogates, splits on other variables with a high agreement with the chosen split. (These can be used to handle missing values if desired. See the subsection on 'missing values' below.) In this case the limit on tree growth is the restriction on the size of child nodes (which by default must cover at least seven cases).

The output from summary.rpart can be voluminous. Two arguments can help: as with print.rpart the argument cp effectively prunes the tree before analysis, and the argument file allows the output to be redirected to a file (via sink).

#### Fine control

The function rpart.control is usually used to collect together arguments for the control parameter of rpart just as for tree, although the defaults differ. The parameter minsplit is like minsize giving the smallest node that will be considered for a split: this defaults to 20. Parameter minbucket is like mincut, the minimum number of observations in a daughter node, which defaults to 7 (minsplit/3, rounded up).

The analogue of the parameter mindev of tree.control is the parameter cp which defaults to 0.01. If a split does not result in a branch  $T_t$  with  $R(T_t)$  at least  $\operatorname{cp} \times |T_t| \times R(T_\emptyset)$  it is not considered further. This is a form of 'pre-pruning'; the tree presented has been pruned to this value and the knowledge that this will happen can be used to stop tree growth<sup>6</sup>. In many of our examples the minimum of xerror occurs for values of cp less than 0.01, so we choose a smaller value.

Parameters maxcompete and maxsurrogate gives the number of good attributes and surrogates that are retained. Set maxsurrogate to zero if it is known that missing values will not be encountered.

The number of cross-validations is controlled by parameter xval, default 10. This can be set to zero at early stages of exploration, since this will produce a very significant speedup.

Note that these parameters may also be passed directly to rpart. For example for the iris data we have

```
> ir.rp1 <- rpart(Species ~ ., ird, cp=0, minsplit=5,</pre>
                       maxsurrogate=0)
> printcp(ir.rp1)
Root node error: 100/150 = 0.667
     CP nsplit rel error xerror xstd
1 0.50 0 1.00 1.18 0.0502

      2 0.44
      1
      0.50
      0.63 0.0604

      3 0.02
      2
      0.06
      0.08 0.0275

      4 0.01
      3
      0.04
      0.08 0.0275

      5 0.00
      4
      0.03
      0.07 0.0258

> print(ir.rp1, cp=0.015)
node), split, n, loss, yval, (yprob)
        * denotes terminal node
1) root 150 100 c ( 0.33 0.33 0.33 )
  2) Petal.L.>2.45 100 50 c ( 0.50 0.00 0.50 )
     4) Petal.W.<1.75 54 5 c ( 0.91 0.00 0.09 )
        8) Petal.L.<4.95 48 1 c ( 0.98 0.00 0.02 ) *
        9) Petal.L.>4.95 6 2 v ( 0.33 0.00 0.67 ) *
     5) Petal.W.>1.75 46  1 v ( 0.02 0.00 0.98 ) *
   3) Petal.L.<2.45 50 0 s ( 0.00 1.00 0.00 ) *
```

which suggests a tree with 4 leaves as in Figure 14.5.

#### Survival data

Now let us try a survival example: we return to the VA cancer dataset cancer.vet we considered in Chapter 12.

<sup>&</sup>lt;sup>6</sup> If  $R(T_t) \ge 0$ , splits of nodes with  $R(t) < \operatorname{cp} R(T_{\emptyset})$  will always be pruned.

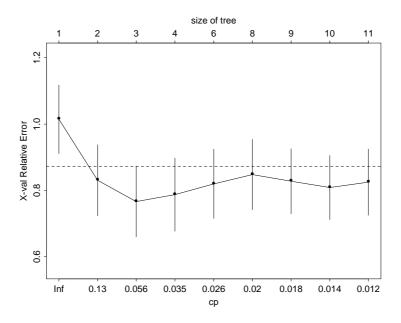


Figure 14.12: Plot by plotcp of the rpart object VA.rp.

```
> set.seed(123)
> VA.rp <- rpart(Surv(stime, status) ~ ., data=VA, minsplit=10)
> plotcp(VA.rp)
> printcp(VA.rp)
Root node error: 158/137 = 1.15
      CP nsplit rel error xerror
                                   xstd
1 0.1923
              0
                    1.000 1.014 0.1034
2 0.0829
              1
                    0.808 0.830 0.1071
3 0.0380
              2
                    0.725 0.766 0.1067
4 0.0319
              3
                    0.687
                          0.787 0.1102
5 0.0210
              5
                    0.623 0.820 0.1045
6 0.0189
             7
                    0.581 0.848 0.1060
7 0.0164
              8
                    0.562 0.828 0.0982
8 0.0123
              9
                    0.546 0.809 0.0966
9 0.0110
                    0.533 0.825 0.0999
             10
> print(VA.rp, cp=0.09)
node), split, n, deviance, yval
      * denotes terminal node
1) root 137 160 1.0
  2) Karn>45 99 81 0.8 *
  3) Karn<45 38 46 2.5 *
```

Here yval is the relative hazard rate for that node; we have a proportional hazards model and this is the estimated proportional factor.

In our experience it is common for tree-based methods to find little structure in cancer prognosis datasets: what structure there is depends on subtle interactions

76

between covariates.

#### **Plots**

There are plot methods for use on a standard S-PLUS graphics device (plot.rpart and tree.rpart), plus a method for post <sup>7</sup> for plots in POSTSCRIPT. Note that unlike post.tree, post.rpart is just a wrapper for calls to plot.rpart and text.rpart on a postscript device.

The function plot.rpart has a wide range of options to choose the layout of the plotted tree. Let us consider some examples<sup>8</sup>.

```
plot(VA.rp, branch=0.2); text(VA.rp, digits=3)
post(VA.rp, horizontal=F, pointsize=8)
```

The argument branch controls the slope of the branches: 1 gives those in the style of plot.tree and 0.2 (close to) the style of post.tree. Arguments uniform and compress control whether the spacing reflects the importance of the fits (by default it does) and whether a compact style is used. The call to tree.rpart may have additional arguments all which gives the value at all nodes (not just the leaves) and use.n which if true gives the numbers of cases reaching the node (and for classification trees the number of errors, for survival trees the number of uncensored values)

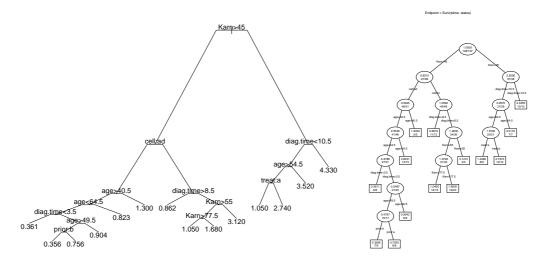


Figure 14.13: Plots of VA.rp. The left plot is from plot.rpart and text.rpart, the right from post.rpart.

The function snip.rpart works in a very similar way to snip.tree to allow interactive pruning of plotted trees.

### Further examples

We can re-analyse the two remaining examples from Chapter 14.

<sup>&</sup>lt;sup>7</sup> and the generic function: only post.tree exists in S-PLUS

<sup>&</sup>lt;sup>8</sup> Using S-PLUS 3.3 under Windows it will be necessary to set the filename argument, as the default filename, VA.rp.ps, is not a legal MS-DOS name.

```
Forensic glass
```

```
set.seed(123)
fgl.rp <- rpart(type ~ ., fgl, cp=0.001)
plotcp(fgl.rp)
printcp(fgl.rp)
Classification tree:
rpart(formula = type ~ ., data = fgl, cp = 0.001)
Variables actually used in tree construction:
[1] Al Ba Ca Fe Mg Na RI
Root node error: 138/214 = 0.645
     CP nsplit rel error xerror
1 0.2065 0 1.000 1.000 0.0507
2 0.0725
          2
               0.587 0.594 0.0515
3 0.0580 3
               0.514 0.587 0.0514
4 0.0362
         4
              0.457 0.551 0.0507
5 0.0326
          5
               0.420 0.536 0.0504
6 0.0109
           7
                0.355 0.478 0.0490
                0.333 0.500 0.0495
7 0.0010
          9
> print(fgl.rp, cp=0.02)
node), split, n, loss, yval, (yprob)
     * denotes terminal node
1) root 214 140 WinNF ( 0.33 0.36 0.07 0.06 0.04 0.14 )
  2) Ba<0.335 185 110 WinNF ( 0.37 0.41 0.09 0.06 0.04 0.01 )
    4) Al<1.42 113 50 WinF ( 0.56 0.27 0.12 0.00 0.02 0.01 )
     8) Ca<10.48 101 38 WinF ( 0.62 0.21 0.13 0.00 0.02 0.02 )
      16) RI>-0.93 85 25 WinF ( 0.71 0.20 0.07 0.00 0.01 0.01)
        32) Mg<3.865 77 18 WinF ( 0.77 0.14 0.06 0.00 0.01 0.0 1 ) *
        33) Mg>3.865 8
                    2 WinNF ( 0.12 0.75 0.12 0.00 0.00 0.0 0 ) *
      17) RI<-0.93 16 9 Veh ( 0.19 0.25 0.44 0.00 0.06 0.06 ) *
     9) Ca>10.48 12 2 WinNF ( 0.00 0.83 0.00 0.08 0.08 0.00 ) *
    5) Al>1.42 72 28 WinNF ( 0.08 0.61 0.05 0.15 0.08 0.01 )
     11) Mg<2.26 20 9 Con ( 0.00 0.15 0.00 0.55 0.25 0.05 )
```

plot(fgl.rp2); text(fgl.rp2)

This suggests a tree of size 8, plotted in

fgl.rp2 <- prune(fgl.rp, cp=0.02)

Low birth weights

This is a fairly small dataset, so the sequence of splits is sensitive to the precise minimum splits allowed. We can come close to copying tree by

which (on this cross-validation run) suggests that no split at all is best. This tree is grown using the Gini criterion, and differs slightly from that grown using entropy; we can get the same splits as tree (but to different depths) by

### Missing data

If the control parameter maxsurrogate is positive (and the parameter usesurrogate has not been altered), the surrogates are used to handle missing cases both in training and in prediction (including cross-validation to choose the complexity). Each of the surrogate splits is examined in turn, and if the variable is available that split is used to decide whether to send the case left or right. If no surrogate is available or none can be used, the case is sent with the majority unless usesurrogate < 2 when it is left at the node.

The default na.action during training is na.rpart, which excludes cases only if the response or *all* the explanatory variables are missing. (This looks like a sub-optimal choice, as cases with missing response are useful for finding surrogate variables.)

When missing values are encountered in considering a split they are ignored and the probabilities and impurity measures are calculated from the non-missing values of that variable. Surrogate splits are then used to allocate the missing cases to the daughter nodes.

Surrogate splits are chosen to match as well as possible the primary split (viewed as a binary classification), and retained provided they send at least two cases down each branch, and agree as well as the rule of following the majority. The measure of agreement is the number of cases that are sent the same way, possibly after swapping 'left' and 'right' for the surrogate. (As far as we can tell, missing values on the surrogate are ignored, so this measure is biased towards surrogate variables with few missing values.)

## Losses and priors

In a classification problem it is quite common to assign losses  $L_{ij}$  of declaring class j when class i is true, and for these to differ from the default choice of  $L_{ij} = I(j=i)$ . How to make optimal decisions when losses are present is discussed in detail in Ripley (1996, Chapter 2). In principle there is a clean separation; we find the posterior probabilities  $p(c \mid x)$  and use these to choose the class that minimizes the expected conditional loss  $\sum_i L_{ij} p(i \mid x)$ . In practice we have to estimate the posterior probabilities, and where we concentrate our effort depends on the use to which they will be put.

A similar argument applies to priors. Sometimes we know that the training set is unrepresentative of the target population (medical studies will often have too few normal patients, for example), and it is easy to adjust the posterior probabilities to take account of this (Ripley, 1996, p. 59). There are strong arguments with just two classes (given in that reference) for a form of weighted fitting with unequal losses that corresponds to adjusting the prior.

Ideally the target prior probabilities and the losses should be used to choose both the splits in the tree and its complexity. However, rpart just uses losses in choosing the splits, although it appears to use priors in the definition of R(T) and hence in the pruning phase. The formal definition of  $R(T) = \sum_t p_t \sum_c p_{tc} L_{c,C_t}$  where the sum is over leaves t, and the declared class  $C_t$  is chosen to minimized the expected loss at that node. Of course  $p_t$  is estimated by  $n_t/n$ , the proportion of cases reaching that node, and  $p_{tc}$  is usually estimated by  $n_{tc}/n_t$ , the proportion of class c cases reaching that node. However, if we have a specified prior  $(\pi_c)$ , we estimate  $p_{tc}$  by  $\widetilde{p}_{tc} = [\pi_c n_{tc}/n_{\cdot c}] / \sum_i [\pi_i n_{ti}/n_{\cdot i}]$ . We leave the reader to check that with no specified prior and the zero-one loss, R(T) becomes the overall error rate, number of misclassifications divided by n.

A prior is specified by a vector of length the number of classes as component prior of the list argument parms. A loss matrix can be specified by component loss of this list: the prior is then taken to be

$$\frac{\pi_i \sum_j L_{ij}}{\sum_{i,j} \pi_i L_{ij}}$$

## 14.5 Tree-structured survival analysis

Survival data are usually continuous, but are characterized by the possibility of censored observations. There have been various approaches to extending regression trees to survival data in which the prediction at each leaf is a survival distribution.

The deviance approach needs a common survival distribution with just one parameter (say the mean) varying between nodes. As the survival distribution has otherwise to be known completely, we would need to take, for example, a Weibull distribution with a specific  $\alpha$ . Thus this approach has most often been used with an exponential distribution (it goes back at least to Ciampi *et al.*, 1987 and is expounded in detail by Davis & Anderson, 1989). This is related to the approach of the rpart library described in the previous section.

Another family of approaches has been via impurity indices, which we recall measure the decrease in impurity on splitting the node under consideration. This can be replaced by a 'goodness-of-split' criterion measuring the difference in survival distribution in the two candidate daughter nodes. In regression trees the reduction in sum of squares can be seen as a goodness-of-split criterion, but a more natural candidate might be the unpooled (Welch) t-test between the samples passed to the two daughters. Given this change of viewpoint we can replace the

t-test by a test which takes censoring into account and is perhaps more appropriate for the typical shape of survival curves. The split selected at a node is then the candidate split with the most significant test of difference.

### Library tssa

Survival tree:

This approach is outlined by Segal (1988), who considers a family of statistics introduced by Tarone & Ware (1977) which includes the log-rank (Mantel-Haenszel) and Gehan tests and Prentice's generalization of the Wilcoxon test. His approach is implemented in the tssa library of Segal and Wager. This uses tssa as the main function, and generates objects of class "tssa" which inherits from class "tree". A member of the family of test statistics is selected by the argument choice. Splitting continues until there are maxnodes nodes (default 50) or no leaf has as many as minbuc cases (default 30) and a proportion at least propn (default 15%) of uncensored cases.

We consider the VA lung cancer data of Section 12.4. Since tssa cannot currently handle multi-level factors, we have to omit the variable cell.

```
> library(tssa, first=T)
> VA.tssa <- tssa(stime ~ treat + age + Karn + diag.time + prior,
                 status, data=VA, minbuc=10)
> VA.tssa
node), split, (n, failures), km-median, split-statistic
      * denotes terminal node, choice is Mantel-Haenzel
 1) root (137,128) 76.5 6.67
   2) Karn<45 (38,37) 19.5 2.71
     4) diag.time<10.5 (28,27) 21.0 2.08
       8) age<62.5 (14,13) 18.0 *
       9) age>62.5 (14,14) 33.0 *
     5) diag.time>10.5 (10,10) 8.0 *
   3) Karn>45 (99,91) 110.5 2.74
     6) Karn<82.5 (90,84) 104.0 2.22
      12) age<67.5 (74,69) 111.5 1.34
        24) prior<1.5 (50,48) 104.0 1.55
          48) age<59 (24,23) 110.0 1.22
           96) age<46.5 (13,13) 99.0 *
            97) age>46.5 (11,10) 127.0 *
          49) age>59 (26,25) 95.0 0.91
           98) diag.time<3.5 (11,11) 91.0 *
            99) diag.time>3.5 (15,14) 98.5 *
        25) prior>1.5 (24,21) 139.5 1.10
          50) treat<1.5 (14,13) 122.0 *
          51) treat>1.5 (10,8) 145.5 *
      13) age>67.5 (16,15) 72.0 *
     7) Karn>82.5 (9,7) 234.5 *
> summary(VA.tssa)
```

It can be helpful to examine more than just the mean at each node; the function km.tssa will plot the Kaplan-Meier estimates of survival curves for the two daughters of a non-terminal node. Interactive exploration<sup>9</sup> shows that there is

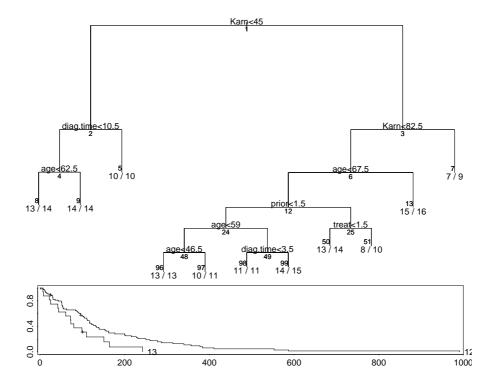


Figure 14.14: Tree fitted by tssa to the cancer.vet dataset. The bottom screen shows the output from km.tssa when node 6 was selected.

very little difference in survival between nodes at (Figure 14.14) or below node 6.

The change from a goodness-of-fit to a goodness-of-split view is not helpful for pruning a tree. Segal (1988) replaced optimizing a measure of the fit of the tree (as in cost-complexity pruning) with a stepwise approach.

- (i) Grow a very large tree.
- (ii) Assign to each non-terminal node the largest split statistic in the subtree rooted at that node. (This can be done in a single upwards pass on the tree.)

<sup>&</sup>lt;sup>9</sup> this relies on erase.screen which is broken in S-PLUS 4.0; it 'erases' by overplotting with a polygon filled with colour 0 which is no longer the background colour, and is normally transparent.

82

- (iii) Obtain a sequence of pruned trees by repeatedly pruning at the remaining node(s) with the smallest assigned values.
- (iv) Select one of these trees, perhaps by plotting the minimum assigned value against tree size and selecting the tree at an 'elbow'.

This is implemented in prune.tssa. Like snip.tree (and snip.tssa), a value is selected by a first click (on the lower screen), and the tree pruned at that value on the second click. For our example we can use

```
tree.screens()
plot(VA.tssa)
prune(VA.tssa)
close.screen(all=T)
```

The only clear-cut pruning point (Figure 14.15) is at a single split. There is

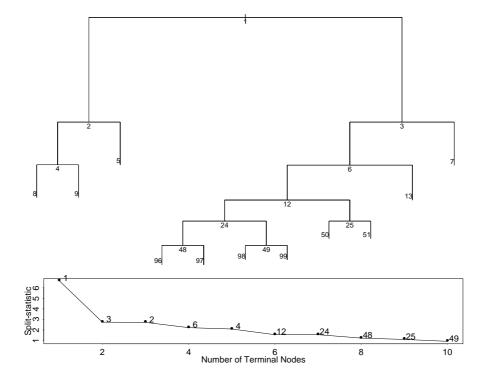


Figure 14.15: Tree fitted by tssa to the cancer.vet dataset. The bottom screen shows the prune sequence from prune.tssa.

a function post.tssa the equivalent of (and modified from) post.tree for tssa trees.

#### Library surveart

The library survcart <sup>10</sup> is sparsely documented, but appears to implement the strategy of LeBlanc & Crowley (1993). Like Segal, LeBlanc & Crowley use a

 $<sup>^{10}</sup>$  also known as <code>CART\_SD</code> .

goodness of split criterion for growing the tree, in this case the log-rank statistic with some adjustment for selecting the maximal statistic over all possible splits of continuous variables. However, the pruning strategy differs from tssa. Associate to each non-terminal node the goodness-of-split statistic  $G(\ell)$ , taking G to be zero at the terminal nodes. Then LeBlanc & Crowley apply cost-complexity pruning to the measure of fit

$$R(T) = -\sum_{\ell \in T} G(\ell)$$

This is not a sum over cases, but as it is defined additively over branches the standard pruning algorithm (Breiman et~al., 1984; Ripley, 1996) is still justified. (The 'deviance' quoted by prune.survtree is  $\sum_{\ell} G(\ell)$ .) The measure of fit can be computed on a validation set based down the optimally pruned tree sequence  $(T_r)$ , but as it is not a measure of performance there is no justification for then choosing the best fit; indeed R(T) decreases monotonically as the tree is grown, since  $G(\ell) \geqslant 0$ . The suggestion of LeBlanc & Crowley is to choose the pruning minimizing  $R_{\alpha}(T)$  on the validation set for  $\alpha \in [2,4]$ . (LeBlanc & Crowley also discuss using bootstrapping to bias-correct R(T) computed on the training set prior to pruning.)

Library survcart can be very memory-hungry: it comes with an informative demonstration that needs over 50Mb<sup>11</sup> of virtual memory to run.

We can try our VA cancer example by

The argument fact.flag says which variables should be regarded as *not* factors and included in the adjustment of the log-rank statistic for continuous variates (although a factor with many levels will give rise to *very* many more possible splits). The 'deviance' is  $-R(T_k) - \alpha_k(|T_k| - 1)$ !

We can reserve a validation set and use this for pruning by

 $<sup>^{11}</sup>$  on each of S-PLUS 3.3 for Windows and on Sun Solaris; over 100Mb on S-PLUS 4.0 for Windows

```
$k:
[1] 0.000000 0.033653 0.048377 0.709060 0.733988 2.595874
[7] 2.692954 3.346168 12.984497 13.469285 19.090138
```

Note that the size is the number of splits, one less than the number of leaves. We need to convert this to a split-complexity measure:

```
attach(VA.st1.pr)
dev <- dev + k*size
> dev - 2*size
[1] 12.6986 14.4335 15.6082 12.6082 14.1233 16.4956 18.4853
[8] 19.5681 5.2198 3.2339 0.0000
> dev - 4*size
[1] -11.3014 -7.5665 -4.3918 -5.3918 -1.8767 6.4956
[7] 10.4853 13.5681 1.2198 1.2339 0.0000
detach()
```

which suggests a tree with three splits

```
> prune(VA.st1, k=4)

1) root 90 19
2) cell:2,3 49 13
4) prior:0 40 0 *
5) prior:10 9 0 *
3) cell:1,4 41 13
6) Karn<45 8 0 *
7) Karn>45 33 0 *
```

Note how the selection penalty on continuous variables such as Karn reduces their prominence.

We can explore the spread of predictions over splits in a manner similar to  ${\tt km.tssa}$  by picking values of k in

```
VA.st.tmp <- prune.survtree(VA.st, k=2)
plot(surv.fit(VA$stime, VA$status, factor(VA.st.tmp$where)))</pre>
```

This shows the Kaplan-Meier estimates of survival at all the leaves, and by successively reducing k we can see when the range of variation is no longer essentially covered.

The function graph.survtree allows various aspects of the tree model to be plotted. The following call plots the median survival by node

but it can also show the survival probability at a fixed time.

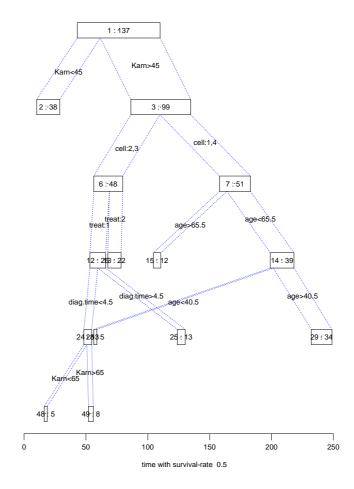


Figure 14.16: Plot of median survival by graph.survtree.

## Chapter 15

## Time Series

## 15.1 Second-order summaries

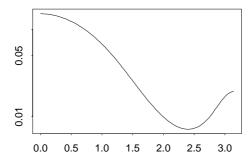
## Spectral analysis

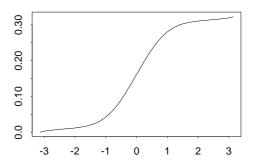
The most common approach to estimating a spectral density is to use a kernel smoother, as implemented by spectrum, but there are alternatives, including the use of fitted high-order AR processes (page 448). One promising line is to use some of the alternative methods of estimating a probability density function function, since a spectral density is just a finite multiple of a pdf.

The library 1spec by Charles Kooperberg implements the logspline approach described in Section 5.5 of these complements. Its application to spectral estimation is described in Kooperberg *et al.* (1995b); note that it is able to estimate mixed spectra that have purely periodic components. We will illustrate this by estimating the spectra of our running examples 1h and deaths as well as the accdeaths and nottem series.

For 1h we have

```
> library(lspec)
> lh.ls <- lspec.fit(lh)
> lspec.summary(lh.ls)
Logspline Spectral Estimation
The fit was obtained by the command:
 lspec.fit(data = lh)
 A spline with 3 knots, was fitted; there were no lines in the model.
The log-likelihood of the model was 60.25 which corresponds to an
 AIC value of -110.96 .
The program went though 1 updown cycles, and reached a stable
 solution. Both penalty (AIC) and minmass were the default
values. For penalty this was log(n) = log(24) = 3.18 (as in BIC)
and for minmass this was 0.0329. The locations of the knots were:
 1.178 2.749 3.142
> lspec.plot(lh.ls, log="y")
> lspec.plot(lh.ls, what="p")
```





**Figure 15.25**: Spectral density (left) and cumulative spectral distribution function (right) for the series 1h computed by library 1spec.

(Figure 15.25). Note that rather different conventions are used for the spectrum, which is taken to run over  $(-\pi, \pi]$  rather than in cycles, and the amplitude is given in the normal units, not decibels. The spectral density and cumulative spectrum can be found by dlspec and plspec respectively.

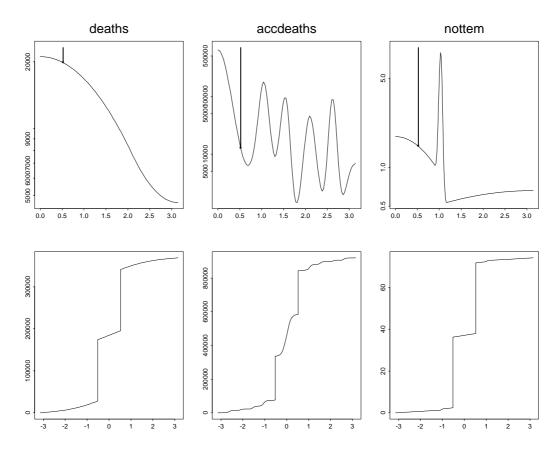
```
deaths.ls <- lspec.fit(deaths)
lspec.plot(deaths.ls, log="y", main="deaths")
lspec.plot(deaths.ls, what="p")
accdeaths.ls <- lspec.fit(accdeaths)
lspec.plot(accdeaths.ls, log="y", main="accdeaths")
lspec.plot(accdeaths.ls, what="p")
nott.ls <- lspec.fit(window(nottem, end=c(1936,12)))
lspec.plot(nott.ls, log="y", main="nottem")
lspec.plot(nott.ls, what="p")</pre>
```

(Figure 15.26). Note how lspec.fit finds the discrete component at frequency  $\pi/12$  in all three cases, but is fooled by harmonics in the last two. We can allow lspec.fit to fit more discrete components by reducing the value of its argument minmass (whose default can be found from lspec.summary). In the accdeaths example we can pick up all but one of the harmonics by

```
lspec.plot(lspec.fit(accdeaths, minmass=7000), log="y")
lspec.plot(lspec.fit(accdeaths, minmass=1000), log="y")
```

but reducing minmass introduces discrete components at non-harmonic frequencies (Figure 15.27).

The functions clspec and rlspec compute the autocovariance (or autocorrelation) sequence corresponding to the fitted spectrum and simulate a Gaussian time series with the fitted spectrum respectively.



**Figure 15.26**: Spectral density (top) and cumulative spectral distribution function (bottom) for the series deaths, accdeaths and nottem.

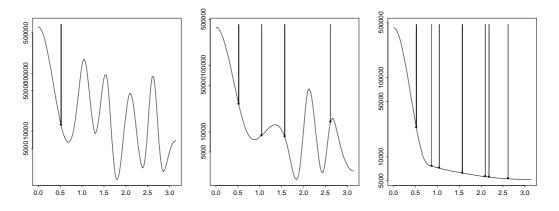


Figure 15.27: Spectra for nottem with minmass as (left to right) 77 000, 7000 and 1000.

## Chapter 16

# **Spatial Statistics**

### 16.3 Module S+SPATIALSTATS

The first release of the S-PLUS module S+SPATIALSTATS was released in mid-1996. That has a comprehensive manual (published as Kaluzny & Vega, 1997), which we do not aim to duplicate, but rather to show how our examples in Chapter 16 can be done using S+SPATIALSTATS.

The module S+SPATIALSTATS is attached and made operational by

```
module(spatial)
```

which we will assume has been done. Unfortunately the name is the same as our library (as are some of the function names); modules take priority over libraries.

## Kriging

The kriging functions use a slight extension of the model formula language. The function loc is used to specify the two spatial coordinates of the points, which are used to find the covariance matrix in kriging. Universal kriging is specified by adding other terms to form a linear model. Thus we can specify the model used in the bottom row of Figure 16.5 by

```
})
> topo.plt2 <- contourplot(se.fit ~ x*y, data=prsurf, pretty=F,
    at=c(20, 25), aspect=1)
> print(topo.plt1, split=c(1,1,2,1), more=T)
> print(topo.plt2, split=c(2,1,2,1))
```

(The sill value is explained below.) We can of course obtain a least-squares trend surface by giving a covariance function that drops to zero immediately, for example exp.cov with range = 0, but there seems no simple way to obtain a trend surface fitted by GLS. The predict method for krige objects takes either a newdata argument or a grid argument as used here. The grid argument must be a list with two components with names matching those given to loc and specifying the minimum, maximum and number of points. (This is passed to expand.grid to compute a data frame for newdata.)

Analogues of the fits shown in Figure 16.6 may be obtained by

Various functions are provided to fit variograms and correlograms. We start by fitting a variogram to the original data.

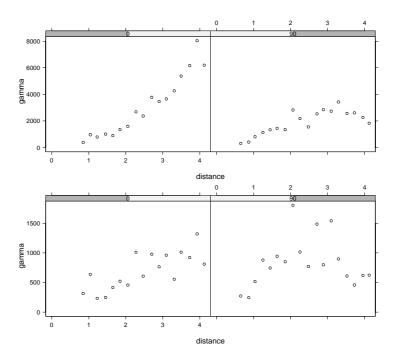
```
topo.var <- variogram(z ~ loc(x, y), data=topo)
model.variogram(topo.var, gauss.vgram, range=2,
    sill=6500, nugget=100)</pre>
```

The function model.variogram plots the variogram object (which may also be plotted directly) and draws a theoretical variogram. It then prompts the user to alter the parameters of the variogram to obtain a good fit by eye. It this case range = 3.5 seems indicated. The parametrization is that nugget is the increment at the origin, and sill is the change over the range of increase of the variogram. (In geostatistical circles the sum of 'nugget' and 'sill' is called the sill.) Thus the alph of our covariance functions is nugget/(sill + nugget).

There are functions correlogram and covariogram which can be used in the same way (including with model.variogram).

```
topo.cov <- covariogram(z ~ loc(x, y), data=topo)
model.variogram(topo.cov, gauss.cov, range=2,
    sill=4000, nugget=2000)</pre>
```

We can now explain how we chose the parameters of the exponential covariance in the first plot. An object of class "krige" contains residuals, so we can use



**Figure 16.10**: Directional variograms for the topo dataset. The top pair is for the raw data, the bottom pair of residuals from a quadratic trend surface. The left plots are vertical variograms, the right plots are horizontal ones. (The strip coverage is misleading, only showing the positive part of the angular tolerance.)

This suggests a sill of about 800. The kriging predictions do not depend on the sill, and our spatial library relies on this to work throughout with correlograms and to fit the overall scale factor when plotting the standard errors. Knowledge of our code allowed us to read off the value 770. It would be a good idea to repeat the forming of the residuals, this time from the GLS trend surface. We can choose the covariogram for the Gaussian case in the same way.

```
topo.var <- covariogram(topo.res ~ loc(x, y), data=topo)
model.variogram(topo.var, gauss.cov, range=1, sill=210,
    nugget=90)</pre>
```

### Spatial anisotropy

The geostatistical functions in S+SPATIALSTATS have considerable support for studying anisotropy of smooth spatial surfaces, and to correct for geometrical anisotropy (anisotropy which can be removed by 'squeezing' the plot in some direction). The function loc has two additional parameters angle and ratio to remove geometrical anisotropy. The functions variogram, correlogram and covariogram all allow multiple plots for pairs of distances in angular sectors. For example

```
plot(variogram(z ~ loc(x, y), data=topo, azimuth = c(0, 90),
    tol.azimuth = 45), aspect=0.7, layout=c(2,1))
plot(variogram(topo.res ~ loc(x, y), data=topo,
```

```
azimuth = c(0, 90), tol.azimuth = 45), aspect=0.7, layout=c(2,1))
```

They show vertical and horizontal variograms (for pairs within a tolerance of  $\pm 45^{\circ}$ ) of the raw topo data and then the residuals from the quadratic trend surface. (As these produce *and* print Trellis plots, none of the normal ways to put two plots on one page are possible and Figure 16.10 is assembled from two S-PLUS plots.)

## Point process functions

Spatial point patterns are objects of class "spp", with constructor function spp. We can convert our pines.dat to a spp object by

An object of class "spp" is a data frame with two attributes, "coords" declares which columns give the spatial coordinates, and "boundary" which gives the boundary of a polygon within which the pattern was observed. (This defaults to the bounding rectangle aligned with the axes, but the use of that is not advisable.)

We can reproduce Figure 16.8 quite closely by

```
par(pty = "s", mfrow=c(2,2))
plot(pines, boundary = T)
Lhat(pines, maxdist = 5)
Lenv(pines, 25, process = "binomial", maxdist=5)
Lhat(pines, maxdist =1.5)
Lenv(pines, 100, process = "Strauss", maxdist = 1.5,
    cpar = 0.2, radius = 0.7)
```

As this code shows, Lenv can simulate from several point process models: it does so by calling the function make.pattern whose functionality is equivalent to that of our functions Psim, SSI and Strauss plus certain Poisson cluster processes.

There is no way to estimate parameters of point process models in the current release of S+SPATIALSTATS, but it does have functions Fhat and Ghat to use *nearest neighbour* methods, and function intensity to estimate the intensity function of a heterogeneous point process. (This is closely related to bivariate density estimation.)

## Chapter 17

## Classification

## 17.3 Forensic glass

#### Neural networks

The recently-added method nnet.formula allows us to write some general functions for testing neural network models by V-fold cross-validation. First we re-scale the dataset so the inputs have range [0,1].

Then we can experiment with multiple logistic regressions.

```
res.multinom <- CVtest(
  function(x, ...) multinom(type ~ ., fgl1[x,], ...),
  function(obj, x) predict(obj, fgl1[x,],type="class"),
  maxit=1000, trace=F)
con(fgl$type, res.multinom)</pre>
```

We can now use a modest amount of weight decay as 'ridge regression', to reduce the effects of any irrelevant inputs.

```
res.mult2 <- CVtest(
    function(x, ...) multinom(type ~ ., fgl1[x,], ...),
    function(obj, x) predict(obj, fgl1[x,], type="class"),
    maxit=1000, trace=F, decay=1e-3)
> con(fgl$type, res.mult2)
    ....
error rate = 36.45 %

and also try out subset selection by

res.mult3 <- CVtest(
    function(xsamp, ...) {
        assign("xsamp", xsamp, frame=1)
        obj <- multinom(type ~ ., fgl1[xsamp,], trace=F, ...)
        stepAIC(obj)</pre>
```

```
},
function(obj, x) predict(obj, fgl1[x, ],type="class"),
maxit=1000, decay=1e-3)
> con(fgl$type, res.mult3)
....
error rate = 41.12 %
```

In our runs the variables RI, Na, Mg, Al and Si were retained in all 10 folds, and Ca in all but one, the only one in which K and Ba were retained.

It is straightforward to fit a fully specified neural network in the same way.

```
res.nn <- CVtest(
  function(x, ...) nnet(type ~ ., fgl1[x,], ...),
  function(obj, x) predict(obj, fgl1[x,], type="class"),
  maxit=1000, size=6, decay=0.01, trace=F)
> con(fgl$type, res.nn)
  ....
error rate = 29.91 %
```

We will, however, want to average across several fits

and to choose the number of hidden units and the amount of weight decay by an inner cross-validation. To do so we wrote fairly general function that can easily be used or modified to suit other problems.

```
res <- matrix(0, nrow(data), length(levels(truth)))</pre>
    if(verbose > 20) cat(" inner fold")
    for (i in sort(unique(ri))) {
      if(verbose > 20) cat(" ", i, sep="")
      for(rep in 1:nreps) {
        learn <- nnet(formula, data[ri !=i,], trace=F, ...)</pre>
        res[ri == i,] <- res[ri == i,] +
          predict(learn, data[ri == i,])
      }
  }
    if(verbose > 20) cat("\n")
    sum(unclass(truth) != max.col(res/nreps))
  truth <- data[,deparse(formula[[2]])]</pre>
  res <- matrix(0, nrow(data), length(levels(truth)))</pre>
  choice <- numeric(length(lambda))</pre>
  for (i in sort(unique(rand))) {
    if(verbose > 0) cat("fold ", i,"\n", sep="")
    ri <- sample(nifold, sum(rand!=i), replace=T)</pre>
    for(j in seq(along=lambda)) {
      if(verbose > 10)
        cat(" size =", size[j], "decay =", lambda[j], "\n")
      choice[j] <- CVnn1(formula, data[rand != i,], nreps=nreps,</pre>
                          ri=ri, size=size[j], decay=lambda[j],
                          verbose=verbose, ...)
    }
    decay <- lambda[which.is.max(-choice)]</pre>
    csize <- size[which.is.max(-choice)]</pre>
    if(verbose > 5) cat(" #errors:", choice, " ")
    if(verbose > 1) cat("chosen size = ", csize,
                        " decay = ", decay, "\n", sep="")
    for(rep in 1:nreps) {
      learn <- nnet(formula, data[rand != i,], trace=F,</pre>
                    size=csize, decay=decay, ...)
      res[rand == i,] <- res[rand == i,] +
          predict(learn, data[rand == i,])
    }
  }
  factor(levels(truth)[max.col(res/nreps)],
         levels = levels(truth))
> res.nn2 <- CVnn2(type ~ ., fgl1, skip=T, maxit=500, nreps=10)
> con(fgl$type, res.nn2)
      WinF WinNF Veh Con Tabl Head
       57
             10 3
                            Ω
WinF
                      0
                            2
WinNF
       16
           51 3
                      4
                                 0
  Veh
      8
             3 6 0
                            0
       0
  Con
              3 0 9
                            0
                                1
       0
                     1
                         5
 Tabl
             1 0
                                2
             3 0 1
 Head 0
                          0 25
```

```
error rate = 28.5 %
```

This fits a neural network 1000 times, and so is fairly slow (6 hours on the PC) and memory-intensive (about 20 Mb).

This code chooses between neural nets on the basis of their cross-validated error rate. An alternative is to use logarithmic scoring, which is equivalent to finding the deviance on the validation set. Rather than count 0 if the predicted class is correct and 1 otherwise, we count  $-\log p(c\,|\,x)$  for the true class c. We can easily code this variant by replacing the line

```
sum(unclass(truth) != max.col(res/nreps))
by
sum(-log(res[cbind(seq(along=truth),unclass(truth))]/nreps))
```

### Learning vector quantization

For LVQ as for k-nearest neighbour methods we have to select a suitable metric. The following experiments used Euclidean distance on the original variables, but the rescaled variables or Mahalanobis distance could also be tried.

```
cd0 <- lvqinit(fgl0, fgl$type, prior=rep(1,6)/6,k=3)
cd1 <- olvq1(fgl0, fgl$type, cd0)
con(fgl$type, lvqtest(cd1, fgl0))</pre>
```

We set an even prior over the classes as otherwise there are too few representatives of the smaller classes. Our initialization code follows Kohonen's in selecting the number of representatives: in this problem 24 points are selected, four from each class.

```
CV.lvq <- function()</pre>
  res <- fgl$type
  for(i in sort(unique(rand))) {
    cat("doing fold",i,"\n")
    cd0 <- lvqinit(fgl0[rand != i,], fgl$type[rand != i],</pre>
                   prior=rep(1,6)/6, k=3)
    cd1 <- olvq1(fgl0[rand != i,], fgl$type[rand != i], cd0)</pre>
    cd1 <- lvq3(fgl0[rand != i,], fgl$type[rand != i],</pre>
                cd1, niter=10000)
    res[rand == i] <- lvqtest(cd1, fgl0[rand == i,])
  }
  res
con(fgl$type, CV.lvq())
      WinF WinNF Veh Con Tabl Head
WinF
        59 10
                 1
                       0
                            0
                                 0
                 1
                            2
WinNF
      10
              61
                       2
                                 0
  Veh 6 8 3 0
                            0
```

```
Con 0 2 0 6 2 3
Tabl 0 0 0 2 7 0
Head 3 2 0 1 1 22
error rate = 26.17 %

# Try Mahalanobis distance
fgl0 <- scale(princomp(fgl[,-10])$scores)
con(fgl$type, CV.lvq())
....
error rate = 35.05 %</pre>
```

The initialization is random, so your results are likely to differ.

### Additive and tensor-spline models

The additive models discussed in Section 11.1 of these complements can also be used for classification problems. Three approaches to using a flexible family  $g(x;\theta)$  of functions for classification are discussed in Ripley (1996, Chapter 4), and we can use each of them for this problem.

### Least-squares fitting to indicator functions

In this approach the K classes generate an  $N \times K$  indicator matrix Y, which is regressed on the flexible family. The indicator matrix can easily be generated by the function class.ind in library nnet. Thus we can use BRUTO by

```
library(mda); library(nnet)
levs <- levels(fgl$type)
fgl.bruto <- bruto(fgl[, 1:9], class.ind(fgl$type))
bruto.class <- max.col(predict(fgl.bruto, as.matrix(fgl[, 1:9])))
con(fgl$type, factor(levs[bruto.class], levels=levs))</pre>
```

In this approach it is conventional to classify by predicting the class whose indicator is nearest to the vector prediction: elementary algebra shows that this is the same as choosing the largest of the predictions.

To obtain comparable results we need to use cross-validation.

Class Veh was never selected.

Almost exactly the same code can be used with MARS. We try additive models, then pairwise and then general tensor products.

```
res.mars <- CVtest(
   function(xsamp, ...)
     mars(as.matrix(fgl[xsamp, 1:9]),
          class.ind(fgl$type)[xsamp,], ...),
   function(obj, x)
     factor(levs[max.col(predict(obj,
                 as.matrix(fgl[x, 1:9])))], levels=levs)
con(fgl$type, res.mars)
error rate = 35.98 %
res.mars2 <- CVtest(degree=2,
   function(xsamp, ...)
     mars(as.matrix(fgl[xsamp, 1:9]),
          class.ind(fgl$type)[xsamp,], ...),
   function(obj, x)
     factor(levs[max.col(predict(obj,
                 as.matrix(fgl[x, 1:9])))], levels=levs)
con(fgl$type, res.mars2)
error rate = 33.64 %
res.mars9 <- CVtest(degree=9,
   function(xsamp, ...)
     mars(as.matrix(fgl[xsamp, 1:9]),
          class.ind(fgl$type)[xsamp,], ...),
   function(obj, x)
     factor(levs[max.col(predict(obj,
                 as.matrix(fgl[x, 1:9])))], levels=levs)
con(fgl$type, res.mars9)
error rate = 34.11 %
```

The library polymars of Kooperberg and O'Connor implements a restrictive form of MARS (for example, allowing only pairwise interations) suggested by Kooperberg *et al.* (1997), but will automatically generate the necessary indicator functions.

Prediction followed by linear discriminant analysis

Breiman & Ihaka (1984) had an idea to use a flexible family within linear discriminant analysis. This was picked up by Hastie *et al.* (1994) and Ripley (1994b); a full explanation of the connections is given in Ripley (1996). The idea amounts to using a least-squares prediction as above, but using linear discriminant analysis on the outputs, rather than choosing the largest output. Hastie *et al.* call this 'flexible discriminant analysis'.

The function fda in library mda can be used to implement this procedure. This does use formulae.

```
library(mda)
res.bruto.fda <- CVtest(method=bruto.
   function(xsamp, ...)
     fda(type ~ ., data=fgl[xsamp,], ...),
   function(obj, x) predict(obj, fgl[x, ])
con(fgl$type, res.bruto.fda)
error rate = 34.58 %
res.mars.fda <- CVtest(method=mars,</pre>
   function(xsamp, ...)
     fda(type ~ ., data=fgl[xsamp,], ...),
   function(obj, x) predict(obj, fgl[x, ])
con(fgl$type, res.mars.fda)
error rate = 35.51 %
res.mars2.fda <- CVtest(method=mars, degree=2,
   function(xsamp, ...)
     fda(type ~ ., data=fgl[xsamp,], ...),
   function(obj, x) predict(obj, fgl[x, ])
con(fgl$type, res.mars2.fda)
error rate = 38.32 %
res.mars9.fda <- CVtest(method=mars, degree=9,
   function(xsamp, ...)
     fda(type ~ ., data=fgl[xsamp,], ...),
   function(obj, x) predict(obj, fgl[x, ])
con(fgl$type, res.mars9.fda)
error rate = 34.58 %
```

Non-linear logistic discrimination

The third approach is a non-linear logistic model, that is

$$p(C = c \mid X = x) = \frac{\exp g_c(x; \theta)}{\sum_i \exp g_i(x; \theta)}$$
(17.2)

This is the approach taken by nnet with argument softmax=T. Note that there is some redundancy in (17.2) since the fitted probabilities depend only on the differences between the coordinates of g.

Library polyclass <sup>1</sup> by Charles Kooperberg fits (17.2) by additive models

<sup>&</sup>lt;sup>1</sup> polyclas on Windows.

with linear splines and can also include pairwise interactions. (Thus its space of non-linear functions is the same as that used by MARS with degree=2.) The redundancy is resolved by taking  $g_K \equiv 0$ . The methodology is described in more detail by Kooperberg *et al.* (1997) and Stone *et al.* (1997).

Fits using the polyclass library can be very slow. In the following code we reduce the maximum dimension of model fitted to achieve a more reasonable response time (about 2 minutes) after monitoring some preliminary runs (with parameter silent=F).

By default poly.fit uses a penalty on the number of terms used, in a similar way to logspline. If the argument cv is set to V it uses V-fold cross-validation to choose the complexity.

This fit took 17 minutes on the PC. The answer depends on the random partition; this is selected by the seed parameter (see the help page for the details).

The function poly.summary provides extensive information on a fitted polyclass model, and poly.beta and poly.plot plots aspects of the model.

### Mixture discriminant analysis

'Mixture discriminant analysis' (Hastie & Tibshirani, 1996) is a variant on plug-in linear discriminant analysis in which a mixture of normals is fitted to each class,

all normals having a common covariance matrix. This can be fitted by the function mda in library mda. We chose varying numbers of components depending on the prevalence of each class. The initialization is random, so your results may differ.

```
library(class) # needed for the initialization
res.mda <- CVtest(subclasses=c(6,6,3,3,2,4),
    function(xsamp, ...)
    mda(type ~ ., data=fgl[xsamp,], ...),
    function(obj, x) predict(obj, fgl[x,])
)
con(fgl$type, res.mda)
    ....
error rate = 30.84 %</pre>
```

This took about 4 minutes.

#### 17.4 Cross-validation

We have several uses of V-fold cross-validation in this chapter, as well as in selecting the complexity parameter when pruning classification trees. The code given on page 493 is reasonably general, and can be used for cross-validation of any procedure with a fitting function and a predict method that returns a relatively simple result (such as a classification factor or a matrix of probabilities. We can use something like

```
rand <- sample(V, nrow(data), replace=T)
CVtest <- function(fitfn, predfn, ...)
{
   res <- data$response
   for (i in sort(unique(rand))) {
      cat("fold ",i,"\n", sep="")
      learn <- fitfn(rand != i, ...)
      res[rand == i] <- predfn(learn, rand==i)
      NULL
   }
   res
}</pre>
```

(We added a NULL at the end of the loop as in sp 3.x this can help in minimizing memory usage.) For example, to find cross-validated posterior probabilities for linear discriminant analysis of the iris data we would use

```
ir <- rbind(iris[,,1], iris[,,2], iris[,,3])
ir.species <- c(rep("s",50), rep("c",50), rep("v",50))
V <- 10
rand <- sample(V, nrow(ir), replace=T)
CVtest <- function(fitfn, predfn, ...)
{
    res <- matrix(nrow=nrow(ir), ncol=3)</pre>
```

```
for (i in sort(unique(rand))) {
    cat("fold ",i,"\n", sep="")
    learn <- fitfn(rand != i, ...)
    res[rand == i,] <- predfn(learn, rand==i)
    NULL
  }
  res
}
res
}
res.lda <- CVtest(
  function(x, ...) lda(ir.species, ir, subset=x, ...),
  function(obj, x) predict(obj, ir[x, , drop=F])$post )
)</pre>
```

In general such cross-validated results can be quite variable, and we say for the use of cross-validation with classification trees, it can be helpful to average the results across a several different random partitions if CPU time permits.

What may not be obvious is that exactly the same code can be used for the earlier technique of leave-one-out cross-validation: just use

```
rand <- 1:nrow(ir)</pre>
```

Leave-one-out cross-validation is not generally to be recommended: it has considerable disadvantages, principally in giving highly-variable results and for some fitting procedures in not making a sufficient perturbation to the problem, for example when variable selection is used. Nevertheless, it may be of historical interest, and as for programming exercise we have added an argument CV=T to both lda and qda that invokes the fast updating formulae given<sup>2</sup> in Ripley (1996, p. 100).

Leave-one-out cross-validation is of much greater interest for a nearest-neighbour classifier. The function knn.cv in library class implements this in the straightforward way (by removing to considering each point when searching for its neighbours).

<sup>&</sup>lt;sup>2</sup> see its Errata for typographical corrections

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Entries in this font are names of S objects.

```
accdeaths, see Datasets
                                                Aids, 56, 57
additive models, 37, 97–100
                                                birthwt, 43, 44
Aids, see Datasets
                                                cancer.vet, 59, 60, 74, 81, 82
                                                Cars 93, 16
BCa confidence intervals, 9
                                                coop, 27
bcanon, 11
                                                cpus, 39, 47, 68, 69
BIC, 25
                                                deaths, 86, 88
biplot, 63
                                                faithful, 2, 5
biplot.correspondence, 63
                                                fgl, 93
birthwt, see Datasets
                                                galaxies, 3, 4, 7, 8
boot, 8-10
                                                gehan, 55, 56
boot.ci, 8,9
                                                heart, 57
bootstrap, 8, 22
                                                iris, 68, 69, 74, 101
   parametric, 9
                                                1h, 86, 87
bootstrap, 9-11
                                                mcycle, 37, 38
boott, 11
                                                minn38, 14
bruto, 39,40
                                                nottem, 88
                                                oats, 26
cancer.vet, see Datasets
                                                petrol, 24
Cars93, see Datasets
                                                Pima, 44
censboot, 9
                                                quine, 17, 20
                                                rock, 45, 46, 48-50
class.ind, 97
clspec, 87
                                                sitka, 27, 30
coop, see Datasets
                                                topo, 89, 91, 92
corClasses, 29
                                             deaths, see Datasets
correlogram, 90
                                             density estimation
correlogram, 90,91
                                                local polynomial, 4–7
corresp, 63
                                                logspline, 1–3
correspondence analysis, 62
                                             denumerate, 17
   multiple, 64
                                             digamma function,
   plots, 63
                                             discriminant analysis
covariogram, 90,91
                                                flexible, 98
cpus, see Datasets
                                                mixture, 100
cross-validation, 93, 94, 101
                                             dispersion parameter, 18
   leave-one-out, 102
                                             dlogspline, 3
crosstabs, 16
                                             dlspec, 87
cv.tree, 67
                                             erase.screen, 81
Datasets
                                             expand.grid, 90
   accdeaths, 86-88
                                             experiments
```

split-plot, 26	mda, 39, 98, 100
	multinom, 50
faithful, see Datasets	nlme, 24, 32, 35
fda, 98	nnet, 49, 50, 97
fgl, see Datasets	polyclass, 99, 100
Fhat, 92	polymars, 39, 98
flexible discriminant analysis, 98	ppr, 45
forensic glass, 93	rpart, 67, 79
	sm, 1, 37, 43, 57
galaxies, see Datasets	survcart, 82, 83
gam, 41	tssa, 80
gamma family, 18	linear mixed effects models, 24–29
gehan, see Datasets	lme, 24-29, 35, 36
generalized linear models	loadings, 65
gamma family, 18	correlation, 65
Ghat, 92	loc, 89,91
glm.dispersion, 19	locfit, 4-8, 38, 43, 44, 56, 58
glm.shape, 19	locpoly, 4,38
gls, 35	loess, 43,58
graph.survtree, 84,85	log-linear models, 12
	logarithmic scoring, 96
hare.fit, 59	logistic regression, 93
hazcov, 58	loglin, 12-14, 16, 17
heart, see Datasets	loglm, 13-17
heft.fit, 56,57,60	logspline.fit, 2,3,56
	logspline.plot, 3
iris, 71	logspline.summary, 3
iris, see Datasets	lspec.fit, 86,87
iterative proportional scaling, 12	lspec.plot, 86
	lspec.summary, 87
km.tssa, 81,84	LVQ, 96
knn.cv, 102	
krige, 89	mars, $39,40$
kriging, 89	mca, 64
	mcycle, see Datasets
learning vector quantization, 96	mda, 100
Lenv, 92	minn38, see Datasets
library	mixed effects models
boot, 8, 9, 23	linear, 24–29
bootstra, 10	non-linear, 30–35
class, 102	mixture discriminant analysis, 100
hare, 59	model formulae, 89
hazcov, 58	model.variogram, 90
heft, 56	multinom, 49,50
KernSmooth, 4, 37	
ksmooth, 4, 37	na.rpart, 78
locfit, 4, 37, 43, 56	nearest-neighbour, 102
logspline, 1, 55	neural networks, 49, 93
lspec, 86, 87	nlme, 30,32
MASS, 13, 19	nls, 32

nnet, 49, 52, 99	renumerate, 18
nnet.default, 49,51	rlspec, 87
nnet.formula, 49-51,93	rock, see Datasets
nnet.Hess, 49	rotate.princomp, 65
non-linear mixed effects models, 30-	rotation
35	in principal components, 65
non-linear models	rpart, 67,70,74,79
self-starting, 32	rpart.control, 73
nottem, see Datasets	,
,	S+SPATIALSTATS, 89–92
oats, see Datasets	scatterplot smoothers, 37
	sitka, see Datasets
petrol, see Datasets	sm.logit, 43,44
Pima, see Datasets	sm.poisson, 43
plogspline, 3	sm.regression, 37
plot.corresp, 63	sm.survival, 57
plot.rpart, 76	snip.rpart, 76
plotcp, 70,75	spectral analysis, 86, 87
plspec, 87	spectrum, 86
point processes, 92	splines, 1–3, 39, 45, 86, 87, 97–100
Poisson log-linear model, 12	split-plot experiments, 26
poly.beta, 100	spp, 92
poly.fit, 100	SSfpl, 32
poly.plot, 100	step.gam, 41
poly.summary, 100	summary.glm, 12,19
polyclass models, 100	summary.rpart, 73
post, 76	supsmu, 46
-	Surv, 68
post.rpart, 76 post.tree, 76	
_	survival analysis
post.tssa, 82	tree-structured, 79–83
ppreg, 45	tima sarias
predict, 90	time series
princomp, 65	spectral analysis, 86, 87
print.tree, 69	topo, see Datasets
printcp, 69,73	tree, 67,73
projection pursuit	tree.rpart, 76
regression, 45	trees, 67
prune.rpart, 67	in survival analysis, 68, 74, 75, 79–
prune.survtree, 83	83
prune.tree, 67	pruning, 67, 73, 81–83
prune.tssa, 82	tsboot, 9
	tssa, 80-82
qlogspline, 3	
quine, see Datasets	Unix, i, 4, 8, 10, 24, 37, 67
random effects, 24–35	VA, see Datasets, cancer.vet
multilevel, 26, 33	varClasses, 29
regression	variance components, 24–35
projection-pursuit, 45	variogram, 90
REML, 24	variogram, 91

```
vcov.multinom, 51
vector quantization
learning, 96
Windows, i, 1, 4, 8, 10, 24, 37, 67, 76, 83, 99
xpred.rpart, 71
```