



## A NADLER-TYPE FIXED POINT THEOREM IN DISLOCATED SPACES AND APPLICATIONS

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*Abstract.* In this paper, we introduce the concept of a Hausdorff dislocated metric. We initiate the study of fixed point theory for multi-valued mappings on dislocated metric space using the Hausdorff dislocated metric and we prove a generalization of the well known Nadler's fixed point theorem. Moreover, we provide some examples and we give an application of our main result.

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### 1. INTRODUCTION AND PRELIMINARIES

Let  $(X, d)$  be a metric space and  $CB(X)$  denotes the collection of all nonempty closed and bounded subsets of  $X$ . For  $A, B \in CB(X)$ , define

$$H(A, B) := \max \left\{ \sup_{a \in A} d(a, B), \sup_{b \in B} d(b, A) \right\},$$

where  $d(x, A) := \inf\{d(x, a) : a \in A\}$  is the distance of a point  $x$  to the set  $A$ . It is known that  $H$  is a metric on  $CB(X)$ , called the Hausdorff metric induced by the metric  $d$ .

**Definition 1.** Let  $X$  be any nonempty set. An element  $x$  in  $X$  is said to be a fixed point of a multi-valued mapping  $T : X \rightarrow 2^X$  if  $x \in Tx$ , where  $2^X$  denotes the collection of all nonempty subsets of  $X$ .

We recall that a multi-valued mapping  $T : X \rightarrow CB(X)$  is said to be a contraction if

$$H(Tx, Ty) \leq kd(x, y)$$

for all  $x, y \in X$  and for some  $k$  in  $[0, 1)$ .

The study of fixed points for multi-valued contractions using the Hausdorff metric was initiated by Nadler [18] who proved the following theorem.

**Theorem 1** ([18]). *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow CB(X)$  be a contraction mapping. Then, there exists  $x \in X$  such that  $x \in Tx$ .*

The notion of dislocated metric space was introduced by Hitzler and Seda [12] (see also [11]). Later, Amini-Harandi [9] re-discovered the notion of dislocated metric under the name of "metric-like". In this paper, the author [9] presented some fixed point results in the class of dislocated metric spaces. Very recently, Karapinar and Salimi [19] established some fixed point theorems for cyclic contractions. For more fixed point results on dislocated metric spaces, see e.g. [1–3, 7, 8, 13, 15, 16, 20–23].

**Definition 2.** Let  $X$  be a nonempty set. A function  $\sigma : X \times X \rightarrow [0, \infty)$  is said to be a dislocated metric (or a metric-like) on  $X$  if for any  $x, y, z \in X$ , the following conditions hold:

- ( $\sigma_1$ )  $\sigma(x, y) = 0 \implies x = y$ ;
- ( $\sigma_2$ )  $\sigma(x, y) = \sigma(y, x)$ ;
- ( $\sigma_3$ )  $\sigma(x, z) \leq \sigma(x, y) + \sigma(y, z)$ .

The pair  $(X, \sigma)$  is then called a dislocated metric (metric-like) space.

It is known that a partial metric [17] is also a dislocated metric. So, a trivial example of a dislocated metric space is the pair  $([0, \infty), \sigma)$ , where  $\sigma : [0, \infty) \times [0, \infty) \rightarrow [0, \infty)$  is defined as  $\sigma(x, y) = \max\{x, y\}$ .

In the sequel,  $\mathbb{R}_0^+$  represents the set of all nonnegative reals. In the following example, we give a dislocated metric which is neither a metric nor a partial metric.

*Example 1* ([6]). Take  $X = \{1, 2, 3\}$  and consider the dislocated metric  $\sigma : X^2 \rightarrow \mathbb{R}_0^+$  given by

$$\begin{aligned} \sigma(1, 1) &= 0, & \sigma(2, 2) &= 1, & \sigma(3, 3) &= \frac{2}{3}, \\ \sigma(1, 2) &= \sigma(2, 1) = \frac{9}{10}, & \sigma(2, 3) &= \sigma(3, 2) = \frac{4}{5}, \\ \sigma(1, 3) &= \sigma(3, 1) = \frac{7}{10}. \end{aligned}$$

Since  $\sigma(2, 2) \neq 0$ ,  $\sigma$  is not a metric and since  $\sigma(2, 2) > \sigma(1, 2)$ ,  $\sigma$  is not a partial metric [17].

Each dislocated metric  $\sigma$  on  $X$  generates a  $T_0$  topology  $\tau_\sigma$  on  $X$  which has as a base the family open  $\sigma$ -balls  $\{B_\sigma(x, \varepsilon) : x \in X, \varepsilon > 0\}$ , where  $B_\sigma(x, \varepsilon) = \{y \in X : |\sigma(x, y) - \sigma(x, x)| < \varepsilon\}$ , for all  $x \in X$  and  $\varepsilon > 0$ .

Observe that a sequence  $\{x_n\}$  in a dislocated metric space  $(X, \sigma)$  converges to a point  $x \in X$ , with respect to  $\tau_\sigma$ , if and only if  $\sigma(x, x) = \lim_{n \rightarrow \infty} \sigma(x, x_n)$ .

**Definition 3.** Let  $(X, \sigma)$  be a dislocated metric space.

- (a) A sequence  $\{x_n\}$  in  $X$  is said to be a Cauchy sequence if  $\lim_{n, m \rightarrow \infty} \sigma(x_n, x_m)$  exists and is finite.

- (b)  $(X, \sigma)$  is said to be complete if every Cauchy sequence  $\{x_n\}$  in  $X$  converges with respect to  $\tau_\sigma$  to a point  $x \in X$  such that  $\lim_{n \rightarrow \infty} \sigma(x, x_n) = \sigma(x, x) = \lim_{n, m \rightarrow \infty} \sigma(x_n, x_m)$ .

We need in the sequel the following trivial inequality

$$\sigma(x, x) \leq 2\sigma(x, y) \quad \text{for all } x, y \in X. \tag{1.1}$$

In this paper, we introduce a new concept called a Hausdorff dislocated metric . Using this concept, we establish a fixed point result for multi-valued mappings involving a generalized contraction. We derive many interesting corollaries on existing known results in the literature. Our obtained results are supported by some examples and an application to an integral equation.

## 2. HAUSDORFF DISLOCATED METRIC

Let  $(X, \sigma)$  be a dislocated metric space. Let  $CB^\sigma(X)$  be the family of all nonempty, closed and bounded subsets in the dislocated metric space  $(X, \sigma)$ , induced by the dislocated metric  $\sigma$ . Note that the boundedness is given as follows:  $A$  is a bounded subset in  $(X, \sigma)$  if there exist  $x_0 \in X$  and  $M \geq 0$  such that for all  $a \in A$ , we have  $a \in B_\sigma(x_0, M)$ , that is,

$$|\sigma(x_0, a) - \sigma(x_0, x_0)| < M.$$

The Closedness is taken in  $(X, \tau_\sigma)$  (where  $\tau_\sigma$  is the topology induced by  $\sigma$ ). Let  $\bar{A}$  be the closure of  $A$  with respect to the dislocated metric  $\sigma$ . We have

**Definition 4.**

$$\begin{aligned} a \in \bar{A} &\iff B_\sigma(a, \varepsilon) \cap A \neq \emptyset \quad \text{for all } \varepsilon > 0 \\ &\iff \text{there exists } x_n \in A, \quad x_n \rightarrow a \text{ in } (X, \sigma). \end{aligned}$$

If  $A \in CB^\sigma(X)$ , then  $\bar{\bar{A}} = A$ .

For  $A, B \in CB^\sigma(X)$  and  $x \in X$ , define

$$\begin{aligned} \sigma(x, A) &= \inf\{\sigma(x, a), a \in A\}, \quad \delta_\sigma(A, B) = \sup\{\sigma(a, B) : a \in A\} \quad \text{and} \\ \delta_\sigma(B, A) &= \sup\{\sigma(b, A) : b \in B\}. \end{aligned}$$

**Lemma 1.** *Let  $(X, \sigma)$  be a dislocated metric space and  $A$  be any nonempty set in  $(X, \sigma)$ , then*

$$\text{if } \sigma(a, A) = 0, \quad \text{then } a \in \bar{A}. \tag{2.1}$$

Also, if  $\{x_n\}$  is a sequence in  $(X, \sigma)$  that is  $\tau_\sigma$ -convergent to  $x \in X$ , then

$$\lim_{n \rightarrow \infty} |\sigma(x_n, A) - \sigma(x, A)| = \sigma(x, x). \tag{2.2}$$

*Proof.* If  $\sigma(a, A) = 0$ , so  $\inf_{x \in A} \sigma(a, x) = 0$ , that is, for all  $\varepsilon > 0$ , there exists  $x \in A$  such that  $\sigma(a, x) < \varepsilon$ . Hence, for all  $n \geq 1$ , there exists  $x_n \in A$  such that

$$\sigma(a, x_n) < \frac{1}{n}.$$

Thus,  $\lim_{n \rightarrow \infty} \sigma(a, x_n) = 0$ . By (1.1), we have  $\sigma(a, a) \leq 2\sigma(a, x_n)$ ,  $\forall n$ . Then,  $\sigma(a, a) \leq 2 \lim_{n \rightarrow \infty} \sigma(a, x_n) = 0$ . Finally, we obtain  $\lim_{n \rightarrow \infty} \sigma(a, x_n) = \sigma(a, a) = 0$ , which means that  $\{x_n\}$  converges to  $a$  in  $(X, \sigma)$ . By Definition 4,  $a \in \bar{A}$ .

The equality from (2.2) follows from the inequality

$$|\sigma(x_n - A) - \sigma(x, A)| = \sigma(x_n, x).$$

□

*Remark 1.* It was shown in Remark 2.1 from [4] that if  $A$  is a subset of a partial metric space  $(X, p)$  and  $x \in X$ , then

$$x \in \bar{A} \iff p(x, A) = p(x, x).$$

We show by an example that this property is not longer true in a dislocated metric space.

*Example 2.* Let  $X = \{0, 1\}$  and  $\sigma : X \times X \rightarrow \mathbb{R}_0^+$  be defined by

$$\sigma(0, 0) = 2 \quad \text{and} \quad \sigma(x, y) = 1 \text{ if } (x, y) \neq (0, 0).$$

Then,  $(X, \sigma)$  is a dislocated metric space. Note that  $\sigma$  is not a partial metric on  $X$  because  $\sigma(0, 0) \geq \sigma(1, 0)$ .

We have  $0 \in \bar{X} (= X)$ , but  $\sigma(0, X) = \min\{\sigma(0, 0), \sigma(0, 1)\} = 1 \neq \sigma(0, 0)$

Let  $(X, \sigma)$  be a dislocated metric space. For  $A, B \in CB^\sigma(X)$ , define

$$H_\sigma(A, B) = \max\{\delta_\sigma(A, B), \delta_\sigma(B, A)\}.$$

Now, we shall study some properties of  $H_\sigma : CB^\sigma(X) \times CB^\sigma(X) \rightarrow [0, \infty)$ .

**Proposition 1.** *Let  $(X, \sigma)$  be a dislocated metric space. For all  $A, B, C \in CB^\sigma(X)$ , we have the following:*

- (i) :  $H_\sigma(A, A) = \delta_\sigma(A, A) = \sup\{\sigma(a, A) : a \in A\}$ ;
- (ii) :  $H_\sigma(A, B) = H_\sigma(B, A)$ ;
- (iii) :  $H_\sigma(A, B) = 0$  implies that  $A = B$ ;
- (iv) :  $H_\sigma(A, B) \leq H_\sigma(A, C) + H_\sigma(C, B)$ .

*Proof.* (i) and (ii) are clear.

(iii) Suppose that  $H_\sigma(A, B) = 0$ . Then,

$$\sup_{a \in A} \sigma(a, B) = 0.$$

Mention that  $\sup_{a \in A} \sigma(a, B) = 0$ , implies  $\forall a \in A, \sigma(a, B) = 0$ . Then, by lemma 1,  $a \in \overline{B} = B$ . As  $a$  is arbitrary in  $A$ , we conclude that  $A \subset B$ . Similarly,  $H_\sigma(B, A) = 0$  implies  $B \subset A$ .

(iv) Let  $a \in A, b \in B$  and  $c \in C$ . As

$$\sigma(a, b) \leq \sigma(a, c) + \sigma(c, b),$$

so we have

$$\sigma(a, B) \leq \sigma(a, c) + \sigma(c, B) \leq \sigma(a, c) + \delta_\sigma(C, B) \leq \sigma(a, C) + \delta_\sigma(C, B),$$

since  $c$  is an arbitrary element of  $C$ . As  $a$  is an arbitrary element of  $A$ , it follows

$$\delta_\sigma(A, B) \leq \delta_\sigma(A, C) + \delta_\sigma(C, B) \leq H_\sigma(A, C) + H_\sigma(C, B).$$

Similarly, due to symmetry of  $H_\sigma$ , we have

$$\delta_\sigma(B, A) \leq H_\sigma(A, C) + H_\sigma(C, B).$$

Combining the two above inequalities, we get (iv). □

*Remark 2.* The converse of assertion (iii) from Proposition 1 is not true in general as it is clear from the following example.

*Example 3.* Let  $X = \{0, 1\}$  be endowed with the dislocated metric  $\sigma : X \times X \rightarrow [0, \infty)$  defined by

$$\sigma(1, 1) = 2 \quad \text{and} \quad \sigma(0, 0) = \sigma(0, 1) = \sigma(1, 0) = 1.$$

Note that  $\sigma$  is not a partial metric since  $\sigma(1, 1) > \sigma(1, 0)$ . From (i) of Proposition 1, we have

$$\begin{aligned} H_\sigma(X, X) &= \delta_\sigma(X, X) = \sup\{\sigma(x, X), x \in \{0, 1\}\} \\ &= \max\{\sigma(0, \{0, 1\}), \sigma(1, \{0, 1\})\} = 1 \neq 0. \end{aligned}$$

In view of Proposition 1, we call the mapping  $H_\sigma : CB^\sigma(X) \times CB^\sigma(X) \rightarrow [0, +\infty)$ , a Hausdorff dislocated metric induced by  $\sigma$ .

*Remark 3.* It is easy to show that any Hausdorff metric is a Hausdorff dislocated metric. The converse is not true (see Example 3).

### 3. FIXED POINT OF MULTI-VALUED CONTRACTION MAPPINGS

We start with the following simple useful lemma. One may find its analogous for the partial metric case in [5].

**Lemma 2.** *Let  $A, B \in CB^\sigma(X)$  and  $a \in A$ . Then, for all  $\varepsilon > 0$ , there exists a point  $b \in B$  such that  $\sigma(a, b) \leq H_\sigma(A, B) + \varepsilon$ .*

The inequality from Lemma 2 also appears in Nadler's paper [18]. Now, we state and prove our main result.

**Theorem 2.** *Let  $(X, \sigma)$  be a complete dislocated metric space. If  $T : X \rightarrow CB^\sigma(X)$  is a multi-valued mapping such that for all  $x, y \in X$ , we have*

$$H_\sigma(Tx, Ty) \leq k M(x, y) \quad (3.1)$$

where  $k \in [0, 1)$  and

$$M(x, y) = \max \left\{ \sigma(x, y), \sigma(x, Tx), \sigma(y, Ty), \frac{1}{4} (\sigma(x, Ty) + \sigma(y, Tx)) \right\}.$$

Then,  $T$  has a fixed point.

*Proof.* Let  $x_0 \in X$  and  $x_1 \in Tx_0$ . Clearly, if  $\sigma(x_0, x_1) = 0$ , then  $x_0 = x_1$  and  $x_0$  is a fixed point of  $T$ . Assume  $\sigma(x_0, x_1) > 0$ . Since  $Tx_0, Tx_1 \in CB^\sigma(X)$  and  $x_1 \in Tx_0$ , Lemma 2 implies the existence of a point  $x_2 \in Tx_1$  such that

$$\sigma(x_2, x_1) \leq H_\sigma(Tx_1, Tx_0) + \frac{1-k}{2} M(x_1, x_0). \quad (3.2)$$

If  $\sigma(x_2, x_1) = 0$ , then  $x_2 = x_1$  and  $x_1$  is a fixed point of  $T$ . Assuming  $\sigma(x_2, x_1) > 0$ , then, by Lemma 2, there is a point  $x_3 \in Tx_2$  such that

$$\sigma(x_3, x_2) \leq H_\sigma(Tx_2, Tx_1) + \frac{1-k}{2} M(x_2, x_1). \quad (3.3)$$

Continuing in this fashion, we complete a sequence  $(x_n) \subset X$  such that  $x_{n+1} \in Tx_n$  and  $\sigma(x_n, x_{n+1}) > 0$  with

$$\sigma(x_{n+1}, x_n) \leq H_\sigma(Tx_n, Tx_{n-1}) + \frac{1-k}{2} M(x_n, x_{n-1}).$$

Then, we get

$$\begin{aligned} & \sigma(x_{n+1}, x_n) \\ & \leq k M(x_n, x_{n-1}) + \frac{1-k}{2} M(x_n, x_{n-1}) \\ & = \frac{1+k}{2} M(x_n, x_{n-1}) \\ & \leq \frac{1+k}{2} \max \left\{ \sigma(x_n, x_{n-1}), \sigma(x_n, x_{n+1}), \frac{1}{4} [\sigma(x_n, x_n) + \sigma(x_{n-1}, x_{n+1})] \right\}. \end{aligned}$$

By a triangular inequality, we get

$$\begin{aligned} \frac{1}{4} (\sigma(x_n, x_n) + \sigma(x_{n-1}, x_{n+1})) & \leq \frac{1}{4} (3\sigma(x_n, x_{n-1}) + \sigma(x_{n+1}, x_n)) \\ & \leq \max \{ \sigma(x_n, x_{n-1}), \sigma(x_n, x_{n+1}) \}. \end{aligned}$$

Then

$$\sigma(x_n, x_{n+1}) \leq \frac{1+k}{2} \max \{ \sigma(x_{n-1}, x_n), \sigma(x_n, x_{n+1}) \}.$$

Now, if  $\sigma(x_n, x_{n+1}) > \sigma(x_{n-1}, x_n)$ , then we have

$$\sigma(x_n, x_{n+1}) \leq \frac{1+k}{2} \sigma(x_n, x_{n+1}) < \sigma(x_n, x_{n+1}),$$

which is a contradiction. So, for all  $n \geq 1$ ,  $\sigma(x_n, x_{n+1}) \leq \sigma(x_n, x_{n-1})$ . Finally, we get

$$\sigma(x_n, x_{n+1}) \leq \frac{1+k}{2} \sigma(x_{n-1}, x_n), \quad \forall n \geq 1.$$

Moreover, by induction, one finds

$$\sigma(x_n, x_{n+1}) \leq \left(\frac{1+k}{2}\right)^n \sigma(x_0, x_1), \quad \forall n \geq 1.$$

Since  $k \in [0, 1)$ , we have  $\sum_{n \geq 0} \left(\frac{1+k}{2}\right)^n < \infty$ . So, for all  $p \geq 0$ , we have

$$\begin{aligned} \sigma(x_n, x_{n+p}) &\leq \sigma(x_n, x_{n+1}) + \sigma(x_{n+1}, x_{n+2}) + \dots + \sigma(x_{n+p-1}, x_{n+p}) \\ &\leq \sum_{i=n}^{n+p-1} \left(\frac{1+k}{2}\right)^i \sigma(x_0, x_1) \\ &\leq \sum_{i=n}^{\infty} \left(\frac{1+k}{2}\right)^i \sigma(x_0, x_1) \rightarrow 0 \text{ as } n \rightarrow \infty. \end{aligned} \tag{3.4}$$

Thus, by symmetry of  $\sigma$ , we obtain

$$\lim_{n, m \rightarrow \infty} \sigma(x_n, x_m) = 0. \tag{3.5}$$

This yields that the sequence  $\{x_n\}$  is Cauchy. Since  $(X, \sigma)$  is complete, the sequence  $\{x_n\}$  converges to a point  $x^* \in X$ , i.e,

$$\lim_{n \rightarrow \infty} \sigma(x_n, x^*) = \sigma(x^*, x^*) = \lim_{n, m \rightarrow \infty} \sigma(x_n, x_m) = 0. \tag{3.6}$$

We have  $\sigma(x^*, Tx^*) \leq \sigma(x^*, x_{n+1}) + \sigma(x_{n+1}, Tx^*)$ .

Since  $x_{n+1} \in Tx_n$ , it follows

$$\begin{aligned} \sigma(x^*, Tx^*) &\leq \sigma(x^*, x_{n+1}) + \delta_{\sigma}(Tx_n, Tx^*) \\ &\leq \sigma(x^*, x_{n+1}) + H_{\sigma}(Tx_n, Tx^*) \\ &\leq \sigma(x^*, x_{n+1}) + kM(x_n, x^*), \end{aligned}$$

where

$$M(x_n, x^*)$$

$$= \max \left\{ \sigma(x_n, x^*), \sigma(x_n, Tx_n), \sigma(x^*, Tx^*), \frac{1}{4} (\sigma(x_n, Tx^*) + \sigma(x^*, Tx_n)) \right\}.$$

We have

$$\begin{aligned} \sigma(x_n, Tx_n) &\leq \sigma(x_n, x_{n+1}), \\ \sigma(x^*, Tx_n) &\leq \sigma(x^*, x_{n+1}). \end{aligned}$$

When passing to limit, it should be mentioned that, by Lemma 1 and (3.6),

$$\sigma(x^*, Tx_n) \rightarrow \sigma(x^*, Tx^*).$$

Again, by taking  $n \rightarrow \infty$  and using (3.6), we obtain

$$\begin{aligned} \sigma(x^*, Tx^*) &\leq k \max \left\{ \sigma(x^*, Tx^*), \frac{1}{4} \sigma(x^*, Tx^*) \right\} \\ &= k \sigma(x^*, Tx^*). \end{aligned}$$

Since,  $k \in [0, 1)$ , we have  $\sigma(x^*, Tx^*) = 0$ . Finally, by lemma 1, we have  $x^* \in \overline{Tx^*} = Tx^*$ . Then,  $x^*$  is a fixed point of  $T$ .  $\square$

As consequences of our main result, we may state the following immediate corollaries.

**Corollary 1** (Hardy-Rogers type [10]). *Let  $(X, \sigma)$  be a complete dislocated metric space. If  $T : X \rightarrow CB^\sigma(X)$  is a multi-valued mapping such that for all  $x, y \in X$ , we have*

$$H_\sigma(Tx, Ty) \leq a\sigma(x, y) + b\sigma(x, Tx) + c\sigma(y, Ty) + d[\sigma(x, Ty) + \sigma(y, Tx)] \quad (3.7)$$

where  $a, b, c, d \in [0, 1)$  such that  $a + b + c + 4d < 1$ . Then,  $T$  has a fixed point.

**Corollary 2** (Kannan type [14]). *Let  $(X, \sigma)$  be a complete dislocated metric space. If  $T : X \rightarrow CB^\sigma(X)$  is a multi-valued mapping such that for all  $x, y \in X$ , we have*

$$H_\sigma(Tx, Ty) \leq a\sigma(x, y) + b\sigma(x, Tx) + c\sigma(y, Ty) \quad (3.8)$$

where  $a, b, c \in [0, 1)$  such that  $a + b + c < 1$ . Then,  $T$  has a fixed point.

**Corollary 3.** *Let  $(X, \sigma)$  be a complete dislocated metric space. If  $T : X \rightarrow CB^\sigma(X)$  is a multi-valued mapping such that for all  $x, y \in X$ , we have*

$$H_\sigma(Tx, Ty) \leq k \sigma(x, y) \quad (3.9)$$

where  $k \in [0, 1)$ . Then,  $T$  has a fixed point.

**Corollary 4** ([4]). *Let  $(X, \sigma)$  be a complete partial metric space. If  $T : X \rightarrow CB^\sigma(X)$  is a multi-valued mapping such that for all  $x, y \in X$ , we have*

$$H_\sigma(Tx, Ty) \leq k \sigma(x, y) \quad (3.10)$$

where  $k \in [0, 1)$ . Then,  $T$  has a fixed point.



**Corollary 5** ([18]). *Let  $(X, \sigma)$  be a complete metric space. If  $T : X \rightarrow CB^\sigma(X)$  is a multi-valued mapping such that for all  $x, y \in X$ , we have*

$$H_\sigma(Tx, Ty) \leq k \sigma(x, y) \tag{3.11}$$

where  $k \in [0, 1)$ . Then,  $T$  has a fixed point.

**Corollary 6.** *Let  $(X, \sigma)$  be a complete dislocated metric space. If  $T : X \rightarrow X$  is a single-valued mapping such that for all  $x, y \in X$ , we have*

$$\begin{aligned} & \sigma(Tx, Ty) \\ & \leq k \max \left\{ \sigma(x, y), \sigma(x, Tx), \sigma(y, Ty), \frac{1}{4}(\sigma(x, Ty) + \sigma(y, Tx)) \right\} \end{aligned} \tag{3.12}$$

where  $k \in [0, 1)$ . Then,  $T$  has a fixed point  $x \in X$ , that is,  $Tx = x$ .

#### 4. EXAMPLES AND AN APPLICATION

First, we give the following illustrative examples where the main result of Aydi et al. [4] is not applicable..

*Example 4.* Let  $X = \{0, 1, 2\}$  and  $\sigma : X \times X \rightarrow [0, \infty)$  defined by

$$\begin{aligned} \sigma(0, 0) = \sigma(1, 1) = 0, \quad \sigma(2, 2) = \frac{23}{48} \\ \sigma(0, 1) = \sigma(1, 0) = \frac{1}{3}, \quad \sigma(0, 2) = \sigma(2, 0) = \frac{11}{24} \quad \text{and} \quad \sigma(1, 2) = \sigma(2, 1) = \frac{1}{2}. \end{aligned}$$

Then,  $(X, \sigma)$  is a complete dislocated metric space. Note that  $\sigma$  is not a partial metric on  $X$  because  $\sigma(2, 2) \geq \sigma(2, 0)$ .

Define the map  $T : X \rightarrow CB^\sigma(X)$  by

$$T0 = T1 = \{0\}, \quad T2 = \{0, 1\}$$

Note that it easy that  $Tx$  is bounded and is closed for all  $x \in X$  in the dislocated metric space  $(X, \sigma)$ .

We shall show that

$$H_\sigma(Tx, Ty) \leq \frac{8}{11} M(x, y), \quad \forall x, y \in X.$$

For this, we distinguish the following cases:

case1 :  $x, y \in \{0, 1\}$ . We have

$$H_\sigma(Tx, Ty) = \sigma(0, 0) = 0 \leq \frac{8}{11} \sigma(x, y) \leq \frac{8}{11} M(x, y).$$

case2 :  $x \in \{0, 1\}, y = 2$ . We have

$$\begin{aligned} H_\sigma(Tx, Ty) &= H_\sigma(\{0\}, \{0, 1\}) = \max\{\sigma(0, \{0, 1\}), \max\{\sigma(0, 0), \sigma(0, 1)\}\} \\ &= \max\{\min\{\sigma(0, 0), \sigma(0, 1)\}, \frac{1}{3}\} = \frac{1}{3} \end{aligned}$$

$$\leq \frac{8}{11}\sigma(x, y) \leq \frac{8}{11}M(x, y).$$

case3 :  $x = y = 2$ . We have

$$\begin{aligned} H_\sigma(Tx, Ty) &= H_\sigma(\{0, 1\}, \{0, 1\}) = \max\{\sigma(0, \{0, 1\}), \sigma(1, \{0, 1\})\} \\ &= \min\{\sigma(0, 1), \sigma(1, 1)\} = 0 \leq \frac{8}{11}\sigma(2, 2) \leq \frac{8}{11}M(2, 2). \end{aligned}$$

Thus, all the required hypotheses of Theorem 2 are satisfied. Then,  $T$  has a fixed point. Here,  $x = 0$  is the unique fixed point of  $T$ .

*Example 5.* Let  $X = \{0, 1, 2\}$  and  $\sigma : X \times X \rightarrow [0, \infty)$  defined by

$$\begin{aligned} \sigma(0, 0) &= 0, \quad \sigma(1, 1) = 3, \quad \sigma(2, 2) = 1 \\ \sigma(0, 1) &= \sigma(1, 0) = 7, \quad \sigma(0, 2) = \sigma(2, 0) = 3 \quad \text{and} \quad \sigma(1, 2) = \sigma(2, 1) = 4. \end{aligned}$$

Then,  $(X, \sigma)$  is a complete dislocated metric space. Note that  $\sigma$  is not a partial metric on  $X$  because  $\sigma(0, 1) \geq \sigma(2, 0) + \sigma(2, 1) - \sigma(2, 2)$ .

Define the map  $T : X \rightarrow CB^\sigma(X)$  by

$$T0 = T2 = \{0\} \quad \text{and} \quad T1 = \{0, 2\}.$$

Note that  $Tx$  is bounded and is closed for all  $x \in X$  in the dislocated metric space  $(X, \sigma)$ .

We shall show that

$$H_\sigma(Tx, Ty) \leq \frac{3}{4}M(x, y), \quad \forall x, y \in X.$$

For this, we consider the following cases:

case1 :  $x, y \in \{0, 2\}$ . We have

$$H_\sigma(Tx, Ty) = \sigma(0, 0) = 0 \leq \frac{3}{4}M(x, y).$$

case2 :  $x \in \{0, 2\}, y = 1$ . We have

$$\begin{aligned} H_\sigma(Tx, Ty) &= H_\sigma(\{0\}, \{0, 2\}) = \max\{\sigma(0, \{0, 2\}), \max\{\sigma(0, 0), \sigma(0, 2)\}\} \\ &= \max\{0, 3\} = 3 \leq \frac{3}{4}\sigma(x, y) \leq \frac{3}{4}M(x, y). \end{aligned}$$

case3 :  $x = y = 1$ . We have

$$\begin{aligned} H_\sigma(Tx, Ty) &= H_\sigma(\{0, 2\}, \{0, 2\}) = \max\{\sigma(0, \{0, 2\}), \sigma(2, \{0, 2\})\} \\ &= \min\{\sigma(0, 2), \sigma(2, 2)\} = 1 \leq \frac{3}{4}\sigma(1, 1) \leq \frac{3}{4}M(1, 1). \end{aligned}$$

Therefore, all the required hypotheses of Theorem 2 are satisfied. Here,  $x = 0$  is the unique fixed point of  $T$ .

*Example 6.* Let  $X = [0, 1]$  and  $\sigma : X \times X \rightarrow [0, \infty)$  defined by

$$\sigma(x, y) = x + y, \quad \forall x, y \in X$$

Then,  $(X, \sigma)$  is a complete dislocated metric space. Note that  $\sigma$  is not a partial metric on  $X$  because  $\sigma(x, x) > \sigma(x, y)$  for all  $x > y$ .  $\sigma$  is not also a metric on  $X$  since  $\sigma(1, 1) = 2$ .

Define the map  $T : X \rightarrow CB^\sigma(X)$  by

$$Tx = \{0, \frac{x^2}{1+x}\}, \quad \forall x \in X$$

It is easy that  $Tx$  is bounded and is closed for all  $x \in X$  in the dislocated metric space  $(X, \sigma)$ .

We shall show that

$$H_\sigma(Tx, Ty) \leq \frac{1}{2}M(x, y), \quad \forall x, y \in X.$$

For this, we consider the following cases:

case1 :  $x = y$ . We have

$$\begin{aligned} H_\sigma(Tx, Ty) &= \max\{\sigma(0, Tx), \sigma(\frac{x^2}{1+x}, Tx)\} \\ &= \max\{\min\{\sigma(0, 0), \sigma(0, \frac{x^2}{1+x})\}, \min\{\sigma(0, \frac{x^2}{1+x}), \sigma(\frac{x^2}{1+x}, \frac{x^2}{1+x})\}\} \\ &= \max\{0, \frac{x^2}{1+x}\} = \frac{x^2}{1+x} \leq x = \frac{1}{2}\sigma(x, x) \leq \frac{1}{2}M(x, y). \end{aligned}$$

case2 :  $x \neq y$ . Since  $\sigma$  is symmetric, we suppose  $x > y$ . We have

$$\begin{aligned} &H_\sigma(Tx, Ty) \\ &= H_\sigma(\{0, \frac{x^2}{1+x}\}, \{0, \frac{y^2}{1+y}\}) \\ &= \sup\{\max\{\sigma(0, \{0, \frac{y^2}{1+y}\}), \sigma(\frac{x^2}{1+x}, \{0, \frac{y^2}{1+y}\})\}, \\ &\max\{\sigma(0, \{0, \frac{x^2}{1+x}\}), \sigma(\frac{y^2}{1+y}, \{0, \frac{x^2}{1+x}\})\}\} \\ &= \max\{\sigma(\frac{x^2}{1+x}, \{0, \frac{y^2}{1+y}\}), \sigma(\frac{y^2}{1+y}, \{0, \frac{x^2}{1+x}\})\} \\ &= \max\{\frac{x^2}{1+x}, \frac{y^2}{1+y}\} = \frac{x^2}{1+x} \leq \frac{1}{2}x \leq \frac{1}{2}(x+y) = \frac{1}{2}\sigma(x, y) \leq \frac{1}{2}M(x, y). \end{aligned}$$

Thus, all the required hypotheses of Theorem 2 are satisfied. Here,  $x = 0$  is the unique fixed point of  $T$ .

Now, we provide an application on the research of a solution of an integral equation. For instance, using Corollary 6, we will prove the existence of a solution of the following integral equation.

$$x(t) = \int_a^b K(t, x(s)) ds, \quad (4.1)$$

where  $K : [a, b] \times \mathbb{R} \rightarrow [0, \infty)$  is a continuous nonnegative function.

Throughout this part, let  $X = C([a, b], [0, \infty))$  be the set of real nonnegative continuous functions defined on  $[a, b]$ . Take the dislocated metric  $\sigma : X \times X \rightarrow [0, \infty)$  defined by

$$\sigma(x, y) = \|x\|_\infty + \|y\|_\infty = \max_{s \in [a, b]} x(s) + \max_{s \in [a, b]} y(s) \quad \text{for all } x, y \in X.$$

Mention that  $\sigma$  is not partial metric on  $X$ . But, it is easy that  $(X, d)$  is a complete dislocated metric space.

Now, take the operator  $T : X \rightarrow X$  defined by

$$Tx(t) = \int_a^b K(t, x(s)) ds. \quad (4.2)$$

Mention that (4.1) has a solution if and only if the operator  $T$  has a fixed point.

The main result is

**Theorem 3.** *Assume that there exists  $\lambda \in (0, 1)$ , such that for every  $s \in [a, b]$  and  $u \in X$ , we have*

$$K(s, u(s)) \leq \frac{\lambda}{b-a} u(s).$$

*Then,  $T$  has a fixed point in  $X$ .*

*Proof.* For all  $x \in X$

$$\begin{aligned} |T(x)(t)| &\leq \int_a^b |K(t, s, x(s))| ds \\ &\leq \frac{\lambda}{b-a} \int_a^b x(s) ds \leq \lambda \|x\|_\infty. \end{aligned}$$

It follows that for all  $x, y \in X$

$$\sigma(Tx, Ty) \leq \lambda \sigma(x, y) \leq \lambda M(x, y). \quad (4.3)$$

Therefore, all the hypotheses of Corollary 6 are satisfied. Consequently,  $T$  has a fixed point, that is, (4.1) has a solution  $x \in X$ . □

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