

Minimizing Turtle-Shell Matrix Based Stego Image Distortion Using Particle Swarm Optimization

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Abstract

The purpose of data hiding is to embed secret messages into cover media so that the receiver will not be aware of the existence of these important messages. Recently, Chang et al. proposed a novel data hiding scheme based on turtle shells, which provided a good visual quality and an acceptable embedding capacity. However, the matrix that is used in the scheme based on turtle shells is not an optimal matrix. This means that the distortion of the image can be reduced further. In this paper, we propose a method that uses particle swarm optimization (PSO) to further reduce the distortion of the cover image based on turtle shells. Our experimental results confirmed that our scheme was efficient in finding an optimal replacement table and achieved a better visual quality of the cover image. Also, our scheme enhanced the security of scheme based on the turtle-shell matrix.

Keywords: Data hiding, GA, PSO, turtle shell

1 Introduction

With the rapid development and extensive application of the Internet, information security has been recognized as an important issue by many users. As a result, data encryption and data hiding, the two key techniques in the field of information security, also have received greater interest as topics of concern and research. Data encryption [3, 13] can alter a piece of clear text, or unencrypted information, into cipher text, or encrypted information. However, assailants are attracted easily by multimedia information after encrypting, and its content is totally transparent once the cipher-text is decrypted. Different from data encryption, data hiding is a technique that

hides secret information in an image to make the secret data inaudible or invisible for assailants. Due to this advantage, it is used extensively in many fields, such as electronic commerce, copyright protection, and image authentication.

Generally, data hiding techniques are conducted mainly in three domains, i.e., the compression domain, the frequency domain and the spatial domain. In the compression domain, vector quantization (VQ) [5, 8, 9, 12] is often used in data hiding schemes to obtain more space for embedding secret information. In 2003, Du and Hsu [9] proposed an adaptive algorithm to embed secret data into VQ compressed images. Later, Hu [12] and Chang et al. [8] improved the embedding capacity of VQ compressed images to embed secret data. Although these compression-domain data hiding schemes achieved higher hiding capability, the reduction in the quality of the images was a serious concern.

In the frequency domain, first, cover images are transformed by using a frequency-oriented mechanism such as the discrete cosine transformation (DCT) [6, 16], or the discrete wavelet transformation (DWT) [1, 17]. Then the secret data are embedded into the transformed coefficients. Although these data hiding schemes can obtain the stego images that have better visual quality, the embedding capacity of secret data still is not satisfactory because only a small number of coefficients are used to embed the secret data.

In the spatial domain, secret messages are embedded directly into the pixels to ensure a high embedding capacity of secret data. The most common method is least significant bit (LSB) replacement. In the traditional LSB method [2], the LSB of the cover image is replaced directly by a secret bit. In 2001, Wang [22] proposed a data hiding

ferent cases are considered according to the position of the extraction value in the turtle shell.

Case 1: If the extraction value is on the back of the turtle shell, the value that is equal to the secret digit that is to be embedded can be searched within this turtle shell. And the corresponding abscissa and ordinate of this value are used to substitute for the cover pixel pair (p_i, p_{i+1}) . However, if the extraction value is on the edge of the turtle shell, the searching range of the value that is equal to the secret digit will be the collection of the turtle shell that contains it.

Case 2: If the extraction value does not involve in any turtle shell, the searching range is a 3×3 sub-block on which this pixel pair is located. Any 3×3 sub-block also contains 8 different values from 0 to 7 because of the architectural property of the matrix.

Step 6. Repeat Steps 3 through 5 until all of the pixel pairs have been processed to embed the secret digit. In this way, a stego image is generated.

For example, suppose that two secret digits, i.e., 0 and 7, are to be embedded into two pixel pairs, i.e., (4, 4) and (0, 1), respectively. Figure 1 shows an example of the matrix based on turtle shells. The corresponding extraction value of pixel pair (4, 4) is 6, which, obviously, it is not equal to the secret digit 0 that is to be embedded. Because this extraction value is on the edge of three turtle shells, the closest 0 is searched within the three turtle shells with the red background in Figure 1. Then the pixel pair (4, 5) is taken as the new pixel pair to substitute for the original pixel pair. In the same way, the extraction value of the pixel pair (0, 1) does not involve in any turtle shell, so the searching range is a 3×3 sub-block with the red background in Figure 1. For this pair, the secret digit is 7 which is located in (2, 2). This pixel pair is replaced by (2, 2).

In the process of extracting secret data, taking each pixel pair of the stego image as a coordinate of the matrix, a corresponding extraction value in the matrix can be determined. It is the embedded secret digit. By converting each extraction value into binary bits in order, the original secret data can be recovered.

2.2 Particle Swarm Optimization

PSO, which was proposed by Kennedy and Eberhart in 1995 [19], is a global search algorithm. It was developed based on the social behavior of flocks of birds and schools of fish when searching for food. This technique has been used successfully in many fields as an optimization tool, such as estimating the distribution state [21] and dispatching reactive power [24].

In PSO, each individual of the population is called a particle, and it flies around in a multi-dimensional search space in order to find the optimal solution. The position

of a particle represents a candidate solution to the optimization problem at hand. Each particle searches for a better position in the search space by changing its velocity according to the rules that were inspired originally by behavioral models of flocks of birds. The position of the particle is updated as follows [19]:

$$x_i(t+1) = x_i(t) + v_i(t+1), \tag{1}$$

where $x_i(t+1)$ and $x_i(t)$ are two parameters that represent the updated position and the current position, respectively. The velocity of this particle is updated according to the following equation:

$$v_i(t+1) = wv_i(t) + c_1r_1(p_{best} - x_i(t)) + c_2r_2(g_{best} - x_i(t)), \tag{2}$$

where c_1 and c_2 are two acceleration coefficients, w is an inertia factor, r_1 and r_2 are two independent random numbers that are distributed uniformly in the range of $[0,1]$, and p_{best} and g_{best} are the local best particle and the global best particle, respectively.

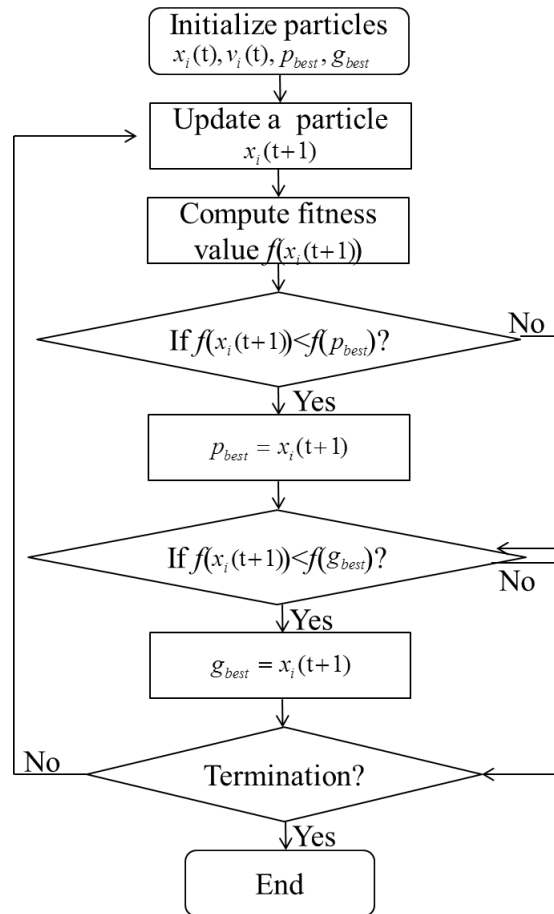


Figure 2: The flowchart of PSO

Figure 2 shows the basic flowchart of PSO, and the process of PSO is summarized as follows:

Step 1. Initialize a population of particles with random positions $x_i(t)$ and velocities $v_i(t)$ and compute the corresponding fitness values $f(x_i(t))$. Each initial particle is denoted as the local best particle p_{best} , and the particle that has the best fitness value is denoted as the global best particle g_{best} .

Step 2. Update the position of a particle $x_i(t + 1)$ according to its updated velocity $v_i(t + 1)$, which are determined by using Equations (1) and (2), respectively.

Step 3. Compute the fitness value of the updated particle $f(x_i(t + 1))$.

Step 4. Compare this new fitness value $f(x_i(t + 1))$ with $f(p_{best})$. If $f(x_i(t + 1)) < f(p_{best})$, p_{best} is replaced by $x_i(t + 1)$. Otherwise, p_{best} remains unchanged.

Step 5. Compare the current fitness value $f(x_i(t + 1))$ with $f(g_{best})$. If $f(x_i(t + 1)) < f(g_{best})$, g_{best} is replaced by $x_i(t + 1)$. Otherwise, g_{best} remains unchanged.

Step 6. If the terminal condition is met, then the best particle g_{best} and its fitness value are output. Otherwise, go back to Step 2.

3 Proposed Scheme

In the turtle-shell matrix, there are eight integers from 0 to 7 in a turtle shell or a 3×3 sub-block due to the architectural property of the matrix. In order to minimize the distortion of the cover image, it is important to determine the best table to replace the original eight integers. An example of substitution tables is shown in Figure 3. There is a total of 40,320 ways to sort these eight integers in total. So, it would take a lot of time to search all of the tables to find the best one. Thus, in this paper, we used PSO to search for the best table of the matrix.

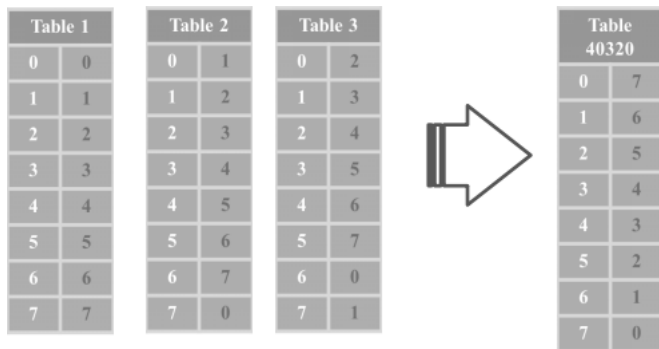


Figure 3: Substitution tables

3.1 Searching for The Best Replaceable Table Based on PSO

Input: A matrix M based on turtle shells, a cover image CI, secret messages S;

Output: A near optimal replaceable table T;

Step 1. The initial phase.

First, a population of particles is initialized randomly. Each particle represents a table that has 8 different values that range from 0 to 7. Table 1 shows an example of an initial particle, $P_i(t)=(x_{i1}(t),x_{i2}(t),\dots,x_{i8}(t))$, where $x_{ij}(t)$ represents the initial position of this particle and each position has a different value. The initial particle denotes its local best particle as p_{best} , and the particle that has the best fitness value is denoted as the global best particle g_{best} . The velocity of each position of a particle, $v_{ij}(t)$, is chosen randomly from 0 through 7.

Step 2. Update one position of a particle.

In order to keep a particle that has 8 different values, each position should be saved before this position is updated. The parameter $temp_{ij}$ is used to save the original values of these particles and it is shown in Equation (3).

$$temp_{ij} = temp_{ij}(t), i = 1, 2, \dots, n; j = 1, 2, \dots, 8. \quad (3)$$

The velocity of a particle is updated mainly according to three values, i.e., the local best particle, the global best particle and its particle value, which is shown in Equation (4).

$$v_{ij}(t + 1) = wv_{ij}(t) + c_1r_1(p_{best(ij)} - x_{ij}(t)) + c_2r_2(g_{best(j)} - x_i(t)), \quad (4)$$

where i is the i^{th} particle, j is the j^{th} position of this particle, c_1 and c_2 are two acceleration coefficients, both of which are set to 1, and w is an inertia factor that is set to 0.4.

Then the particle's position is updated as $x_{ij}(t + 1)$ according to its corresponding velocity. When the position of this particle is updated, the corresponding value should be limited in the range of 0 through 7. A modular function is used to achieve this purpose, as shown in Equation (5).

$$v_{ij}(t + 1) = (x_{ij}(t) + v_{ij}(t + 1)) \bmod 8. \quad (5)$$

If the new value has already existed in this particle, the old value will be replaced by the saved value $temp_{ij}$ that is shown in Equation (6). In other words, the two values of this particle in different positions are exchanged. In each circulation, only one position

Table 1: An example of an initial particle $P_i(t)$

| position | $x_{i1}(t)$ | $x_{i2}(t)$ | $x_{i3}(t)$ | $x_{i4}(t)$ | $x_{i5}(t)$ | $x_{i6}(t)$ | $x_{i7}(t)$ | $x_{i8}(t)$ |
|----------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|
| value | 2 | 5 | 7 | 1 | 6 | 3 | 4 | 0 |

of the particle is updated. In this way, this particle is updated as $P_{ij}(t+1)=(x_{i1}(t),x_{i2}(t),\dots,x_{ij}(t+1),\dots,x_{i8}(t))$.

$$x_{ik}(t+1) = \begin{cases} temp_{ij} & \text{if } x_{ij}(t+1) = x_{ik}(t) \\ & k = 1, 2, \dots, 8, k \neq j, \\ x_{ik}(t) & \text{otherwise} \end{cases} \quad (6)$$

Step 3. Compute the corresponding fitness value.

After getting the new updated particle, $P_i(t+1)$, it is used to replace the eight integers in the matrix that is from 0 through 7. Then, a new matrix is generated, and it is used to embed secret data into cover images. In order to judge whether the new matrix is better than the original matrix, the fitness function is used to measure the distortion between the cover image and the stego-image as shown in Equation (7).

$$f(P_i(t+1)) = \sum_{i=1}^H \sum_{j=1}^W (CI_{hw} - SI_{hw})^2, \quad (7)$$

where CI_{hw} and SI_{hw} are the pixel values of the original image and the cover image, respectively, and $H \times W$ is the size of the image.

For example, if we use the particle, $P_i(t) = (2, 5, 7, 1, 6, 3, 4, 0)$, in Table 1 to replace the original eight integers, $P_0(t) = (0, 1, 2, 3, 4, 5, 6, 7)$, one by one at corresponding positions, a new matrix will be obtained, as shown in Figure 4. The main architectural property of the matrix is not changed, which means that any 3×3 sub-block or a turtle shell still contains 8 different values from 0 through 7. Suppose that two secret digits, e.g., 0 and 7, must be embedded into two pixel pairs, i.e., (4, 4) and (0, 1), respectively. According to the theory mentioned in Subsection 2.1, the new pixel pairs will be (5, 4) and (0, 1) after embedding the secret digit based on the new matrix. The fitness value between the original two pixel pairs and the new pixel pairs is computed as $f(P_i(t))=(4-4)^2+(5-4)^2+(4-4)^2+(0-0)^2+(1-1)^2$ based on the new matrix. If the original matrix is used to hide the two secret digits by using the same pixel pairs, as shown in Figure 1, the new pixel pairs will be (4, 5) and (2, 2). The corresponding fitness value is computed as $f(P_0(t))=(4-4)^2+(5-4)^2+(4-4)^2+(2-0)^2+(2-1)^2$. Since $f(P_i(t))<f(P_0(t))$, the distortion associated with embedding the secret digits using the new matrix is less than that by using the original matrix.

Step 4. Update p_{best} and g_{best} .

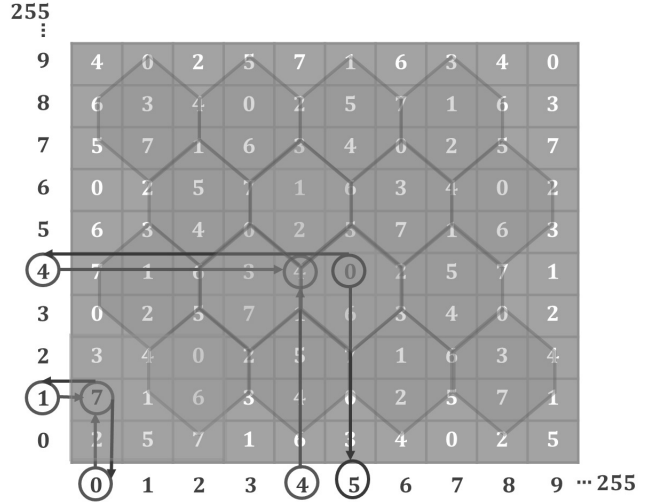


Figure 4: An example of the new matrix based on turtle shells

If $f(P_i(t+1))<f(p_{best})$, p_{best} will be updated by this new particle. Otherwise, p_{best} will remain unchanged. If $f(P_i(t+1))<f(g_{best})$, g_{best} will be updated by this new particle. Otherwise, g_{best} will remain unchanged.

Step 5. Termination.

If the terminal condition is encountered, then the best particle, g_{best} , is output. Otherwise, go back to Step 2. Here, the terminal condition is the maximum iteration time. After the near optimal table T is obtained, it is saved as a secret key for hiding and extracting the secret data.

3.2 Data Hiding Procedure

In this procedure, first, a new matrix is generated by replacing the original eight integers ranging from 0 through 7 in ascending order with the integers in the near optimal table. And then, each three bits of the secret messages are converted into a decimal digit ranging from 0 to 7. Selecting a pair of pixels from a cover image CI as a pair of coordinates of the new matrix, the secret digit is embedded in the same way that is used in the turtle shell scheme. After all of the pixel pairs are used for embedding secret digits, a stego-image SI is generated, and it is delivered, along with the near optimal table T , to a participant.

3.3 Data Extracting Procedure

In this procedure, first, the original matrix is generated using the original rule described in related work. By using the saved near optimal table T , a new matrix can be generated by replacing the original eight integers ranging from 0 to 7 in an ascending order with the integers in the best table. Then select a pair of pixels from the stego-image SI as a coordinates of the new matrix for extracting the secret digits. After all of the stego pixel pairs have been mapped into the new matrix, the original binary secret messages S can be restored from the extracted digits.

4 Experiments and Discussion

This section describes the experiments that were conducted on a group of 512×512 gray-level images that are shown in Figure 5. The simulation environment of our experiments was a PC with a 2.1 GHz CPU and 4 GB RAM. All schemes were implemented by using MATLAB 2013a. The population of particles was set to 8, and the maximum iteration times were set to 20 in our algorithm.

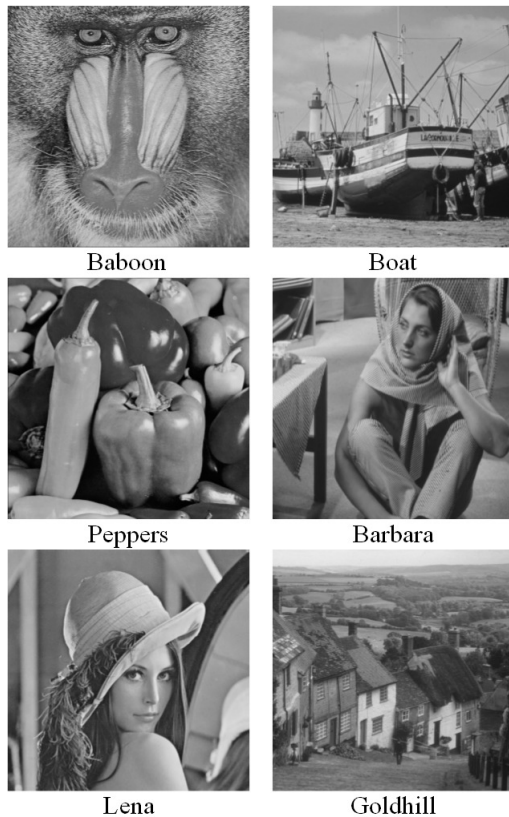


Figure 5: Six 515×512 gray images

The $PSNR$ was used to evaluate the visual quality of the image after embedding the secret data, which is shown in Equation (8). O_{hw} and C_{hw} denote the pixel values of the original image and the cover image, respectively, and

$H \times W$ denotes the size of the image.

$$PSNR = 10 \log_{10} \left(\frac{255^2}{MSE} \right), \quad (8)$$

where

$$MSE = \frac{1}{H \times W} \sum_{h=1}^H \sum_{w=1}^W (O_{hw} - C_{hw})^2. \quad (9)$$

In order to prove the efficiency of our algorithm, we used the exhaustive search and a genetic algorithm (GA) to search the best table. The exhaustive search was intended to identify the best table among the 40,320 tables. For the GA, a chromosome is presented as a table that contains 8 integers ranging from 0 to 7 and each integer represents a gene of this chromosome. A chromosome was selected according to its probability, which depended on the corresponding $PSNR$ value. The population size was set to 8. The crossover operator was implemented by exchanging four genes of two chromosomes. The probability of crossover was controlled by a parameter that was set to 0.8. The mutation operation was to exchange two genes of one chromosome and the probability of mutation was set to 0.001.

We used the scheme based on the turtle-shell matrix to hide the secret digits. There are 393,216 bits embedded into the cover image and the embedding capacity (EC) is 18.75% of the size of the cover image. Table 2 provides a comparison of various schemes. Three different methods were used to search the best table to obtain the minimum distortion of the turtle-shell matrix, i.e., the exhaustive search, GA, and PSO. From Table 2, it is apparent that exhaustive search had the best $PSNR$ values among the three schemes. Both GA and our scheme achieved near optimal results, and the average improvements of $PSNR$ values for the two schemes were 0.02 and 0.03dB, respectively, compared with the original scheme based on the turtle-shell matrix.

The main purpose of our scheme is to find a best table to obtain the minimum distortion of the turtle-shell matrix. Recently, Liu et al. [18] enhanced the embedding capacity by using the location table to develop the turtle shell-based scheme. However, the turtle-shell matrix used in Liu et al.'s scheme is also not optimal, meaning that our scheme can be used in [18] to obtain the minimum distortion of the turtle-shell matrix. The experimental results are shown in Table 3. There are 524,288 bits embedded into the cover image and the embedding capacity (EC) is up to 25% of the size of the cover image. From Table 3, it is obvious that our scheme achieves higher $PSNR$ values.

Table 4 shows the encoding time required of different schemes. Although [7] and [18] cost less time than other schemes, the turtle-shell matrix in their schemes is not optimal. The exhaustive search took the most time to find the best table among these methods, because all of the tables were tested. The GA took less time than the exhaustive search, but the $PSNR$ values were lower than those for the exhaustive search and PSO, as shown in

Table 2: Comparison of various schemes

| Images | Ref.[18] | | Exhaustive search | | GA | | PSO | |
|----------|----------|-------|-------------------|-------|--------|-------|--------|-------|
| | EC | PSNR | EC | PSNR | EC | PSNR | EC | PSNR |
| Baboon | 18.75% | 49.45 | 18.75% | 49.49 | 18.75% | 49.48 | 18.75% | 49.49 |
| Boat | 18.75% | 49.46 | 18.75% | 49.48 | 18.75% | 49.48 | 18.75% | 49.48 |
| Peppers | 18.75% | 49.44 | 18.75% | 49.49 | 18.75% | 49.48 | 18.75% | 49.49 |
| Barb | 18.75% | 49.45 | 18.75% | 49.49 | 18.75% | 49.48 | 18.75% | 49.49 |
| Lena | 18.75% | 49.48 | 18.75% | 49.51 | 18.75% | 49.49 | 18.75% | 49.50 |
| Goldhill | 18.75% | 49.46 | 18.75% | 49.49 | 18.75% | 49.47 | 18.75% | 49.48 |
| Average | 18.75% | 49.46 | 18.75% | 49.49 | 18.75% | 49.48 | 18.75% | 49.49 |

Table 3: Comparisons of the proposed scheme and [18]

| Images | Ref.[19] | | PSO | |
|----------|----------|-------|-----|-------|
| | EC | PSNR | EC | PSNR |
| Baboon | 25% | 45.55 | 25% | 45.57 |
| Boat | 25% | 45.55 | 25% | 45.58 |
| Peppers | 25% | 45.54 | 25% | 45.56 |
| Barb | 25% | 45.56 | 25% | 45.58 |
| Lena | 25% | 45.55 | 25% | 45.57 |
| Goldhill | 25% | 45.49 | 25% | 45.52 |
| Average | 25% | 45.54 | 25% | 45.56 |

Table 2. Compared with other methods, our PSO algorithm achieved near optimal results and more efficiently identified the near optimal table.

In addition, the near optimal table can be used as a secret key for the extraction of secret data. There were 40,320 tables to generate a matrix for the extraction of data extraction. If a receiver were to use a fake table to generate the matrix of turtle shells, the false secret data would be extracted by using the pixel pairs of the stego-image. Therefore, the security of the scheme based on the turtle-shell matrix was enhanced by using our method.

5 Conclusions

In this paper, we proposed a novel scheme to optimize data hiding based on turtle shells. First, we generated an original matrix based on the turtle shell scheme. Then PSO was used to search the near optimal table of the matrix. The integers in the matrix of the turtle shells are replaced by the near optimal table in order to minimize the distortion of the image. Two pixels of the cover image were used to embed secret digits according to this near optimal matrix. Our scheme has the same embedding capacity as the original data hiding scheme based on turtle shells, but it provides higher PSNR values. Also, the near optimal table can be used as a secret key for extracting data, which enhances the security of the scheme based on the turtle-shell matrix. The experimental results showed that the proposed scheme had better visual quality than

the original scheme based on the turtle-shell matrix and was efficient in finding the near optimal table.

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Table 4: Encoding time required of different schemes (s)

| Images | Ref.[18] | Ref.[19] | Exhaustive search | GA | PSO |
|----------|----------|----------|-------------------|---------|--------|
| Baboon | 12.35 | 25.47 | 54149.21 | 1284.19 | 175.21 |
| Boat | 13.14 | 24.52 | 59712.17 | 1230.43 | 171.74 |
| Peppers | 11.86 | 23.76 | 54038.28 | 1238.56 | 173.36 |
| Barb | 11.57 | 24.15 | 52824.63 | 1142.42 | 173.15 |
| Lena | 12.63 | 25.24 | 54856.31 | 1190.71 | 172.97 |
| Goldhill | 13.72 | 24.68 | 59942.15 | 1302.48 | 173.63 |
| Average | 12.55 | 24.64 | 55920.46 | 1231.47 | 173.34 |

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