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# Research article

# Mathematical modeling and impact analysis of the use of COVID Alert SA app

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# Appendix

# 1. Global stability of the disease free equilibrium

#### Theorem 3.3.2

Let the model be expressible in the form,  $\frac{d\mathbf{P}}{dt} = F(\mathbf{P}, \mathbf{Q})$ ,  $\frac{d\mathbf{Q}}{dt} = G(\mathbf{P}, \mathbf{Q})$ ,  $G(\mathbf{P}, 0) = 0$ , where  $\mathbf{P}$  denotes the non-disease classes and  $\mathbf{Q}$  is the disease classes of the model. Let  $U_0 = (\mathbf{P}^*, 0)$  be the fixed point of the model, then  $U_0$  is globally asymptotically stable (g.a.s) if and only if  $\mathcal{R}_0 < 1$  and the following conditions are satisfied

 $C_1: \frac{d\mathbf{P}}{dt} = F(\mathbf{P}, 0), \mathbf{P}^* \text{ is globally asymptotically stable.}$  $C_2: G(\mathbf{P}, \mathbf{Q}) = Z\mathbf{Q} - \widetilde{G}(\mathbf{P}, \mathbf{Q}), \widetilde{G}(\mathbf{P}, \mathbf{Q}) \ge 0 \text{ for } (\mathbf{P}, \mathbf{Q}) \in \Omega_n \text{ where } Z = \frac{\partial G}{\partial \mathbf{Q}} U_0.$ 

#### Proof

From the model system (2) – (7), we find that  $\mathbf{P} = (S, R)$  and  $\mathbf{Q} = (E_A, E, T, I)^T$ . The DFE of the model is  $U_0 = (\mathbf{P}^*, 0) = (\frac{\Lambda}{\mu}, 0, 0, 0, 0, 0)$  as defined by (12). The point  $U_0 = (\mathbf{P}^*, 0)$  is g.a.s if  $\mathcal{R}_0 < 1$ , thus  $\frac{d\mathbf{P}}{dt} = F(\mathbf{P}, 0) = [\Lambda - \mu S, 0]^T$  hence condition  $C_1$  is easily satisfied. For condition  $C_2$ 

$$Z\mathbf{Q} = \begin{pmatrix} -(\alpha_1 + \mu) & 0 & 0 & 0\\ 0 & -(\alpha_2 + \mu) & 0 & 0\\ \alpha_1 & \alpha_2 \rho & -(\psi + \phi + \mu) & 0\\ 0 & \alpha_2(1 - \rho) & \psi & -(\lambda + \mu) \end{pmatrix} \begin{pmatrix} E_A \\ E \\ T \\ I \end{pmatrix}$$
(1)

and

$$G(\mathbf{P}, \mathbf{Q}) = \begin{pmatrix} \beta \varepsilon IS - (\alpha_1 + \mu)E_A \\ \beta(1 - \varepsilon)IS - (\alpha_2 + \mu)E \\ \alpha_1 E_A + \alpha_2 \rho E - (\psi + \phi + \mu)T \\ \psi T + \alpha_2 (1 - \rho)E - (\lambda + \mu)I \end{pmatrix}.$$
(2)

From the identity that  $G(\mathbf{P}, \mathbf{Q}) = Z\mathbf{Q} - \widetilde{G}(\mathbf{P}, \mathbf{Q})$ , then it implies using (1) and (2) we have

$$\widetilde{G}(\mathbf{P}, \mathbf{Q}) = \begin{pmatrix} \beta \varepsilon I \left(1 - \frac{S}{N}\right) \\ \beta (1 - \varepsilon) I \left(1 - \frac{S}{N}\right) \\ 0 \\ 0 \end{pmatrix}$$
(3)

where  $\widetilde{G}(\mathbf{P}, \mathbf{Q}) \ge 0$  if  $\left(1 - \frac{s}{N}\right) \ge 0$ . We note that since,  $S \le N$  then  $\frac{s}{N} \le 1$  and hence  $\left(1 - \frac{s}{N}\right) \ge 0$ . Further more, all the model parameters and the state variables are defined to be positive and thus  $\widetilde{G}(\mathbf{P}, \mathbf{Q}) \ge 0$  holds for the model satisfying the condition  $C_2$ . Based on the proof, we conclude that the DFE of the model is globally asymptotically stable whenever  $\mathcal{R}_0 < 1$ .

#### 2. Labeled contour plots for sensitivity analysis

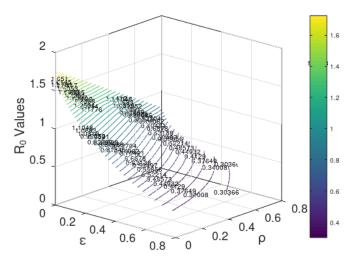


Figure S1. Labeled Contour plot visualization for Figure 3.

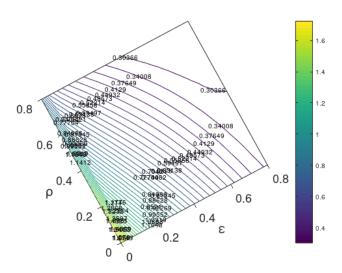


Figure S2. Labeled Contour plot visualization for Figure 3.



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