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Research article

Mathematical modeling and impact analysis of the use of COVID Alert SA app

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Appendix

1. Global stability of the disease free equilibrium

Theorem 3.3.2

Let the model be expressible in the form, $\frac{dP}{dt} = F(P, Q)$, $\frac{dQ}{dt} = G(P, Q)$, $G(P, 0) = 0$, where **P** notes the non-disease classes and **O** is the disease classes of the model. Let $U_1 = (P^* \ 0)$ be the denotes the non-disease classes and **Q** is the disease classes of the model. Let $U_0 = (\mathbf{P}^*, 0)$ be the fixed point of the model, then U_0 is globally asymptotically stable (g, a, s) if and only if $\mathcal{R}_s < 1$ and th fixed point of the model, then U_0 is globally asymptotically stable (g.a.s) if and only if $\mathcal{R}_0 < 1$ and the following conditions are satisfied

 C_1 : $\frac{d\mathbf{P}}{dt} = F(\mathbf{P}, 0)$, \mathbf{P}^* is globally asymptotically stable.
C + *C*(**P O**) = **70** \widetilde{C} (**P O**) = 0 for (**P O**) C_2 : $G(\mathbf{P}, \mathbf{Q}) = Z\mathbf{Q} - \widetilde{G}(\mathbf{P}, \mathbf{Q}), \widetilde{G}(\mathbf{P}, \mathbf{Q}) \ge 0$ for $(\mathbf{P}, \mathbf{Q}) \in \Omega_n$ where $Z = \frac{\partial G}{\partial \mathbf{Q}} U_0$.

Proof

From the model system (2) – (7), we find that $\mathbf{P} = (S, R)$ and $\mathbf{Q} = (E_A, E, T, I)^T$. The DFE of the model
is $U_s = (\mathbf{P}^* \cap \mathbf{Q}^* \cap \mathbf{Q}^*) = (\mathbf{Q}^* \cap \mathbf{Q}^*) \cap \mathbf{Q}^* \cap \mathbf{Q}^*$ as $\mathbf{Q} = (\mathbf{Q}^* \cap \mathbf{Q}^*) \cap \mathbf{Q}$ is $U_0 = (\mathbf{P}^*, 0) = (\frac{\Delta}{\mu}, 0, 0, 0, 0, 0)$ as defined by (12). The point $U_0 = (\mathbf{P}^*, 0)$ is g.a.s if $\mathcal{R}_0 < 1$, thus $\frac{dP}{dt} = F(\mathbf{P}, 0) = [\Lambda - \mu S, 0]^T$ hence condition C_1 is easily satisfied. For condition C_2

$$
Z\mathbf{Q} = \begin{pmatrix} -(\alpha_1 + \mu) & 0 & 0 & 0 \\ 0 & -(\alpha_2 + \mu) & 0 & 0 \\ \alpha_1 & \alpha_2 \rho & -(\psi + \phi + \mu) & 0 \\ 0 & \alpha_2 (1 - \rho) & \psi & -(\lambda + \mu) \end{pmatrix} \begin{pmatrix} E_A \\ E \\ T \\ I \end{pmatrix}
$$
(1)

and

$$
G(\mathbf{P}, \mathbf{Q}) = \begin{pmatrix} \beta \varepsilon I S - (\alpha_1 + \mu) E_A \\ \beta (1 - \varepsilon) I S - (\alpha_2 + \mu) E \\ \alpha_1 E_A + \alpha_2 \rho E - (\psi + \phi + \mu) T \\ \psi T + \alpha_2 (1 - \rho) E - (\lambda + \mu) I \end{pmatrix}.
$$
 (2)

From the identity that $G(\mathbf{P}, \mathbf{Q}) = Z\mathbf{Q} - \widetilde{G}(\mathbf{P}, \mathbf{Q})$, then it implies using [\(1\)](#page-1-0) and [\(2\)](#page-1-1) we have

$$
\widetilde{G}(\mathbf{P}, \mathbf{Q}) = \begin{pmatrix} \beta \varepsilon I \left(1 - \frac{S}{N}\right) \\ \beta (1 - \varepsilon) I \left(1 - \frac{S}{N}\right) \\ 0 \\ 0 \end{pmatrix}
$$
\n(3)

where $\widetilde{G}(\mathbf{P}, \mathbf{Q}) \ge 0$ if $\left(1 - \frac{S}{\lambda}\right)$
Further more all the model $\left(\frac{S}{N}\right) \geq 0$. We note that since, $S \leq N$ then $\frac{S}{N} \leq 1$ and hence $\left(1 - \frac{S}{N}\right)$ $\frac{S}{N}$ \geq 0. Further more, all the model parameters and the state variables are defined to be positive and thus $\widetilde{G}(\mathbf{P}, \mathbf{Q}) \ge 0$ holds for the model satisfying the condition C_2 . Based on the proof, we conclude that the DFE of the model is globally asymptotically stable whenever $\mathcal{R}_0 < 1$.

2. Labeled contour plots for sensitivity analysis

Figure S1. Labeled Contour plot visualization for Figure 3.

Figure S2. Labeled Contour plot visualization for Figure 3.

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