OpenMP ARB, 2007

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OpenMP 3.0

OpenMP ARB

Mark Bull SC07, November, 2007, Reno

Tasks

- Adding tasking is the biggest addition for 3.0
- Worked on by a separate subcommittee
 - led by Jay Hoeflinger at Intel
- Re-examined issue from ground up
 - quite different from Intel taskq's

General task characteristics

- A task has
 - Code to execute
 - A data environment (it owns its data)
 - An assigned thread that executes the code and uses the data
- Two activities: packaging and execution
 - Each encountering thread packages a new instance of a task (code and data)
 - Some thread in the team executes the task at some (potentially later) time

Definitions

- Task construct task directive plus structured block
- Task the package of code and instructions for allocating data created when a thread encounters a task construct
- Task region the dynamic sequence of instructions produced by the execution of a task by a thread

Tasks and OpenMP

- Tasks have been fully integrated into OpenMP
- Key concept: OpenMP has always had tasks, we just never called them that.
 - Thread encountering parallel construct packages up a set of implicit tasks, one per thread.
 - Team of threads is created.
 - Each thread in team is assigned to one of the tasks (and tied to it).
 - Barrier holds original master thread until all implicit tasks are finished.
- We have simply added a way to create a task explicitly for the team to execute.
- Every part of an OpenMP program is part of one task or another!

task Construct

where clause can be one of:

```
if (expression)
untied
shared (list)
private (list)
firstprivate (list)
default( shared | none )
```

The if clause on a task construct

- When the if clause argument is false
 - The current task region is suspended.
 - The new task is executed immediately by the encountering thread.
 - The suspended task region is not resumed until the new task is complete.
 - The data environment is still local to the new task...
 - ...and it's still a different task with respect to synchronization.
- It's a user directed optimization
 - when the cost of deferring the task is too great compared to the cost of executing the task code
 - to control cache and memory affinity

When/where are tasks complete?

- At barriers, explicit or implicit
 - applies to all tasks generated in the current parallel region up to the barrier
 - matches user expectation
- At a taskwait directive
 - applies only to child tasks of the current task, not to further "descendants"

Example – parallel pointer chasing using tasks

```
#pragma omp parallel
  #pragma omp single private(p)
    p = listhead ;
                           p is firstprivate by default here
    while (p) {
       #pragma omp task
                process (p)
       p=next (p);
```

Example – parallel pointer chasing on multiple lists using tasks

```
#pragma omp parallel
   #pragma omp for private(p)
   for ( int i =0; i <numlists ; i++) {</pre>
       p = listheads [ i ];
       while (p ) {
       #pragma omp task
           process (p)
       p=next (p );
```

Example: tree traversal, children before parents

```
void traverse(node *p) {
   if (p->left)
        #pragma omp task
        traverse(p->left);
   if (p->right)
        #pragma omp task
        traverse(p->right);
        #pragma omp taskwait
        process(p->data);
```

Parent task suspended until child tasks complete

Task switching

- Certain constructs have task scheduling points at defined locations within them
- When a thread encounters a task scheduling point, it is allowed to suspend the current task and execute another (called task switching)
- It can then return to the original task and resume

Task switching example

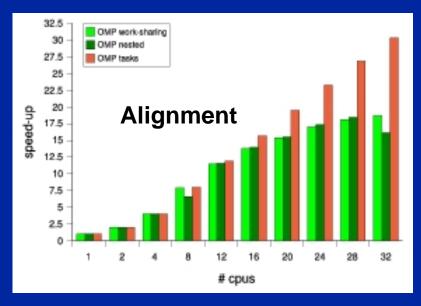
```
#pragma omp single
{
  for (i=0; i<ONEZILLION; i++)
     #pragma omp task
     process(item[i]);
}</pre>
```

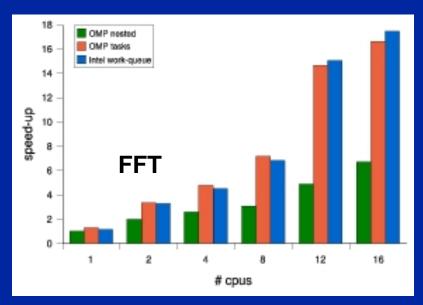
- Too many tasks generated in an eye-blink
- Generating task will have to suspend for a while
- With task switching, the executing thread can:
 - execute an already generated task (draining the "task pool")
 - dive into the encountered task (could be very cache-friendly)

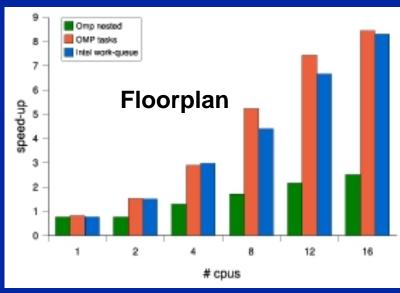
Thread switching

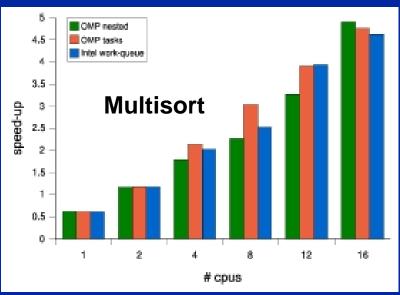
- Eventually, too many tasks are generated
- Generating task is suspended and executing thread switches to a long and boring task
- Other threads get rid of all already generated tasks, and start starving...
- With thread switching, the generating task can be resumed by a different thread, and starvation is over
- Too strange to be the default: the programmer is responsible!

Performance Results 1

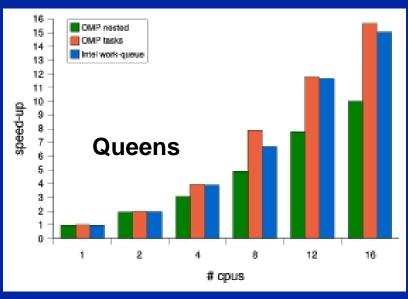


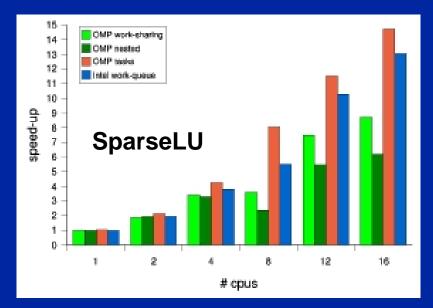


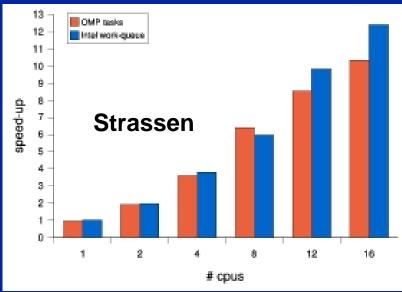




Performance Results 2







Reference Implementation

• URL:

http://mercurium.pc.ac.upc.edu/nanos

 Made by Xavier Teruel, Roger Ferrer, Alex Duran, Eduard Ayguadé, Xavier Martorell

Conclusions on tasks

- Enormous amount of work by many people
- Tightly integrated into 2.5 spec
- Flexible model for irregular parallelism
- Provides balanced solution despite often conflicting goals
- Appears that performance can be reasonable

Better support for nested parallelism

- Per-thread internal control variables
 - Allows, for example, calling omp_set_num_threads() inside a parallel region.
 - Controls the team sizes for next level of parallelism
- Library routines to determine depth of nesting, IDs of parent/grandparent etc. threads, team sizes of parent/grandparent etc. teams

```
omp_get_level()
omp_get_active_level()
omp_get_ancestor_thread_num(level)
omp_get_team_size(level)
```

N.B. new defn. of active parallel region: a parallel region executed by more than one thread

Parallel loops

• Guarantee that this works:

```
!$omp do schedule(static)
do i=1,n
    a(i) = ....
end do
!$omp end do nowait
!$omp do schedule(static)
do i=1,n
    .... = a(i)
end do
```

Loops (cont.)

Allow collapsing of perfectly nested loops

Will form a single loop and then parallelise that

Loops (cont.)

- Made schedule(runtime) more useful
 - can get/set it with library routines

```
omp_set_schedule()
omp_get_schedule()
```

- allow implementations to implement their own schedule kinds
- Added a new schedule kind AUTO which gives full freedom to the runtime to determine the scheduling of iterations to threads.
- Allowed unsigned ints and C++ RandomAccessIterators as loop control variables in parallel loops

Portable control of threads

 Added environment variable to control the size of child threads' stack

OMP_STACKSIZE

 Added environment variable to hint to runtime how to treat idle threads

OMP_WAIT_POLICY

ACTIVE keep threads alive at barriers/locks

PASSIVE try to release processor at barriers/locks

 Added environment variable and runtime routines to get/set the maximum number of active levels of nested parallelism

```
OMP_MAX_NESTED_LEVELS
omp_set_max_nested_levels()
omp_get_max_nested_levels()
```

 Added environment variable to set maximum number of threads in use

```
OMP_THREAD_LIMIT
omp_get_thread_limit()
```

Odds and ends

- Disallowed use of the original variable as master thread's private variable
- Made it clearer where/how private objects are constructed/destructed
- Relaxed some restrictions on allocatable arrays
- Plugged some minor gaps in memory model
- Allowed C++ static class members to be threadprivate
- Minor fixes and clarifications to 2.5

Summary

OpenMP 3.0 is almost ready

Been a lot of hard work by a lot of people

• We hope you like it: let us know via the public comment process what you think!

Acknowledgements

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