

Understanding 5Gs Signal-Processing Demands: Device Centric Network Cooperation for 5G and Beyond: Theory and Algorithms

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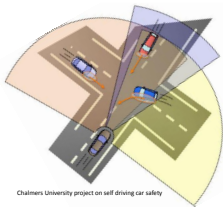
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Network Coordination

Coordination and cooperation have emerged as central concepts in many types of **networks**

- Robots networks (autonomous drones, smart factory, plant probes, etc.)
- Transportation networks (driver less cars, truck trains, etc.)
- Sensor networks
- Processor networks
- Energy (Smart Grids) networks
- **Wireless networks**



Cooperation Scenarios in Wireless Network (5G and beyond)

Cooperation turns a **resource usage conflict** into a **system gain**, for instance in following scenarios:

- 1 Coordinated Multipoint (CoMP) transmission
- 2 Power control for interference reduction
- 3 Spectrum sublicensing (coordinated cognitive radios)
- 4 Beam alignment for massive MIMO in mmwave bands
- 5 Dynamic content caching
- 6 Inter-cell Interference Coordination (ICIC and eICIC)
- 7 Coordinated power transfer for battery life extension (IoT)
- 8 and more...

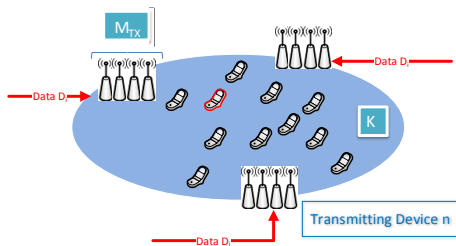
Joint Processing CoMP

- n otherwise-interfering base stations jointly combine their nM_{TX} antenna elements over ideal backhaul
- K users are served simultaneously, free of interference (with K up to nM_{TX})

$$\text{Spatial Multiplexing Gain} = nM_{TX}$$

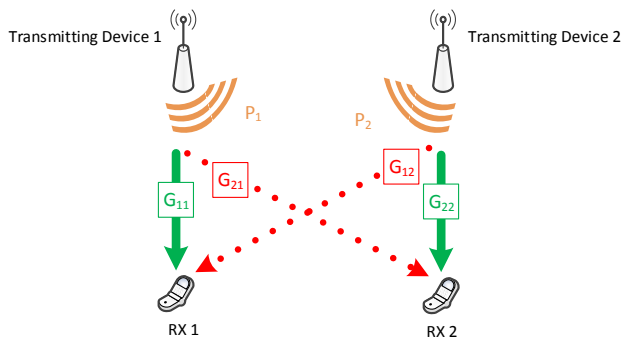
- **Challenges:**

- All base stations must be **synchronized** and acquire knowledge of **all served users' channels**
- All base stations must acquire knowledge of **all served users' channels**



Power Control for Interference Reduction

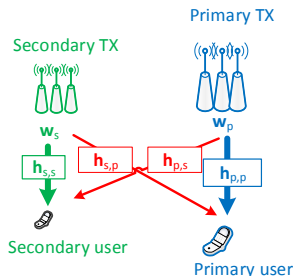
- Neighboring base stations interfere and coordinate their power control policies
- Power control is subject to a maximum power constraint
- Optimum policy aims at maximizing the overall throughput, i.e. just the right amount of interference is generated
- **Challenges:** Coordination **requires knowledge of all channel strengths G_{ij}**



Spectrum Sub-licensing using Cognitive Radio Beamforming

- A primary operator (p) is sub-licensing its spectrum to a secondary operator (s)
- Both operator base stations control a beamforming vector

$$\text{Maximize } \underbrace{\mathbb{E}[R_s]}_{\text{Secondary}} \quad \text{subject to } \underbrace{\mathbb{E}[R_p]}_{\text{Primary}} \geq \tau > 0$$

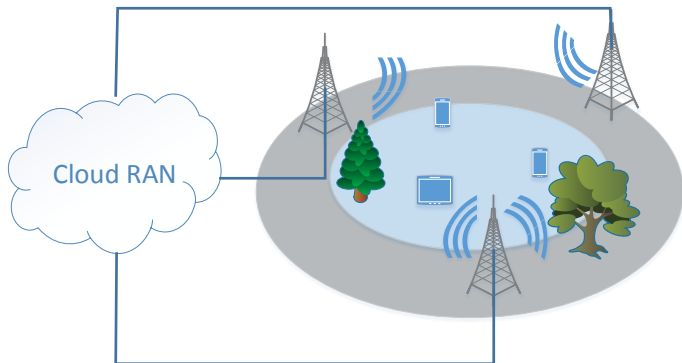


➔ Most common approach: Interference temperature constraint $I_{\text{primary}} \leq \tau$

- **Challenge:** Full beamforming coordination requires centralized knowledge of primary and secondary channels.

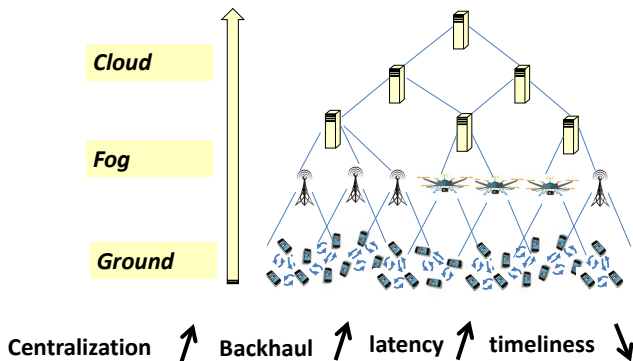
Centralized VS Decentralized Signal Processing Architectures in 5G and Beyond

- **Cloud RAN** is popular, pushes for more centralization
- Centralized decision making is conceptually **simple**
- Coordination is **easy**
- Mobile service providers **love it**



Centralized vs. Decentralized Signal Processing Architectures in 5G and Beyond

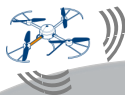
- Centralization leads to **expensive** deployment (road digging, fiber,..)
- Backhaul architectures can be of **diverse nature**
- Curse of **dimension** (IoT: billions of devices)
- More centralization increases **latency**, decreases timeliness of **CSI**



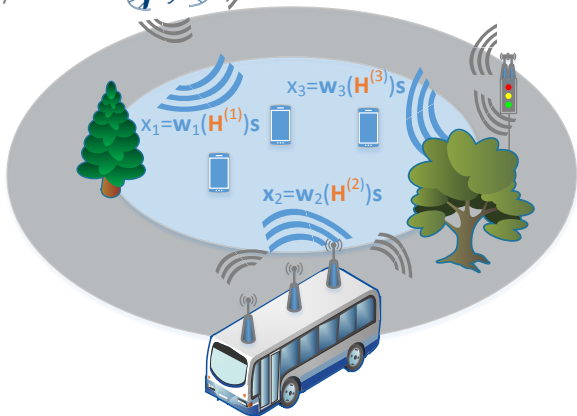
Cooperation in LTE with Heterogeneous Backhaul: A Device Centric Perspective



sharing/caching of user's data symbols



Imperfect CSI sharing



CSI for Device-Centric Cooperation

- CSI affected by mobility, limited training and feedback
- CSI exchange is **not** free
 - ➔ Devices are **myopic**: They know **better** what is **close**
 - ➔ Need for local (**device-centric**) decision-making

CSI for Device-Centric Cooperation

- CSI affected by mobility, limited training and feedback
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Today's questions:

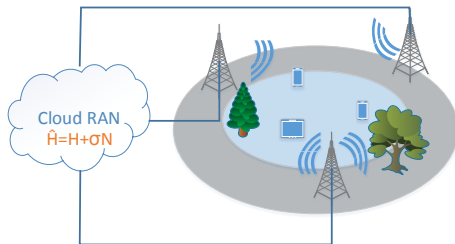
- 1 **Distributed** information models?
- 2 **Price** of myopia?
- 3 **Myopia-robust** approaches?

Outline

- 1 Distributed Information Models
- 2 Device-Centric Cooperation: Formulation and methods
- 3 Applications of Team Decision to Device-Centric Cooperation

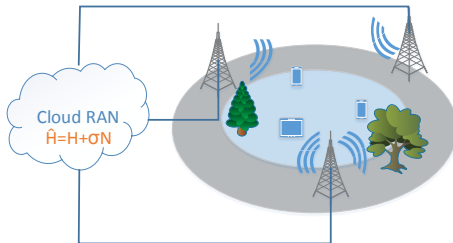
Centralized VS Distributed Channel State Information

- **Centralized (TX Independent)**

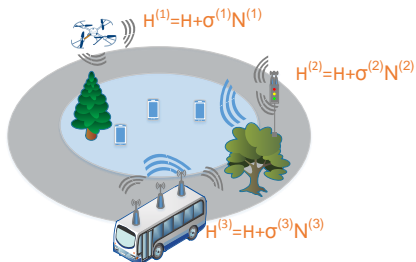


Centralized VS Distributed Channel State Information

- Centralized (TX Independent)



- Distributed (TX Dependent)



Outline

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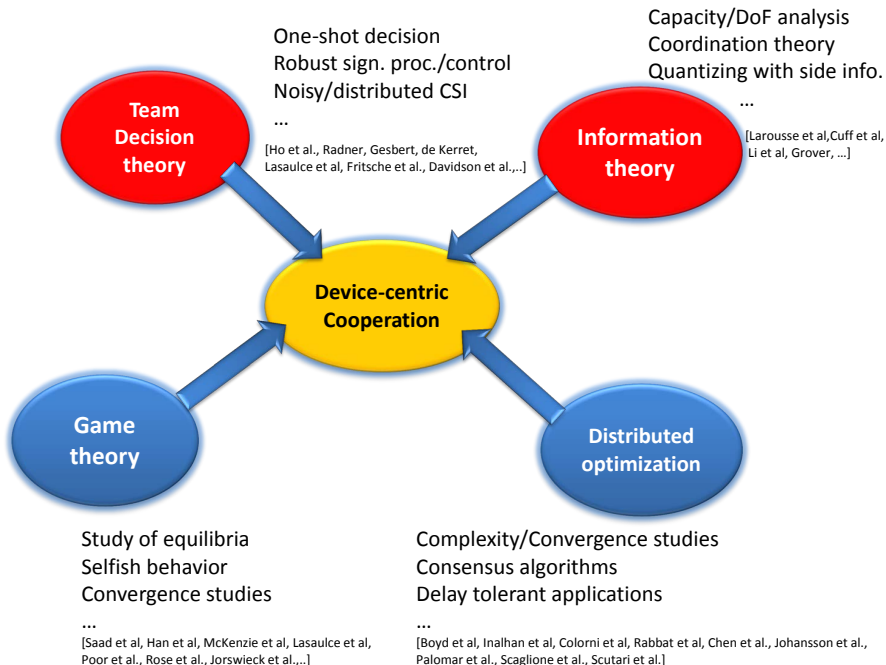
Device-centric Coordination \iff Team Decision

K devices cooperate to maximize network performance f

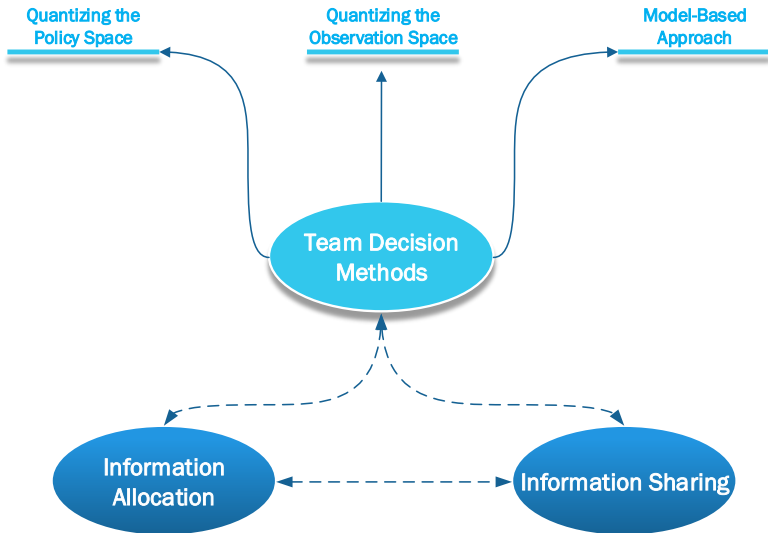
$$(\mathbf{s}_1^*, \dots, \mathbf{s}_K^*) = \underset{\mathbf{s}_1, \dots, \mathbf{s}_K}{\operatorname{argmax}} \mathbb{E}_{\mathbf{x}, \mathbf{x}^{(1)}, \dots, \mathbf{x}^{(K)}} \left[f \left(\mathbf{x}, \overbrace{\mathbf{s}_1}^{\text{Decision policy at device 1}} \left(\underbrace{\mathbf{x}^{(1)}}_{\text{Observation at device 1}} \right), \dots, \mathbf{s}_K(\mathbf{x}^{(K)}) \right) \right]$$

where

- $\mathbf{x} \in \mathbb{C}^m$: System State (for wireless: $\mathbf{x} = \mathbf{H}$)
- $\mathbf{x}^{(j)} \in \mathbb{C}^m$: Observation of the state of the world \mathbf{x} at device j
- $\mathbf{s}_j : \mathbb{C}^m \rightarrow \mathcal{A}_j \subset \mathbb{C}^{d_j}$: Decision policy at device j
- $P_{\mathbf{x}, \mathbf{x}^{(1)}, \dots, \mathbf{x}^{(K)}}$: Joint probability distribution of the channel and the estimates



One-Shot Team Decision: Algorithm Design



Outline

- 1 Distributed Information Models
- 2 Device-Centric Cooperation: Formulation and methods
- 3 Applications of Team Decision to Device-Centric Cooperation**

I/ First Application: Joint Processing CoMP

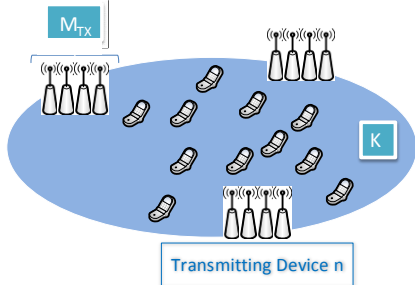
- Find precoders $\{\mathbf{w}_j\}_{j=1}^K$:

$$(\mathbf{w}_1^*, \dots, \mathbf{w}_K^*) = \underset{(\mathbf{w}_1, \dots, \mathbf{w}_K) \in \mathcal{W}}{\operatorname{argmax}} \mathbb{E}[R(\mathbf{H}, \mathbf{w}_1(\hat{\mathbf{H}}^{(1)}), \dots, \mathbf{w}_K(\hat{\mathbf{H}}^{(K)}))]$$

- \mathbf{w}_j being the precoder at TX j

$$\mathbf{w}_j : \begin{array}{l} \mathbb{C}^{N_{\text{tot}} \times M_{\text{tot}}} \rightarrow \mathbb{C}^{M_j \times d_{\text{tot}}} \\ \hat{\mathbf{H}}^{(j)} \quad \mapsto \quad \mathbf{w}_j(\hat{\mathbf{H}}^{(j)}) \end{array}$$

$$\mathbf{T} = [\mathbf{T}_1 \quad \dots \quad \mathbf{T}_K] = \begin{bmatrix} \mathbf{w}_1(\hat{\mathbf{H}}^{(1)}) \\ \vdots \\ \mathbf{w}_K(\hat{\mathbf{H}}^{(K)}) \end{bmatrix}$$



K and M_{TX} grow large at the same rate $\beta \triangleq \lim_{M,K \rightarrow \infty} \frac{M}{K} \geq 1$: Asymptotic analysis

Large Random Matrix Theory in Wireless Networks [A Short Digression]

Example

Let \mathbf{A} be the matrix of size $n \times n$ defined as

$$\mathbf{A} \triangleq \begin{bmatrix} 0 & \pm 1 & \pm 1 \\ \pm 1 & 0 & \pm 1 \\ \pm 1 & \pm 1 & 0 \end{bmatrix}$$

➔ Convergence of the eigenvalue distribution

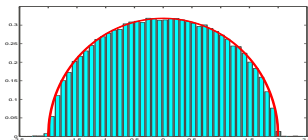


Fig. 1.4 The semicircle law density function (1.18) compared with the histogram of the average of 100 empirical density functions for a Wigner matrix of size $n = 100$.

Figure: from [Tulino and Verdu, 2004]

- Application to Wireless Networks for more than 10 years: Asymptotic expressions for SINR, rate, power, BER,...
 - ➔ Made more relevant by Massive MIMO technology!
- Many books and lecture notes [Tulino and Verdu, 2004] [Couillet and Debbah, 2011]

Model-Based Optimization: Introduction of Regularized Zero Forcing

Modelization of the precoder using Regularized Zero Forcing:

$$w_j(\hat{\mathbf{H}}^{(j)}) = \underbrace{[\mathbf{0}_j, 1, \mathbf{0}_{M-j}]}_{\text{Selects the } j \text{ th row}} \underbrace{\left((\hat{\mathbf{H}}^{(j)})^H \hat{\mathbf{H}}^{(j)} + M\gamma^{(j)} \mathbf{I}_M \right)^{-1} (\hat{\mathbf{H}}^{(j)})^H \frac{\sqrt{P}}{\sqrt{\Psi^{(j)}}}}_{\text{Robust channel inversion}}$$

- **Intuition:** Distributed (regularized) Channel Inversion
 - Tikhonov Regularization of channel inversion [Golub et al., 2016], widely used [Shenouda and Davidson, 2006]
- ➔ How to find optimization parameter $\gamma^{(j)}$ at TX j ?

Optimization of the Regularization Parameter $\gamma^{(j)}$

- **Myopic** regularization

$$\gamma^{(j), \text{Myopic}} = \operatorname{argmax}_{\gamma \in \mathbb{R}} \mathbb{E}[R(\hat{\mathbf{H}}^{(j)}, \dots, \hat{\mathbf{H}}^{(j)})]$$

- **Team-Based** regularization

$$(\gamma^{(1),*}, \dots, \gamma^{(n),*}) = \operatorname{argmax}_{(\gamma^{(1)}, \dots, \gamma^{(n)})} \mathbb{E}[R(\hat{\mathbf{H}}^{(1)}, \dots, \hat{\mathbf{H}}^{(n)})].$$

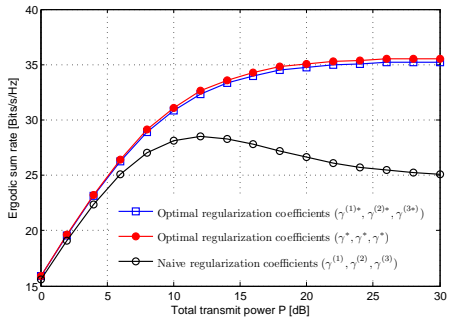
- **Low Complexity Team-Based** regularization (Equal coefficient at all TXs)

$$(\gamma^*, \dots, \gamma^*) = \operatorname{argmax}_{(\gamma, \dots, \gamma)} \mathbb{E}[R(\hat{\mathbf{H}}^{(1)}, \dots, \hat{\mathbf{H}}^{(n)})].$$

➡ RMT allows to get rid of the expectation operator in the optimization

Performance of CoMP Transmission with Distributed CSIT

Antenna Setting	n	3
	K	30
	M	30
Channel Modeling	Fading	Rayleigh
	Pathloss	Uniform
CSIT Configuration	$(\sigma_k^{(1)})^2$	0.01
	$(\sigma_k^{(2)})^2$	0.16
	$(\sigma_k^{(3)})^2$	0.49
	$\rho_k^{(j,j')}$	0.1



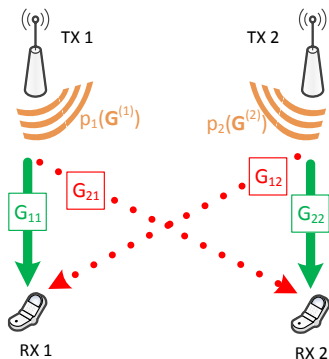
II/ Second Application: On-Off Power Control

- Power control to reduce interference of two interfering wireless links:

$$(p_1^*, p_2^*) = \underset{(p_1, p_2) \in \mathcal{P}}{\operatorname{argmax}} [R(p_1(\underbrace{\mathbf{G}^{(1)}}_{\text{Local Channel at device 1}}), p_2(\mathbf{G}^{(2)}))]$$

where p_j is the power control function

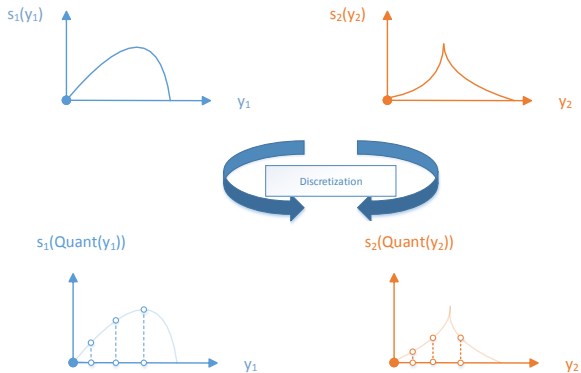
$$p_j : \begin{array}{l} \mathbb{R}_+^4 \rightarrow \{P_j^{\min}, P_j^{\max}\} \\ \mathbf{G}^{(j)} \mapsto p_j(\mathbf{G}^{(j)}) \end{array}$$



Discretization of the Observation Space [de Kerret and Gesbert, 2016, SPAWC]

- Replace the strategy $p_j(\hat{\mathbf{G}}^{(j)})$ by $p_j(\underbrace{\text{Quant}(\hat{\mathbf{G}}^{(j)})}_{\text{belongs to a codebook of size } n})$

➔ Optimizing a function over a **discrete set** is more easy than a **continuous one**



Best Response Optimization

- Solve iteratively

- At TX 1, $\forall \mathbf{G}_i \in \{\mathbf{G}_1^{\text{Quant}}, \dots, \mathbf{G}_n^{\text{Quant}}\}$,

$$p_1^{\text{BR}} = \underset{p_1}{\operatorname{argmax}} \mathbb{E}[R(p_1(\mathbf{G}^{(1)}), p_2^{\text{BR}}(\mathbf{G}^{(2)}))]$$

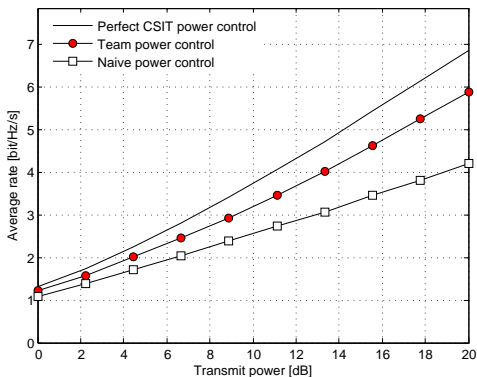
- At TX 2, $\forall \mathbf{G}_i \in \{\mathbf{G}_1^{\text{Quant}}, \dots, \mathbf{G}_n^{\text{Quant}}\}$,

$$p_2^{\text{BR}} = \underset{p_2}{\operatorname{argmax}} \mathbb{E}[R(p_1^{\text{BR}}(\mathbf{G}^{(1)}), p_2(\mathbf{G}^{(2)}))]$$

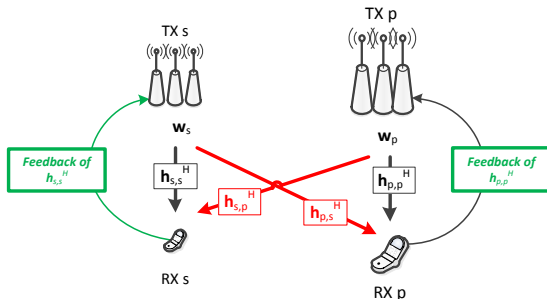
➡ Made possible by the discretization of the observation space

Simulations of On-Off Power Control with Local Feedback

Channel Modeling	Fading Pathloss	Rayleigh Uniform
Algorithm parameters	Codebook size for quantization	10^4
	Number of Monte-Carlo runs	500
CSIT Configuration	$\sigma^{(1)}$	1
	$\sigma^{(2)}$	0



III/ Third Application: Cognitive Radio Beamforming with Local Feedback



$$\text{Maximize } \underbrace{\mathbb{E}[R_s]}_{\text{Secondary}} \text{ subject to } \underbrace{\mathbb{E}[R_p]}_{\text{Primary}} \geq \tau > 0$$

- CSI configuration
 - Primary TX only knows $h_{p,p}$
 - Secondary TX only knows $h_{s,s}$
- SOTA: Primary user is oblivious of the secondary user

Coordination scheme

Primary TX adapts **without any exchange of instantaneous information**

Robust Distributed Optimization

Optimization Problem (P)

$$\begin{aligned}
 (\mathbf{w}_p^*, \mathbf{w}_s^*) = \underset{(\mathbf{w}_p, \mathbf{w}_s)}{\operatorname{argmax}} \mathbb{E} [R_s(\mathbf{w}_p(\mathbf{h}_{p,p}), \mathbf{w}_s(\mathbf{h}_{s,s}))] \\
 \text{s. to } \mathbb{E} [R_p(\mathbf{w}_p(\mathbf{h}_{p,p}), \mathbf{w}_s(\mathbf{h}_{s,s}))] \geq \tau > 0, \quad (\text{P})
 \end{aligned}$$

- \mathbf{w}_p is the beamforming function at the primary TX

$$\begin{aligned}
 \mathbf{w}_p : \mathbb{C}^{M_p} &\rightarrow \mathbb{C}^{M_p} \\
 \mathbf{h}_{p,p} &\mapsto \mathbf{w}_p(\mathbf{h}_{p,p})
 \end{aligned}$$

- \mathbf{w}_s is the beamforming function at the secondary TX

$$\begin{aligned}
 \mathbf{w}_s : \mathbb{C}^{M_s} &\rightarrow \mathbb{C}^{M_s} \\
 \mathbf{h}_{s,s} &\mapsto \mathbf{w}_s(\mathbf{h}_{s,s})
 \end{aligned}$$

Primary Friendly (PF) Strategy

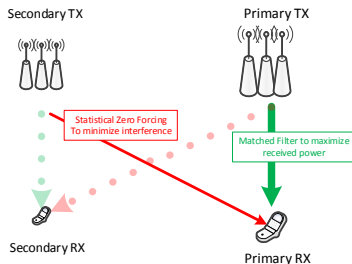
- **Primary TX:** uses Matched Filtering with full power $\bar{P}_p = P_p^{\max}$

$$\mathbf{u}_p^{(\text{PF})} \triangleq \frac{\mathbf{h}_{p,p}}{\|\mathbf{h}_{p,p}\|}$$

- **Secondary TX:** uses the statistical Zero Forcing beamforming

$$\mathbf{u}_s^{(\text{PF})} \triangleq \underset{\mathbf{u}}{\operatorname{argmin}} \mathbf{u}^H \mathbf{R}_{p,s} \mathbf{u}$$

and average transmit power \bar{P}_s to fulfill the ergodic rate constraint



Secondary Friendly (SF) Strategy

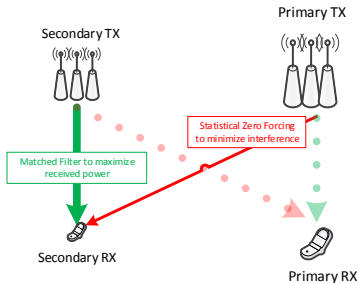
- **Secondary TX:** uses Matched Filtering with full power $\bar{P}_s = P_s^{\max}$

$$\mathbf{u}_s^{(\text{SF})} \triangleq \frac{\mathbf{h}_{s,s}}{\|\mathbf{h}_{s,s}\|}$$

- **Primary TX:** uses the statistical Zero Forcing beamformer

$$\mathbf{u}_p^{(\text{SF})} \triangleq \underset{\mathbf{u}}{\operatorname{argmin}} \mathbf{u}^H \mathbf{R}_{s,p} \mathbf{u}$$

and average transmit power \bar{P}_p to fulfill the ergodic rate constraint



Quantizing the Policy Space [Filippou et al., 2016, TWC]

- Restrict to 2 strategies labeled **Primary Friendly (PF)** and **Secondary Friendly (SF)**

➔ Need good heuristic choices

Optimization Problem

$$\begin{aligned}
 (\mathbf{w}_p^*, \mathbf{w}_s^*) &= \underset{(\mathbf{w}_p, \mathbf{w}_s) \in \mathcal{W}}{\operatorname{argmax}} \mathbb{E}[R_s(\mathbf{w}_p(\mathbf{h}_{p,p}), \mathbf{w}_s(\mathbf{h}_{s,s}))] \\
 &\text{s. to } \mathbb{E}[R_p(\mathbf{w}_p(\mathbf{h}_{p,p}), \mathbf{w}_s(\mathbf{h}_{s,s}))] \geq \tau > 0, \quad (\text{P}) \\
 \mathcal{W} &= \left\{ \underbrace{\left(\mathbf{w}_p^{(\text{PF})}, \mathbf{w}_s^{(\text{PF})} \right)}_{\text{First Strategy}}, \underbrace{\left(\mathbf{w}_p^{(\text{SF})}, \mathbf{w}_s^{(\text{SF})} \right)}_{\text{Second Strategy}} \right\}
 \end{aligned}$$

Cognitive Radio with Local Feedback: Rate of the Secondary User

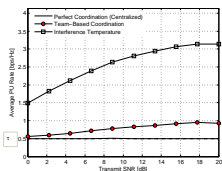


Figure: Ergodic rate of the Primary User

- $M_S = M_P = 3$ antennas per-TX
- Correlation matrices

$$R_{\rho, \rho} = R_{S, S} = I_3,$$

$$R_{\rho, S} = R_{S, \rho} = \begin{bmatrix} 1 & \rho & \rho^2 \\ \rho & 1 & \rho \\ \rho^2 & \rho & 1 \end{bmatrix}$$

- Use in the following $\rho = 0.5$ and $\tau = 0.5$ bps/Hz

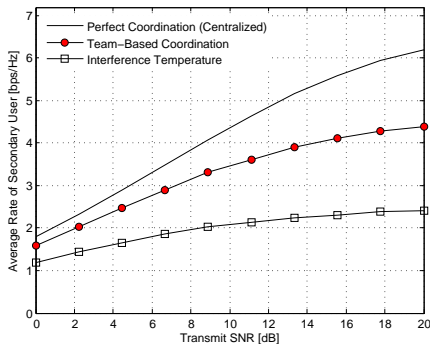


Figure: Ergodic rate of the Secondary User

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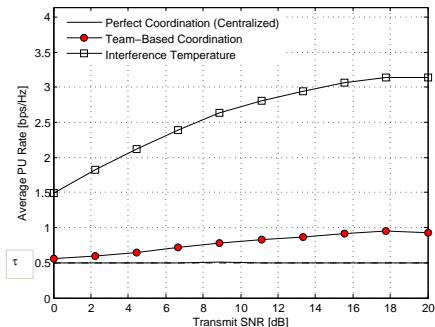


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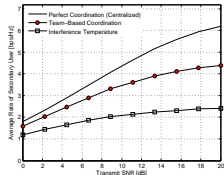


Figure: Ergodic rate of the Secondary User

Take home

- Device coordination is key to performance improvement in 5G and beyond
- Virtually all coordination schemes require extensive CSI acquisition and sharing among devices
- Coordination frameworks that are **robust to CSI locality** are desirable
- Several perspectives on the problem (i) control, (ii) signal processing, (iii) information theoretic

More applications (not covered here)

- Dynamic content caching at device side
- Coordinated beam alignment in millimeter wave Massive MIMO
- Coordinated power transfer for battery recharge in IoT networks
- More examples upon request



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thankS

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